## intel 3-Volt Advanced+ Boot Block Flash Memory

## 28F800C3, 28F160C3, 28F320C3, 28F640C3 (x16)

## **Preliminary Datasheet**

## **Product Features**

- Flexible SmartVoltage Technology
   —2.7 V–3.6 V Read/Program/Erase
   —12 V for Fast Production Programming
- 1.65 V-2.5 V or 2.7 V-3.6 V I/O Option
   —Reduces Overall System Power
- High Performance -2.7 V-3.6 V: 70 ns Max Access Time
- Optimized Architecture for Code Plus Data Storage
- —Eight 4-Kword Blocks, Top or Bottom Locations
- Up to One Hundred-Twenty-Seven 32-Kword Blocks
- Fast Program Suspend Capability — Fast Erase Suspend Capability
- Flexible Block Locking
- -Lock/Unlock Any Block
- -Full Protection on Power-Up
- $-V_{PP} = GND Option$
- -V<sub>CC</sub> Lockout Voltage
- Low Power Consumption
- —9 mA Typical Read Power
- -7 µA Typical Standby Power with Automatic Power Savings Feature
- 12 V Fast Production Program
- Extended Temperature Operation ---40 °C to +85 °C

- 128-bit Protection Register
   —64-bit Unique Device Identifier
- —64-bit User Programmable OTP Cells
- Extended Cycling Capability — Minimum 100,000 Block Erase Cycles
- Supports Intel<sup>®</sup> Flash Data Integrator Software
- -Flash Memory Manager
- -System Interrupt Manager
- --- Supports Parameter Storage, Streaming Data (e.g., voice)
- Automated Word/Byte Program and Block Erase
- -Command User Interface
- -Status Registers
- Cross-Compatible Command Support —Intel Basic Command Set
  - -Common Flash Interface
- Standard Surface Mount Packaging —48-Ball CSP Packages
- -64-Ball Easy BGA Packages
- —48-Lead TSOP Package
- ETOX<sup>™</sup> VIII (0.13 µm) Flash Technology
- —32- and 64-Mbit
- ETOX<sup>TM</sup> VII (0.18 μm) Flash Technology —16-, 32-, 64-Mbit
- ETOX<sup>TM</sup> VI (0.25 μm) Flash Technology —8-, 16- and 32-Mbit

The 3-Volt Advanced+ Boot Block Flash memory, manufactured on Intel's latest 0.13  $\mu$ m and 0.18  $\mu$ m technologies, represents a feature-rich solution for low-power applications. 3-Volt Advanced+ Boot Block Flash memory devices incorporate low-voltage capability (2.7 V read, program and erase) with high-speed, low-power operation. Flexible block locking allows any

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block to be independently locked or unlocked. Add to this the Intel<sup>®</sup> Flash Data Integrator (IFDI) software and you have a cost-effective, flexible, monolithic code plus data storage solution. Intel<sup>®</sup> 3-Volt Advanced+ Boot Block products will be available in 48-lead TSOP, 48-ball CSP, and 64-ball Easy BGA packages. Additional information on this product family can be obtained by accessing the Intel<sup>®</sup> Flash website: http://www.intel.com/design/flash.

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## **Revision History**

Date of Revision	Version	Description
05/12/98	-001	Original version
07/21/98	-002	48-Lead TSOP package diagram change μBGA package diagrams change 32-Mbit ordering information change (Section 6) CFI Query Structure Output Table Change (Table C2) CFI Primary-Vendor Specific Extended Query Table Change for Optional Features and Command Support change (Table C8) Protection Register Address Change I <sub>PPD</sub> test conditions clarification (Section 4.3) μBGA package top side mark information clarification (Section 6)
10/03/98	-003	Byte-Wide Protection Register Address change V <sub>IH</sub> Specification change (Section 4.3) V <sub>IL</sub> Maximum Specification change (Section 4.3) I <sub>CCS</sub> test conditions clarification (Section 4.3) Added Command Sequence Error Note (Table 7) Datasheet renamed from <i>3 Volt Advanced Boot Block, 8-, 16-, 32-Mbit Flash</i> <i>Memory Family.</i>
12/04/98	-004	Added t <sub>BHWH</sub> /t <sub>BHEH</sub> and t <sub>QVBL</sub> (Section 4.6) Programming the Protection Register clarification (Section 3.4.2)
12/31/98	-005	Removed all references to x8 configurations
02/24/99	-006	Removed reference to 40-Lead TSOP from front page
06/10/99	-007	Added Easy BGA package (Section 1.2) Removed 1.8 V I/O references <i>Locking Operations Flowchart</i> changed (Appendix B) Added t <sub>WHGL</sub> (Section 4.6) CFI Primary Vendor-Specific Extended Query changed (Appendix C)
03/20/00	-008	Max $I_{CCD}$ changed to 25 $\mu$ A Table 10, added note indicating $V_{CC}$ Max = 3.3 V for 32-Mbit device
04/24/00	-009	Added specifications for 0.18 micron product offerings throughout document Added 64-Mbit density
10/12/00	-010	Changed references of 32Mbit 80ns devices to 70ns devices to reflect the faster product offering. Changed VccMax=3.3V reference to indicate that the affected product is the 0.25µm 32Mbit device. Minor text edits throughout document.
7/20/01	-011	Added 1.8v I/O operation documentation where applicable Added TSOP PCN 'Pin-1' indicator information Changed references in 8 x 8 BGA pinout diagrams from 'GND' to 'Vssq' Added 'Vssq' to Pin Descriptions Information Removed 0.4 µm references in DC characteristics table Corrected 64Mb package Ordering Information from 48-uBGA to 48-VFBGA Corrected 'bottom' boot block sizes to on 8Mb device to 8 x 4KWords Minor text edits throughout document
10/02/01	-012	Added specifications for 0.13 micron product offerings throughout document

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## 1.0 Introduction

This document contains the specifications for the 3-Volt Advanced+ Boot Block Flash Memory family. These flash memories add features, such as instant block locking and a protection register, that can be used to enhance the security of systems.

This family of products features 1.65 V – 2.5 V or 2.7 V–3.6 V I/Os and a low  $V_{CC}/V_{PP}$  operating range of 2.7 V–3.6 V for Read, Program, and Erase operations. In addition, this family is capable of fast programming at 12 V. Throughout this document, the term "2.7 V" refers to the full voltage range 2.7 V–3.6 V (except where noted otherwise) and " $V_{PP} = 12$  V" refers to 12 V ±5%. Section 1.0 and Section 2.0 provide an overview of the flash memory family including applications, pinouts, pin descriptions, and memory organization. Section 3.0 describes the operation of these products, with Section 4.0 providing the operating specifications. Section 5.0 outlines ordering information, and Section 6.0 describes the location of additional reference material.

The 3-Volt Advanced+ Boot Block flash memory features include the following:

- Zero-latency, flexible block locking
- 128-bit Protection Register
- Simple system implementation for 12-V production programming with 2.7-V, in-field programming
- Ultra low-power operation at 2.7 V
- $V_{CCQ}$  input of 1.65 V–2.5 V on all I/Os. See Figures 1 through 4 for pinout diagrams and  $V_{CCO}$  location
- Minimum 100,000 block erase cycles
- Common Flash Interface for software query of device specs and features

#### Table 1. 3-Volt Advanced+ Boot Block Feature Summary

Feature	8 Mbit <sup>(1)</sup> , 16 Mbit, 32 Mbit <sup>(2)</sup>	Reference
V <sub>CC</sub> Operating Voltage	2.7 V – 3.6 V <sup>(3)</sup>	Table 8
V <sub>PP</sub> Voltage	Provides complete write protection with optional 12 V Fast Programming	Table 8
V <sub>CCQ</sub> I/O Voltage	1.65 V – 2.5 V or 2.7 V – 3.6 V	
Bus Width	16-bit	Table 2
Speed (ns)	8 Mbit: 90, 110 @ 2.7 V and 80, 100 @ 3.0 V 16 Mbit: 70, 80, 90, 110 @ 2.7 V and 70, 80, 100 @ 3.0 V 32 Mbit: 70, 90, 100, 110 @ 2.7 V and 70, 90, 100 @ 3.0 V 64 Mbit: 80, 100 @ 2.7 V and 80, 100 @ 3.0 V	Section 4.4
Blocking (top or bottom)	8 x 4-Kword parameter 8-Mb: 15 x 32-Kword main 16-Mb: 31 x 32-Kword main 32-Mb: 63 x 32-Kword main 64-Mb: 127 x 32-Kword main	Appendix 2.2 Appendix E
Operating Temperature	Extended: -40 °C to +85 °C	Table 8
Program/Erase Cycling	100,000 cycles	Table 8
Packages	48-Lead TSOP 48-Ball μBGA* CSP <sup>(1)</sup> , 48-Ball VF BGA, Easy BGA	Figure 1, 2 and 3
Block Locking	Flexible locking of any block with zero latency	Section 3.3
Protection Register	64-bit unique device number, 64-bit user programmable	Section 3.4



#### NOTES:

8-Mbit density not available in μBGA\* CSP.
 See Specification Update for changes to 32-Mbit devices (order 297938).

3.  $V_{CC}Max = 3.3$  V on 0.25 $\mu$ m 32-Mbit devices.

#### 5. $v_{CC}$ was = 5.5 v on 0.25 $\mu$ m 52-wbit devices

## 1.1 **Product Overview**

Intel provides secure low voltage memory solutions with the Advanced Boot Block family of products. A new block locking feature allows instant locking/unlocking of any block with zero latency. A 128-bit protection register allows unique flash device identification.

Discrete supply pins provide single voltage read, program, and erase capability at 2.7 V, while also allowing 12-V  $V_{PP}$  for faster production programming. Improved 12 V, a new feature designed to reduce external logic, simplifies board designs when combining 12-V production programming with 2.7-V in-field programming.

The 3-Volt Advanced+ Boot Block flash memory products are available in x16 packages in the following densities: (see Section 5.0, "Ordering Information" on page 43)

- 8-Mbit (8, 388, 608 bit) flash memories organized as 512 Kwords of 16 bits each
- 16-Mbit (16, 777, 216 bit) flash memories organized as 1024 Kwords of 16 bits each
- 32-Mbit (33, 554, 432 bit) flash memories organized as 2048 Kwords of 16 bits each
- 64-Mbit (67, 108, 864 bit) flash memories organized as 4096 Kwords of 16 bits each.

Eight 4-Kword parameter blocks are located at either the top (denoted by -T suffix) or the bottom (-B suffix) of the address map in order to accommodate different microprocessor protocols for kernel code location. The remaining memory is grouped into 64-Kbyte main blocks (see Appendix E).

All blocks can be locked or unlocked instantly to provide complete protection for code or data (see Section 3.3, "Flexible Block Locking" on page 17 for details).

The Command User Interface (CUI) serves as the interface between the microprocessor or microcontroller and the internal operation of the flash memory. The internal Write State Machine (WSM) automatically executes the algorithms and timings necessary for Program and Erase operations, including verification, thereby unburdening the microprocessor or microcontroller. The status register indicates the status of the WSM by signifying block-erase or word program completion and status.

Program and erase automation allows Program and Erase operations to be executed using an industry-standard two-write command sequence to the CUI. Program operations are performed in word increments. Erase operations erase all locations within a block simultaneously. Both Program and Erase operations can be suspended by the system software in order to read from any other block. In addition, data can be programmed to another block during an erase suspend.

The 3-Volt Advanced+ Boot Block flash memories offer two low-power savings features: Automatic Power Savings (APS), and standby mode. The device automatically enters APS mode following the completion of a read cycle. Standby mode is initiated when the system deselects the device by driving CE# inactive. Combined, these two power-savings features significantly reduce power consumption.



The device can be reset by lowering RP# to GND, which provides CPU memory reset synchronization and additional protection against bus noise that may occur during system reset and power-up/down sequences (see Section 3.5 and Section 3.6).

Refer to Section 4.4, "DC Characteristics" on page 27 for complete current and voltage specifications. Refer to Section 4.5 and Section 4.6 for read and write performance specifications. Section 4.7 shows program and erase times.

## 2.0 Product Description

This section provides device pin descriptions and package pinouts for the 3-Volt Advanced+ Boot Block Flash Memory family, which is available in 48-lead TSOP (x16) and 48-ball  $\mu$ BGA and Easy BGA packages (Figures 1, 2 and 3, respectively).

## 2.1 Package Pinouts



Figure 1. 48-Lead TSOP Package

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*Note:* Lower densities will have NC on the upper address pins. For example, a 16-Mbit device will have NC on Pins 9 and 10.



#### Figure 2. New Mark for Pin-1 indicator on 48-Lead 8Mb, 16Mb and 32Mb TSOP

**Current Mark:** 



New Mark:



*Note:* The topside marking on 8 Mb, 16 Mb, and 32 Mb Advanced and Advanced + Boot Block 48L TSOP products will convert to a white ink triangle as a Pin 1 indicator. Products without the white triangle will continue to use a dimple as a Pin 1 indicator. There are no other changes in package

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size, materials, functionality, customer handling, or manufactuability. Product will continue to meet Intel stringent quality requirements.

Products Affected are Intel Ordering Codes:

	48-Lead TSOP
	TE28F320C3TC70 TE28F320C3BC70
Extended	TE28F320C3TC90 TE28F320C3BC90
32 Mbit	TE28F320C3TA100 TE28F320C3BA100
	TE28F320C3TA110 TE28F320C3BA110
	TE28F160C3TC70 TE28F160C3BC70
Extended	TE28F160C3TC80 TE28F160C3BC80
16 Mbit	TE28F160C3TA90 TE28F160C3BA90
	TE28F160C3TA110 TE28F160C3BA110
Extended	TE28F800C3TA90 TE28F800C3BA90
8 Mbit	TE28F800C3TA110 TE28F800C3BA110







Shaded connections indicate the upgrade address connections. Lower density devices will not have the upper address solder balls. Routing is not recommended in this area. A<sub>19</sub> is the upgrade address for the 16-Mbit device. A<sub>20</sub> is the upgrade address for the 32-Mbit device. A<sub>21</sub> is the upgrade address for the 64-Mbit device.

4. 8-Mbit not available on  $\mu$ BGA\* CSP.



Figure 4. 8 x 8 Easy BGA Package



#### NOTES:

A<sub>19</sub> denotes 16 Mbit; A<sub>20</sub> denotes 32 Mbit; A<sub>21</sub> denotes 64 Mbit.
 A<sub>22</sub> indicates future density upgrade path to128 Mbit (not yet available).



### Table 2. 3-Volt Advanced+ Boot Block Pin Descriptions

Symbol	Туре	Name and Function
A <sub>0</sub> -A <sub>21</sub>	INPUT	ADDRESS INPUTS: Memory addresses are internally latched during a program or erase cycle. 8-Mbit: A[0-18], 16-Mbit: A[0-19], 32-Mbit: A[0-20], 64-Mbit: A[0-21]
DQ <sub>0</sub> –DQ <sub>7</sub>	INPUT/ OUTPUT	<b>DATA INPUTS/OUTPUTS:</b> Inputs array data on the second CE# and WE# cycle during a Program command. Inputs commands to the Command User Interface when CE# and WE# are active. Data is internally latched. Outputs array, configuration and status register data. The data pins float to tri-state when the chip is de-selected or the outputs are disabled.
DQ <sub>8</sub> -DQ <sub>15</sub>	INPUT/ OUTPUT	<b>DATA INPUTS/OUTPUTS:</b> Inputs array data on the second CE# and WE# cycle during a Program command. Data is internally latched. Outputs array and configuration data. The data pins float to tri-state when the chip is de-selected.
CE#	INPUT	<b>CHIP ENABLE:</b> Activates the internal control logic, input buffers, decoders and sense amplifiers. CE# is active low. CE# high de-selects the memory device and reduces power consumption to standby levels.
OE#	INPUT	<b>OUTPUT ENABLE:</b> Enables the device's outputs through the data buffers during a Read operation. OE# is active low.
WE#	INPUT	<b>WRITE ENABLE:</b> Controls writes to the command register and memory array. WE# is active low. Addresses and data are latched on the rising edge of the second WE# pulse.
		<b>RESET/DEEP POWER-DOWN:</b> Uses two voltage levels ( $V_{IL}$ , $V_{IH}$ ) to control reset/deep power-down mode.
RP#	INPUT	When RP# is at logic low, the device is in reset/deep power-down mode, which drives the outputs to High-Z, resets the Write State Machine, and minimizes current levels (I <sub>CCD</sub> ).
		When RP# is at logic high, the device is in standard operation. When RP# transitions from logic-low to logic-high, the device resets all blocks to locked and defaults to the read array mode.
		WRITE PROTECT: Controls the lock-down function of the flexible locking feature.
		When WP# is a logic low, the lock-down mechanism is enabled and blocks marked lock-down cannot be unlocked through software.
WP#	INPUT	When WP# is logic high, the lock-down mechanism is disabled and blocks previously locked- down are now locked and can be unlocked and locked through software. After WP# goes low, any blocks previously marked lock-down revert to that state.
		See Section 3.3 for details on block locking.
V <sub>CC</sub>	SUPPLY	DEVICE POWER SUPPLY: [2.7 V-3.6 V] Supplies power for device operations.
V <sub>CCQ</sub>	INPUT	<b>I/O POWER SUPPLY:</b> Enables all outputs to be driven to 1.8 V – 2.5 V while the V <sub>CC</sub> is at 2.7 V– 3.3 V. If the V <sub>CC</sub> is regulated to 2.7 V–2.85 V, V <sub>CCQ</sub> can be driven at 1.65 V–2.5 V to achieve lowest power operation (see Section 4.4). This input may be tied directly to V <sub>CC</sub> (2.7 V–3.6 V).
		<b>PROGRAM/ERASE POWER SUPPLY:</b> [1.65 V–3.6 V or 11.4 V–12.6 V] Operates as a input at logic levels to control complete device protection. Supplies power for accelerated Program and Erase operations in 12 V $\pm$ 5% range. This pin cannot be left floating.
		<b>Lower</b> $V_{PP} \leq V_{PPLK}$ , to protect all contents against Program and Erase commands.
V <sub>PP</sub>	INPUT/ SUPPLY	Set $V_{PP} = V_{CC}$ for in-system Read, Program and Erase operations. In this configuration, $V_{PP}$ can drop as low as 1.65 V to allow for resistor or diode drop from the system supply. Note that if $V_{PP}$ is driven by a logic signal, $V_{IH} = 1.65$ . That is, $V_{PP}$ must remain above 1.65 V to perform insystem flash modifications.
		<b>Raise V<sub>PP</sub> to 12 V</b> $\pm$ 5% for faster program and erase in a production environment. Applying 12 V $\pm$ 5% to V <sub>PP</sub> can only be done for a maximum of 1000 cycles on the main blocks and 2500 cycles on the parameter blocks. V <sub>PP</sub> may be connected to 12 V for a total of 80 hours maximum. See Section 3.4 for details on V <sub>PP</sub> voltage configurations.
V <sub>SSQ</sub>	SUPPLY	<b>GROUND:</b> For all internal circuitry. All V <sub>SSQ</sub> inputs <b>must</b> be connected. Same function as GND.
GND	SUPPLY	GROUND: For all internal circuitry. All ground inputs must be connected.

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## 2.2 Block Organization

The 3-Volt Advanced+ Boot Block is an asymmetrically blocked architecture that enables system integration of code and data within a single flash device. Each block can be erased independently of the others up to 100,000 times. For the address locations of each block, see the memory maps in Appendix E.

## 2.2.1 Parameter Blocks

The 3-Volt Advanced+ Boot Block flash memory architecture includes parameter blocks to facilitate storage of frequently updated small parameters (i.e., data that would normally be stored in an EEPROM). Each device contains eight parameter blocks of 4 Kwords (4,096 words).

## 2.2.2 Main Blocks

After the parameter blocks, the remainder of the array is divided into 32-Kword (32,768 words) main blocks for data or code storage. Each 8-Mbit, 16-Mbit, 32-Mbit, or 64-Mbit device contains 15, 31, 63, or 127 main blocks, respectively.

## 3.0 Principles of Operation

The 3-Volt Advanced+ Boot Block flash memory family uses a CUI and automated algorithms to simplify Program and Erase operations. The CUI allows for 100% CMOS-level control inputs and fixed power supplies during erasure and programming.

The internal WSM completely automates Program and Erase operations while the CUI signals the start of an operation and the status register reports status. The CUI handles the WE# interface to the data and address latches, as well as system status requests during WSM operation.

## 3.1 Bus Operation

The 3-Volt Advanced+ Boot Block flash memory devices read, program, and erase in-system via the local CPU or microcontroller. All bus cycles to or from the flash memory conform to standard microcontroller bus cycles. Four control pins dictate the data flow in and out of the flash component: CE#, OE#, WE#, and RP#. Table 3 on page 10 summarizes these bus operations.

## 3.1.1 Read

The flash memory has four read modes available: read array, read configuration, read status, and read query. These modes are accessible independent of the  $V_{PP}$  voltage. The appropriate Read Mode command must be issued to the CUI to enter the corresponding mode. Upon initial device power-up or after exit from reset, the device automatically defaults to read-array mode.

CE# and OE# must be driven active to obtain data at the outputs. CE# is the device selection control; when active it enables the flash memory device. OE# is the data output control, and it drives the selected memory data onto the I/O bus. For all read modes, WE# and RP# must be at  $V_{IH}$ . Figure 9, "AC Waveform: Read Operations" on page 35 illustrates a read cycle.

## 3.1.2 Output Disable

With OE# at a logic-high level ( $V_{IH}$ ), the device outputs are disabled. Output pins are placed in a high-impedance state.

### 3.1.3 Standby

Deselecting the device by bringing CE# to a logic-high level ( $V_{IH}$ ) places the device in standby mode, which substantially reduces device power consumption without any latency for subsequent read accesses. In standby, outputs are placed in a high-impedance state independent of OE#. If deselected during Program or Erase operation, the device continues to consume active power until the Program or Erase operation is complete.

Mode	Notes	RP#	CE#	OE#	WE#	DQ <sub>0-7</sub>	DQ <sub>8-15</sub>
Read (Array, Status, Configuration, or Query)	1, 2,3	V <sub>IH</sub>	V <sub>IL</sub>	V <sub>IL</sub>	V <sub>IH</sub>	D <sub>OUT</sub>	D <sub>OUT</sub>
Output Disable	1	V <sub>IH</sub>	V <sub>IL</sub>	V <sub>IH</sub>	V <sub>IH</sub>	High Z	High Z
Standby	1	V <sub>IH</sub>	V <sub>IH</sub>	Х	Х	High Z	High Z
Reset	1,4	V <sub>IL</sub>	Х	Х	Х	High Z	High Z
Write	1,4,5,6	V <sub>IH</sub>	V <sub>IL</sub>	V <sub>IH</sub>	V <sub>IL</sub>	D <sub>IN</sub>	D <sub>IN</sub>

#### Table 3. Bus Operations

#### NOTES:

1. X must be  $V_{IL}$ ,  $V_{IH}$  for control pins and addresses.

- 2. See DC Characteristics for  $V_{PPLK}$ ,  $V_{PP1}$ ,  $V_{PP2}$ ,  $V_{PP3}$ , voltages.
- 3. Manufacturer and device codes may also be accessed in read-configuration mode ( $A_{1-}A_{20} = 0$ ). See Table 4 on page 12.
- 4. To program or erase the lockable blocks, hold WP# at  $V_{IH}$ .
- 5. Refer to Table 5 on page 15 for valid D<sub>IN</sub> during a Write operation.
- 6. RP# must be at GND  $\pm$  0.2 V to meet the maximum deep power-down current specified.

8-bit devices use only DQ [0:7], 16-bit devices use DQ [0:15].

### 3.1.4 Reset

From read mode, RP# at  $V_{IL}$  for time  $t_{PLPH}$  deselects the memory, places output drivers in a highimpedance state, and turns off all internal circuits. After return from reset, a time  $t_{PHQV}$  is required until the initial read-access outputs are valid. A delay ( $t_{PHWL}$  or  $t_{PHEL}$ ) is required after return from reset before a write can be initiated. After this wake-up interval, normal operation is restored. The CUI resets to read-array mode, the status register is set to 80H, and all blocks are locked. Figure 11, "AC Waveform: Reset Operations" on page 42 (section A) illustrates this case.

If RP# is taken low for time  $t_{PLPH}$  during a Program or Erase operation, the operation will be aborted and the memory contents at the aborted location (for a program) or block (for an erase) are no longer valid, since the data may be partially erased or written. The abort process goes through the following sequence:

- 1. When RP# goes low, the device shuts down the operation in progress, a process which takes time t<sub>PLRH</sub> to complete.
- 2. After this time t<sub>PLRH</sub>, the part will either reset to read-array mode (if RP# has gone high during t<sub>PLRH</sub>, Figure 11, section B) or enter reset mode (if RP# is still logic low after t<sub>PLRH</sub>, Figure 11, section C).

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3. In both cases, after returning from an aborted operation, the relevant time t<sub>PHQV</sub> or t<sub>PHWL</sub>/ t<sub>PHEL</sub> must be observed before a Read or Write operation is initiated, as discussed in the previous paragraph. However, in this case, these delays are referenced to the end of t<sub>PLRH</sub> rather than when RP# goes high.

As with any automated device, it is important to assert RP# during system reset. When the system comes out of reset, the processor expects to read from the flash memory. Automated flash memories provide status information when read during program or Block-Erase operations. If a CPU reset occurs with no flash memory reset, proper CPU initialization may not occur because the flash memory may be providing status information instead of array data. Intel<sup>®</sup> Flash memories allow proper CPU initialization following a system reset through the use of the RP# input. In this application, RP# is controlled by the same RESET# signal that resets the system CPU.

## 3.1.5 Write

A write occurs when both CE# and WE# are low and OE# is high. Commands are written to the Command User Interface (CUI) using standard microprocessor write timings to control Flash operations. The CUI does not occupy an addressable memory location. The address and data buses are latched on the rising edge of the second WE# or CE# pulse, whichever occurs first. See Figure 10, "AC Waveform: Program and Erase Operations" on page 41. The available commands are shown in Table 6 on page 16, and Appendix A provides detailed information on moving between the different modes of operation using CUI commands.

Two commands modify array data: Program (40H), and Erase (20H). Writing either of these commands to the internal Command User Interface (CUI) initiates a sequence of internally timed functions that culminate in the completion of the requested task (unless that operation is aborted by either RP# being driven to  $V_{IL}$  for  $t_{PLRH}$  or an appropriate Suspend command).

## 3.2 Modes of Operation

The flash memory has four read modes (read array, read configuration, read status, and read query), and two write modes (program and erase). Three additional modes (erase suspend to program, erase suspend to read, and program suspend to read) are available only during suspended operations. Tables 5 and 6 summarize the commands used to reach these modes. Appendix A is a comprehensive chart showing the state transitions.

## 3.2.1 Read Array

When RP# transitions from  $V_{IL}$  (reset) to  $V_{IH}$ , the device defaults to read-array mode and will respond to the read-control inputs (CE#, address inputs, and OE#) without any additional CUI commands.

When the device is in read array mode, four control signals control data output.

- WE# must be logic high (V<sub>IH</sub>)
- CE# must be logic low (V<sub>II</sub>)
- OE# must be logic low (V<sub>II</sub>)
- RP# must be logic high (V<sub>IH</sub>)



In addition, the address of the desired location must be applied to the address pins. If the device is not in read-array mode, as would be the case after a Program or Erase operation, the Read Array command (FFH) must be written to the CUI before array reads can occur.

## 3.2.2 Read Configuration

The read-configuration mode outputs three types of information: the manufacturer/device identifier, the block locking status, and the protection register. The device is switched to this mode by writing the Read Configuration command (90H). Once in this mode, read cycles from addresses shown in Table 4 retrieve the specified information. To return to read-array mode, write the Read Array command (FFH).

#### Table 4. Read Configuration Table

Item	Address	Data
Manufacturer Code (x16)	00000	0089
Device ID (See Appendix F)	00001	ID
Block Lock Configuration <sup>(1)</sup>	XX002 <sup>(2)</sup>	LOCK
Block Is Unlocked		$DQ_0 = 0$
Block Is Locked		DQ <sub>0</sub> = 1
Block Is Locked-Down		DQ <sub>1</sub> = 1
Protection Register Lock <sup>(3)</sup>	80	PR-LK
Protection Register (x16)	81–88	PR

#### NOTES:

1. See Section 3.3.4 for valid lock-status outputs.

2. "XX" specifies the block address of lock configuration being read.

3. See Section 3.4 for protection register information.

4. Other locations within the configuration address space are reserved by Intel for future use.

## 3.2.3 Read Status Register

The status register indicates the status of device operations, and the success/failure of that operation. The Read Status Register (70H) command causes subsequent reads to output data from the status register until another command is issued. To return to reading from the array, issue a Read Array (FFH) command.

The status-register bits are output on  $DQ_0-DQ_7$ . The upper byte,  $DQ_8-DQ_{15}$ , outputs 00H during a Read Status Register command.

The contents of the status register are latched on the falling edge of OE# or CE# (whichever occurs last), which prevents possible bus errors that might occur if status register contents change while being read. CE# or OE# must be toggled with each subsequent status read, or the status register will not indicate completion of a Program or Erase operation.

When the WSM is active, SR.7 will indicate the status of the WSM; the remaining bits in the status register indicate whether the WSM was successful in performing the preferred operation (see Table 7, "Status Register Bit Definition" on page 17).

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## 3.2.3.1 Clearing the Status Register

The WSM sets status bits 1 through 7 to "1," and clears bits 2, 6, and 7 to "0," but cannot clear status bits 1 or 3 through 5 to "0." Because bits 1, 3, 4, and 5 indicate various error conditions, these bits can be cleared only through the Clear Status Register (50H) command. By allowing the system software to control the resetting of these bits, several operations may be performed (such as cumulatively programming several addresses or erasing multiple blocks in sequence) before reading the status register to determine if an error occurred during that series. Clear the status register before beginning another command or sequence. Note that this is different from a burst device. The Read Array command must be issued before data can be read from the memory array. Resetting the device also clears the status register.

## 3.2.4 Read Query

The read-query mode outputs Common Flash Interface (CFI) data when the device is read, and can be accessed by writing the Read Query Command (98H). The CFI data structure contains information such as block size, density, command set, and electrical specifications. Once in this mode, read cycles from addresses shown in Appendix C retrieve the specified information. To return to read-array mode, write the Read Array command (FFH).

## 3.2.5 Program Mode

Programming is executed using a two-write sequence. The Program Setup command (40H) is written to the CUI followed by a second write which specifies the address and data to be programmed. The WSM will execute a sequence of internally timed events to program preferred bits of the addressed location, then verify the bits are sufficiently programmed. Programming the memory results in specific bits within an address location being changed to a "0." If users attempt to program "1"s, the memory cell contents do not change and no error occurs.

The status register indicates programming status: while the program sequence executes, status bit 7 is "0." The status register can be polled by toggling either CE# or OE#. While programming, the only valid commands are Read Status Register, Program Suspend, and Program Resume.

When programming is complete, the program-status bits should be checked. If the programming operation was unsuccessful, bit SR.4 of the status register is set to indicate a program failure. If SR.3 is set, then  $V_{PP}$  was not within acceptable limits, and the WSM did not execute the program command. If SR.1 is set, a program operation was attempted on a locked block and the operation was aborted.

The status register should be cleared before attempting the next operation. Any CUI instruction can follow after programming is completed; however, to prevent inadvertent status-register reads, be sure to reset the CUI to read-array mode.

## 3.2.5.1 Suspending and Resuming Program

The Program Suspend command halts an in-progress program operation so that data can be read from other locations of memory. Once the programming process starts, writing the Program Suspend command to the CUI requests that the WSM suspend the program sequence (at predetermined points in the program algorithm). The device continues to output status-register data after the Program Suspend command is written. Polling status-register bits SR.7 and SR.2 will determine when the program operation has been suspended (both will be set to "1"). t<sub>WHRH1</sub>/ t<sub>EHRH1</sub> specify the program-suspend latency.



A Read Array command can now be written to the CUI to read data from blocks other than that which is suspended. The only other valid commands while program is suspended are Read Status Register, Read Configuration, Read Query, and Program Resume. After the Program Resume command is written to the flash memory, the WSM will continue with the programming process and status register bits SR.2 and SR.7 will automatically be cleared. The device automatically outputs status register data when read (see Figure 13, "Program Suspend/Resume Flowchart" on page 49) after the Program Resume command is written.  $V_{PP}$  must remain at the same  $V_{PP}$  level used for program while in program-suspend mode. RP# must also remain at  $V_{IH}$ .

### 3.2.6 Erase Mode

To erase a block, write the Erase Set-up and Erase Confirm commands to the CUI, along with an address identifying the block to be erased. This address is latched internally when the Erase Confirm command is issued. Block erasure results in all bits within the block being set to "1." Only one block can be erased at a time. The WSM will execute a sequence of internally timed events to program all bits within the block to "0," erase all bits within the block to "1," then verify that all bits within the block are sufficiently erased. While the erase executes, status bit 7 is a "0."

When the status register indicates that erasure is complete, check the erase-status bit to verify that the Erase operation was successful. If the Erase operation was unsuccessful, SR.5 of the status register will be set to a "1," indicating an erase failure. If  $V_{PP}$  was not within acceptable limits after the Erase Confirm command was issued, the WSM will not execute the erase sequence; instead, SR.5 of the status register is set to indicate an erase error, and SR.3 is set to a "1" to identify that  $V_{PP}$  supply voltage was not within acceptable limits.

After an Erase operation, clear the status register (50H) before attempting the next operation. Any CUI instruction can follow after erasure is completed; however, to prevent inadvertent status-register reads, it is advisable to place the flash in read-array mode after the erase is complete.

### 3.2.6.1 Suspending and Resuming Erase

Since an Erase operation requires on the order of seconds to complete, an Erase Suspend command is provided to allow erase-sequence interruption in order to read data from—or program data to—another block in memory. Once the erase sequence is started, writing the Erase Suspend command to the CUI suspends the erase sequence at a predetermined point in the erase algorithm. The status register will indicate if/when the Erase operation has been suspended. Erase-suspend latency is specified by  $t_{WHRH2}/t_{EHRH2}$ .

A Read Array/Program command can now be written to the CUI to read/program data from/to blocks other than that which is suspended. This nested Program command can subsequently be suspended to read yet another location. The only valid commands while Erase is suspended are Read Status Register, Read Configuration, Read Query, Program Setup, Program Resume, Erase Resume, Lock Block, Unlock Block, and Lock-Down Block. During erase-suspend mode, the chip can be placed in a pseudo-standby mode by taking CE# to  $V_{IH}$ , which reduces active current consumption.

Erase Resume continues the erase sequence when  $CE\# = V_{IL}$ . Similar to the end of a standard Erase operation, the status register must be read and cleared before the next instruction is issued.

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### Table 5. Command Bus Operations

Command	Notes	Fi	rst Bus Cyc	le	Sec	ond Bus C	ycle
Command	Notes	Oper	Addr	Data	Oper	Addr	Data
Read Array	1	Write	Х	FFH			
Read Configuration	1, 2	Write	Х	90H	Read	IA	ID
Read Query	1, 2	Write	Х	98H	Read	QA	QD
Read Status Register	1	Write	Х	70H	Read	Х	SRD
Clear Status Register	1	Write	Х	50H			
Program	1, 3	Write	Х	40H/10H	Write	PA	PD
Block Erase/Confirm	1	Write	Х	20H	Write	BA	D0H
Program/Erase Suspend	1	Write	Х	B0H			
Program/Erase Resume	1	Write	Х	D0H			
Lock Block	1	Write	Х	60H	Write	BA	01H
Unlock Block	1	Write	Х	60H	Write	BA	D0H
Lock-Down Block	1	Write	Х	60H	Write	BA	2FH
Protection Program	1	Write	Х	C0H	Write	PA	PD
X = Don't Care PA	= Prog Addr	BA =	Block Addr	IA = Ide	entifier Addr.	QA = Qu	ery Addr.
SRD = Status Reg. PD Data	= Prog Data			ID = Ide	entifier Data	QD = Qu	ery Data

#### NOTES:

- Following the Read Configuration or Read Query commands, Read operations output device configuration or CFI query information, respectively. See Section 3.2.2 and Section 3.2.4.
   Either 40H or 10H command is valid, but the Intel standard is 40H.
- 3. When writing commands, the upper data bus  $[DQ_{8-}DQ_{15}]$  should be either  $V_{IL}$  or  $V_{IH}$ , to minimize current draw.

Bus operations are defined in Table 3, "Bus Operations" on page 10.



Table 6. Command Codes and Descriptions	Table 6.	Command	Codes and	<b>Descriptions</b>
---	----------	---------	-----------	---------------------

Code	Device Mode	Description
FF	Read Array	This command places the device in read-array mode, which outputs array data on the data pins.
40	Program Set-Up	This is a two-cycle command. The first cycle prepares the CUI for a program operation. The second cycle latches addresses and data information and initiates the WSM to execute the Program algorithm. The flash outputs status-register data when CE# or OE# is toggled. A Read Array command is required after programming to read array data. See Section 3.2.5.
20	Erase Set-Up	Prepares the CUI for the Erase Confirm command. If the next command is not an Erase Confirm command, then the CUI will (a) set both SR.4 and SR.5 of the status register to a "1," (b) place the device into the read-status-register mode, and (c) wait for another command. See Section 3.2.6.
	Erase Confirm	If the previous command was an Erase Set-Up command, then the CUI will close the address and data latches and begin erasing the block indicated on the address pins. During program/ erase, the device will respond only to the Read Status Register, Program Suspend and Erase Suspend commands, and will output status-register data when CE# or OE# is toggled.
D0	Program/Erase Resume	If a Program or Erase operation was previously suspended, this command will resume that operation.
	Unlock Block	If the previous command was Configuration Set-Up, the CUI will latch the address and unlock the block indicated on the address pins. If the block had been previously set to Lock-Down, this operation will have no effect. (Section 3.3)
B0	Program Suspend Erase Suspend	Issuing this command will begin to suspend the currently executing Program/Erase operation. The status register will indicate when the operation has been successfully suspended by setting either the program-suspend (SR.2) or erase-suspend (SR.6) and the WSM status bit (SR.7) to a "1" (ready). The WSM will continue to idle in the SUSPEND state, regardless of the state of all input-control pins except RP#, which will immediately shut down the WSM and the remainder of the chip if RP# is driven to $V_{IL}$ . See Sections 3.2.5.1 and 3.2.6.1.
70	Read Status Register	This command places the device into read-status-register mode. Reading the device will output the contents of the status register, regardless of the address presented to the device. The device automatically enters this mode after a Program or Erase operation has been initiated. See Section 3.2.3.
50	Clear Status Register	The WSM can set the block-lock status (SR.1), $V_{PP}$ Status (SR.3), program status (SR.4), and erase-status (SR.5) bits in the status register to "1," but it cannot clear them to "0." Issuing this command clears those bits to "0."
90	Read Configuration	Puts the device into the read-configuration mode so that reading the device will output the manufacturer/device codes or block-lock status. Section 3.2.2.
60	Configuration Set-Up	Prepares the CUI for changes to the device configuration, such as block-locking changes. If the next command is not Block Unlock, Block Lock, or Block Lock-Down, then the CUI will set both the program and erase-status-register bits to indicate a command-sequence error. See Section 3.2.
01	Lock-Block	If the previous command was Configuration Set-Up, the CUI will latch the address and lock the block indicated on the address pins. (Section 3.3)
2F	Lock-Down	If the previous command was a Configuration Set-Up command, the CUI will latch the address and lock-down the block indicated on the address pins. (Section 3.3)
98	Read Query	Puts the device into the read-query mode so that reading the device will output Common Flash Interface information. See Section 3.2.4 and Appendix C.
C0	Protection Program Setup	This is a two-cycle command. The first cycle prepares the CUI for a program operation to the protection register. The second cycle latches addresses and data information and initiates the WSM to execute the Protection Program algorithm to the protection register. The flash outputs status-register data when CE# or OE# is toggled. A Read Array command is required after programming to read array data. See Section 3.4.
10	Alt. Prog Set-Up	Operates the same as Program Set-up command. (See 40H/Program Set-Up)
00	Invalid/ Reserved	Unassigned commands that should not be used. Intel reserves the right to redefine these codes for future functions.

**NOTE:** See Appendix A for mode transition information.



Table 7. Status Register Bit Definiti
---------------------------------------

WSMS	ESS	ES	PS	VPPS	PSS	BLS	R		
7	6	5	4	3	2	1	0		
				NOTES:					
SR.7 WRITE S 1 = Ready 0 = Busy	TATE MACHINE	E STATUS (WSM	IS)		ate Machine bit fi completion, befo				
1 = Erase Sus	-SUSPEND STA pended rogress/Comple			both WSMS an	uspend is issued d ESS bits to "1.' me command is	'ESS bit remain			
SR.5 = ERASE 1 = Error In Bl 0 = Successfu	ock Erase				s set to "1," WSN to the block and k erasure.				
1 = Error in Pr	RAM STATUS (P ogramming I Programming	PS)		When this bit is set to "1," WSM has attempted but failed to program a word/byte.					
SR.3 = V <sub>PP</sub> ST 1 = V <sub>PP</sub> Low E 0 = V <sub>PP</sub> OK	ATUS (VPPS) Detect, Operatior	) Abort		The V <sub>PP</sub> status bit does not provide continuous indication of V <sub>PP</sub> level. The WSM interrogates V <sub>PP</sub> level only after the Program or Erase command sequences have been entered, and informs the system if V <sub>PP</sub> has not been switched on. The V <sub>PP</sub> is also checked before the operation is verified by the WSM. The V <sub>PP</sub> status bit is not guaranteed to report accurate feedback between V <sub>PPLK</sub> and V <sub>PP1</sub> Min.					
1 = Program S	SR.2 = PROGRAM SUSPEND STATUS (PSS) 1 = Program Suspended 0 = Program in Progress/Completed			When Program Suspend is issued, WSM halts execution and sets both WSMS and PSS bits to "1." PSS bit remains set to "1' until a Program Resume command is issued.					
1 = Prog/Erase aborted.	<ul> <li>SR.1 = BLOCK LOCK STATUS</li> <li>1 = Prog/Erase attempted on a locked block; Operation aborted.</li> <li>0 = No operation to locked blocks</li> </ul>			If a Program or Erase operation is attempted to one of the locked blocks, this bit is set by the WSM. The operation specified is aborted and the device is returned to read status mode.					
SR.0 = RESER		JRE ENHANCEI	MENTS (R)		ved for future us e status register.		e masked out		

NOTE: A Command-Sequence Error is indicated when SR.4, SR.5, and SR.7 are set.

## 3.3 Flexible Block Locking

Intel 3-Volt Advanced+ Boot Block products offer an instant, individual block-locking scheme that allows any block to be locked or unlocked with no latency, enabling instant code and data protection.

This locking scheme offers two levels of protection. The first level allows software-only control of block locking (useful for data blocks that change frequently), while the second level requires hardware interaction before locking can be changed (useful for code blocks that change infrequently).

The following sections will discuss the operation of the locking system. The term "state [XYZ]" will be used to specify locking states; e.g., "state [001]," where X = value of WP#, Y = bit DQ<sub>1</sub> of the Block Lock status register, and Z = bit DQ<sub>0</sub> of the Block Lock status register. Table 9, "Block Locking State Transitions" on page 20 defines all of these possible locking states.



## 3.3.1 Locking Operation

The following concisely summarizes the locking functionality.

- All blocks power-up locked, then can be unlocked or locked with the Unlock and Lock commands.
- The Lock-Down command locks a block and prevents it from being unlocked when WP# = 0.
  - When WP# = 1, Lock-Down is overridden and commands can unlock/lock locked-down blocks.
  - When WP# returns to 0, locked-down blocks return to Lock Down.
  - Lock Down is cleared only when the device is reset or powered down.

The locking status of each block can be set to Locked, Unlocked, and Lock Down, each of which will be described in the following sections. Table 9 on page 20 is a comprehensive state table for the locking functions; Figure 16 on page 52 is a flowchart for Locking operations.

### 3.3.1.1 Locked State

The default status of all blocks upon power-up or reset is locked (states [001] or [101]). Locked blocks are fully protected from alteration. Any Program or Erase operations attempted on a locked block will return an error on bit SR.1 of the status register. The status of a locked block can be changed to Unlocked or Lock Down using the appropriate software commands. An Unlocked block can be locked by writing the Lock command sequence, 60H followed by 01H.

#### 3.3.2 Unlocked State

Unlocked blocks (states [000], [100], [110]) can be programmed or erased. All unlocked blocks return to the Locked state when the device is reset or powered down. The status of an unlocked block can be changed to Locked or Locked Down using the appropriate software commands. A Locked block can be unlocked by writing the Unlock command sequence, 60H followed by D0H.

#### 3.3.3 Lock-Down State

Blocks that are Locked Down (state [011]) are protected from Program and Erase operations (just like Locked blocks), but their protection status cannot be changed using software commands alone. A Locked or Unlocked block can be Locked Down by writing the Lock-Down command sequence, 60H followed by 2FH. Locked-Down blocks revert to the Locked state when the device is reset or powered down.

The Lock-Down function depends on the WP# input pin. When WP# = 0, blocks in Lock Down [011] are protected from program, erase, and lock status changes. When WP# = 1, the Lock-Down function is disabled ([111]) and Locked-Down blocks can be individually unlocked by software command to the [110] state, where they can be erased and programmed. These blocks can then be relocked [111] and unlocked [110] as required while WP# remains high. When WP# goes low, blocks that were previously Locked Down return to the Lock-Down state [011], regardless of any changes made while WP# was high. Device reset or power-down resets all blocks, including those in Lock-Down, to Locked state.

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## 3.3.4 Reading Block-Lock Status

The Lock status of every block can be read in the configuration-read mode of the device. To enter this mode, write 90H to the device. Subsequent reads at Block Address + 00002 will output the Lock status of that block. The Lock status is represented by  $DQ_0$  and  $DQ_1$ .  $DQ_0$  indicates the Block Lock/Unlock status and is set by the Lock command and cleared by the Unlock command. It is also automatically set when entering Lock Down.  $DQ_1$  indicates Lock-Down status, and is set by the Lock-Down command. It cannot be cleared by software—only by device reset or power-down.

### Table 8. Block Lock Status

Item	Address	Data
Block Lock Configuration	XX002	LOCK
Block Is Unlocked		$DQ_0 = 0$
Block Is Locked		DQ <sub>0</sub> = 1
Block Is Locked-Down		DQ <sub>1</sub> = 1

## 3.3.5 Locking Operations during Erase Suspend

Changes to block-lock status can be performed during an erase-suspend by using the standard locking command sequences to Unlock, Lock, or Lock Down a block. This is useful in the case when another block needs to be updated while an Erase operation is in progress.

To change block locking during an Erase operation, first write the Erase Suspend command (B0H), then check the status register until it indicates that the Erase operation has been suspended. Next, write the preferred Lock command sequence to a block and the Lock status will be changed. After completing any preferred Lock, Read, or Program operations, resume the Erase operation with the Erase Resume command (D0H).

If a block is Locked or Locked Down during a Suspended Erase of the same block, the locking status bits will be changed immediately, but when the Erase is resumed, the Erase operation will complete.

Locking operations cannot be performed during a Program Suspend. Refer to Appendix A for detailed information on which commands are valid during Erase Suspend.

## 3.3.6 Status Register Error Checking

Using nested-locking or program-command sequences during Erase Suspend can introduce ambiguity into status register results.

Since locking changes are performed using a two-cycle command sequence, e.g., 60H followed by 01H to lock a block, following the Configuration Setup command (60H) with an invalid command will produce a Lock-Command error (SR.4 and SR.5 will be set to 1) in the status register. If a Lock-Command error occurs during an Erase Suspend, SR.4 and SR.5 will be set to 1 and will remain at 1 after the Erase is resumed. When Erase is complete, any possible error during the Erase cannot be detected via the status register because of the previous Lock-Command error.

A similar situation happens if an error occurs during a Program-Operation error nested within an Erase Suspend.

		Current	State		Lock Comm	ock Command Input Result (Next State)				
X	Y	Z		Erase/Prog Allowed?	Lask	Uniosh	Look Down			
WP#	DQ <sub>1</sub>	DQ <sub>0</sub>	Name		Lock	Unlock	Lock-Down			
0	0	0	"Unlocked"	Yes	Goes To [001]	No Change	Goes To [011]			
0	0	1	"Locked" (Default)	No	No Change	Goes To [000]	Goes To [011]			
0	1	1	"Locked-Down"	No	No Change	No Change	No Change			
1	0	0	"Unlocked"	Yes	Goes To [101]	No Change	Goes To [111]			
1	0	1	"Locked"	No	No Change	Goes To [100]	Goes To [111]			
1	1	0	Lock-Down Disabled	Yes	Goes To [111]	No Change	Goes To [111]			
1	1	1	Lock-Down Disabled	No	No Change	Goes To [110]	No Change			

#### Table 9. Block Locking State Transitions

#### NOTES:

- In this table, the notation [XYZ] denotes the locking state of a block, where X = WP#, Y = DQ<sub>1</sub>, and Z = DQ<sub>0</sub>. The current locking state of a block is defined by the state of WP# and the two bits of the block-lock status (DQ<sub>0</sub>, DQ<sub>1</sub>). DQ<sub>0</sub> indicates if a block is locked (1) or unlocked (0). DQ<sub>1</sub> indicates if a block has been Locked Down (1) or not (0).
- 2. At power-up or device reset, all blocks default to Locked state [001] (if WP# = 0). Holding WP# = 0 is the recommended default.
- 3. The "Erase/Program Allowed?" column shows whether Erase and Program operations are enabled (Yes) or disabled (No) in that block's current Lock state.
- 4. The "Lock Command Input Result [Next State]" column shows the result of writing the three Lock commands (Lock, Unlock, Lock-Down) in the current Lock state. For example, "Goes To [001]" would mean that writing the command to a block in the current Lock state would change it to [001].

## 3.4 128-Bit Protection Register

The 3-Volt Advanced+ Boot Block architecture includes a 128-bit protection register than can be used to increase the security of a system design. For example, the number contained in the protection register can be used to "mate" the flash component with other system components, such as the CPU or ASIC, preventing device substitution. The Intel application note, *AP-657 Designing with the Advanced+ Boot Block Flash Memory Architecture*, contains additional application information.

The 128 bits of the protection register are divided into two 64-bit segments. One of the segments is programmed at the Intel factory with a unique 64-bit number, which is unchangeable. The other segment is left blank for customer designs to program, as preferred. Once the customer segment is programmed, it can be locked to prevent reprogramming.

### 3.4.1 Reading the Protection Register

The protection register is read in the configuration-read mode. The device is switched to this mode by writing the Read Configuration command (90H). Once in this mode, read cycles from addresses shown in Appendix G retrieve the specified information. To return to read-array mode, write the Read Array command (FFH).

## 3.4.2 **Programming the Protection Register**

The protection register bits are programmed using the two-cycle Protection Program command. The 64-bit number is programmed 16 bits at a time for word-wide parts, and eight bits at a time for byte-wide parts.

First, write the Protection Program Setup command, COH. The next write to the device will latch in address and data, and program the specified location. The allowable addresses are shown in Appendix G. See Figure 17, "Protection Register Programming Flowchart" on page 53. Attempts to address Protection Program commands outside the defined protection register address space should not be attempted. This space is reserved for future use. Attempting to program to a previously locked protection register segment will result in a Status Register error (Program Error bit SR.4 and Lock Error bit SR.1 will be set to 1).

## 3.4.3 Locking the Protection Register

The user-programmable segment of the protection register is lockable by programming Bit 1 of the PR-LOCK location to 0. Bit 0 of this location is programmed to 0 at the Intel factory to protect the unique device number. This bit is set using the Protection Program command to program "FFFD" to the PR-LOCK location. After these bits have been programmed, no further changes can be made to the values stored in the protection register. Protection Program commands to a locked section will result in a Status Register error (Program Error bit SR.4 and Lock Error bit SR.1 will be set to 1). Protection register lockout state is not reversible.

### Figure 5. Protection Register Memory Map



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## 3.5 V<sub>PP</sub> Program and Erase Voltages

Intel 3-Volt Advanced+ Boot Block products provide in-system programming and erase in the 1.65 V–3.6 V range. For fast production programming, it also includes a low-cost, backward-compatible 12-V programming feature.

## 3.5.1 Improved 12-Volt Production Programming

When  $V_{PP}$  is between 1.65 V and 3.6 V, all program and erase current is drawn through the  $V_{CC}$  pin. Note that if  $V_{PP}$  is driven by a logic signal,  $V_{IH}$  min = 1.65 V. That is,  $V_{PP}$  must remain above 1.65 V to perform in-system flash modifications. When  $V_{PP}$  is connected to a 12 V power supply,



the device draws program and erase current directly from the  $V_{PP}$  pin. This eliminates the need for an external switching transistor to control the voltage  $V_{PP}$  Figure 6 on page 22 shows examples of how the flash power supplies can be configured for various usage models.

The 12-V V<sub>PP</sub> mode enhances programming performance during the short period of time typically found in manufacturing processes; however, it is not intended for extended use. 12 V may be applied to V<sub>PP</sub> during Program and Erase operations for a maximum of 1000 cycles on the main blocks and 2500 cycles on the parameter blocks. V<sub>PP</sub> may be connected to 12 V for a total of 80 hours maximum. Stressing the device beyond these limits may cause permanent damage.

## 3.5.2 $V_{PP} \leq V_{PPLK}$ for Complete Protection

In addition to the flexible block locking, the  $V_{PP}$  programming voltage can be held low for absolute hardware write protection of all blocks in the flash device. When  $V_{PP}$  is below  $V_{PPLK}$ , any Program or Erase operation will result in a error, prompting the corresponding status-register bit (SR.3) to be set.

#### Figure 6. Example Power Supply Configurations



#### NOTE:

1. A resistor can be used if the V<sub>CC</sub> supply can sink adequate current based on resistor value. See *AP-657 Designing with the Advanced+ Boot Block Flash Memory Architecture* for details.

## 3.6 Power Consumption

Intel Flash devices have a tiered approach to power savings that can significantly reduce overall system power consumption. The Automatic Power Savings (APS) feature reduces power consumption when the device is selected but idle. If the CE# is deasserted, the flash enters its standby mode, where current consumption is even lower. The combination of these features can minimize memory power consumption, and therefore, overall system power consumption.

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## 3.6.1 Active Power (Program/Erase/Read)

With CE# at a logic-low level and RP# at a logic-high level, the device is in the active mode. Refer to the DC Characteristic tables for  $I_{CC}$  current values. Active power is the largest contributor to overall system power consumption. Minimizing the active current could have a profound effect on system power consumption, especially for battery-operated devices.

## 3.6.2 Automatic Power Savings (APS)

Automatic Power Savings provides low-power operation during read mode. After data is read from the memory array and the address lines are quiescent, APS circuitry places the device in a mode where typical current is comparable to  $I_{CCS}$ . The flash stays in this static state with outputs valid until a new location is read.

## 3.6.3 Standby Power

When CE# is at a logic-high level ( $V_{IH}$ ) and the device is in read mode, the flash memory is in standby mode, which disables much of the device's circuitry and substantially reduces power consumption. Outputs are placed in a high-impedance state independent of the status of the OE# signal. If CE# transitions to a logic-high level during Erase or Program operations, the device will continue to perform the operation and consume corresponding active power until the operation is completed.

System engineers should analyze the breakdown of standby time versus active time, and quantify the respective power consumption in each mode for their specific application. This approach will provide a more accurate measure of application-specific power and energy requirements.

## 3.6.4 Deep Power-Down Mode

The deep power-down mode is activated when  $\text{RP#} = V_{\text{IL}}$  (GND ± 0.2 V). During read modes, RP# going low de-selects the memory and places the outputs in a high-impedance state. Recovery from deep power-down requires a minimum time of  $t_{\text{PHQV}}$  for Read operations, and  $t_{\text{PHWL}}/t_{\text{PHEL}}$  for Write operations.

During program or erase modes, RP# transitioning low will abort the in-progress operation. The memory contents of the address being programmed or the block being erased are no longer valid as the data integrity has been compromised by the abort. During deep power-down, all internal circuits are switched to a low-power savings mode (RP# transitioning to  $V_{IL}$  or turning off power to the device clears the status register).

## 3.7 Power-Up/Down Operation

The device is protected against accidental block erasure or programming during power transitions. Power supply sequencing is not required, because the device is indifferent as to which power supply,  $V_{PP}$  or  $V_{CC}$ , powers-up first.



## 3.7.1 RP# Connected to System Reset

The use of RP# during system reset is important with automated program/erase devices since the system expects to read from the flash memory when it comes out of reset. If a CPU reset occurs without a flash memory reset, proper CPU initialization will not occur because the flash memory may be providing status information instead of array data. Intel recommends connecting RP# to the system CPU RESET# signal to allow proper CPU/flash initialization following system reset.

System designers must guard against spurious writes when  $V_{CC}$  voltages are above  $V_{LKO}$ . Because both WE# and CE# must be low for a command write, driving either signal to  $V_{IH}$  will inhibit writes to the device. The CUI architecture provides additional protection since alteration of memory contents can only occur after successful completion of the two-step command sequences. The device is also disabled until RP# is brought to  $V_{IH}$ , regardless of the state of its control inputs. By holding the device in reset (RP# connected to system POWERGOOD) during power-up/down, invalid bus conditions during power-up can be masked, providing yet another level of memory protection.

## 3.7.2 V<sub>CC</sub>, V<sub>PP</sub> and RP# Transitions

The CUI latches commands as issued by system software and is not altered by  $V_{PP}$  or CE# transitions or WSM actions. Its default state upon power-up, after exit from reset mode or after  $V_{CC}$  transitions above  $V_{LKO}$  (Lockout voltage), is read-array mode.

After any program or Block-Erase operation is complete (even after  $V_{PP}$  transitions down to  $V_{PPLK}$ ), the CUI must be reset to read-array mode via the Read Array command if access to the flash-memory array is desired.

## 3.8 **Power Supply Decoupling**

Flash memory power-switching characteristics require careful device decoupling. System designers should consider the following three supply current issues:

- Standby current levels (I<sub>CCS</sub>)
- Read current levels (I<sub>CCR</sub>)
- Transient peaks produced by falling and rising edges of CE#.

Transient current magnitudes depend on the device outputs' capacitive and inductive loading. Twoline control and proper decoupling capacitor selection will suppress these transient voltage peaks. Each flash device should have a 0.1  $\mu$ F ceramic capacitor connected between each V<sub>CC</sub> and GND, and between its V<sub>PP</sub> and GND. These high- frequency, inherently low-inductance capacitors should be placed as close as possible to the package leads.

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#### **Electrical Specifications** 4.0

#### **Absolute Maximum Ratings** 4.1

Parameter	Maximum Rating			
Extended Operating Temperature				
During Read	–40 °C to +85 °C			
During Block Erase and Program	–40 °C to +85 °C			
Temperature under Bias	–40 °C to +85 °C			
Storage Temperature	–65 °C to +125 °C			
Voltage On Any Pin (except $V_{CC}$ and $V_{PP}$ ) with Respect to GND	-0.5 V to +3.7 V <sup>(1)</sup>			
$V_{PP}$ Voltage (for Block Erase and Program) with Respect to GND	-0.5 V to +13.5 V <sup>(1,2,3)</sup>			
$\rm V_{CC}$ and $\rm V_{CCQ}$ Supply Voltage with Respect to GND	-0.2 V to +3.6 V			
Output Short Circuit Current	100 mA <sup>(4)</sup>			

#### NOTES:

- 1. Minimum DC voltage is -0.5 V on input/output pins. During transitions, this level may undershoot to -2.0 V for periods <20 ns. Maximum DC voltage on input/output pins is V<sub>CC</sub> +0.5 V which, during transitions, may overshoot to V<sub>CC</sub> +2.0 V for periods <20 ns. 2. Maximum DC voltage on V<sub>PP</sub> may overshoot to +14.0 V for periods <20 ns.
- 3. V<sub>PP</sub> Program voltage is normally 1.65 V–3.6 V. Connection to a 11.4 V–12.6 V supply can be done for a maximum of 1000 cycles on the main blocks and 2500 cycles on the parameter blocks during program/erase. V<sub>PP</sub> may be connected to 12 V for a total of 80 hours maximum. See Section 3.5 for details.
- 4. Output shorted for no more than one second. No more than one output shorted at a time.

NOTICE: This datasheet contains preliminary information on new products in production. Specifications are subject to change without notice. Verify with your local Intel Sales office that you have the latest datasheet before finalizing a design.

Warning: Stressing the device beyond the "Absolute Maximum Ratings" may cause permanent damage. These are stress ratings only. Operation beyond the "Operating Conditions" is not recommended and extended exposure beyond the "Operating Conditions" may affect device reliability.



#### **Operating Conditions** 4.2

#### **Table 10. Temperature and Voltage Operating Conditions**

Symbol	Parameter	Notes	Min	Max	Units
T <sub>A</sub>	Operating Temperature		-40	+85	°C
V <sub>CC1</sub>	V <sub>CC</sub> Supply Voltage	1, 2	2.7	3.6	Volts
V <sub>CC2</sub>		1, 2	3.0	3.6	
V <sub>CCQ1</sub>		1	2.7	3.6	
V <sub>CCQ2</sub>	I/O Supply Voltage		1.65	2.5	Volts
V <sub>CCQ3</sub>			1.8	2.5	
V <sub>PP1</sub>	Supply Voltage	1	1.65	3.6	Volts
V <sub>PP2</sub>		1, 3	11.4	12.6	Volts
Cycling	Block Erase Cycling	3	100,000		Cycles

#### NOTES:

 V<sub>CC</sub> and V<sub>CCQ</sub> must share the same supply when they are in the V<sub>CC1</sub> range.
 V<sub>CC</sub>Max = 3.3 V for 0.25µm 32-Mbit devices.
 Applying V<sub>PP</sub> = 11.4 V–12.6 V during a program/erase can only be done for a maximum of 1000 cycles on the main blocks and 2500 cycles on the parameter blocks. V<sub>PP</sub> may be connected to 12 V for a total of 20 kerne parameters 0.5 for 4 total or 80 hours maximum. See Section 3.5 for details.

#### 4.3 Capacitance

 $T_A = 25 \text{ °C}, f = 1 \text{ MHz}$ 

Sym	Parameter	Notes	Тур	Max	Units	Conditions
C <sub>IN</sub>	Input Capacitance	1	6	8	pF	$V_{IN} = 0 V$
C <sub>OUT</sub>	Output Capacitance	1	10	12	pF	V <sub>OUT</sub> = 0 V

#### NOTE:

1. Sampled, not 100% tested.

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## 4.4 DC Characteristics

			2.7 V-	-3.6 V	2.7 V-	-2.85 V	2.7 V-	-3.3 V			
Sym	Parameter	V <sub>CCQ</sub>	2.7 V-	-3.6 V	1.65 \	/–2.5 V	1.8 V-	-2.5 V	Unit	Test Conditions	
		Note	Тур	Max	Тур	Max	Тур	Max			
ILI	Input Load Current	1,2		± 1		± 1		± 1	μA	$V_{CC} = V_{CC}Max$ $V_{CCQ} = V_{CCQ}Max$ $V_{IN} = V_{CCQ} \text{ or } GND$	
I <sub>LO</sub>	Output Leakage Current	1,2	0.2	± 10	0.2	± 10	0.2	± 10	μA	$V_{CC} = V_{CC}Max$ $V_{CCQ} = V_{CCQ}Max$ $V_{IN} = V_{CCQ} \text{ or GND}$	
I <sub>ccs</sub>	V <sub>CC</sub> Standby Current for 0.13 and 0.18 Micron Product	1	7	15	20	50	150	250	μΑ	$V_{CC} = V_{CC}Max$ $CE\# = RP\# = V_{CCQ}$ or during Program/ Erase Suspend $WP\# = V_{CCQ}$ or GND	
	V <sub>CC</sub> Standby Current for 0.25 Micron Product	1	10	25	20	50	150	250	μA		
I <sub>CCD</sub>	V <sub>CC</sub> Power-Down Current for 0.13 and 0.18 Micron Product	1,2	7	15	7	20	7	20	μΑ	$V_{CC} = V_{CC}Max$ $V_{CCQ} = V_{CCQ}Max$ $V_{IN} = V_{CCQ} \text{ or } GND$ $RP# = GND \pm 0.2 \text{ V}$	
000	V <sub>CC</sub> Power-Down Current for 0.25 Product	1,2	7	25	7	25	7	25	μA		
	V <sub>CC</sub> Read Current for 0.13 and 0.18 Micron Product	1,2,3	9	18	8	15	9	15	mA	$V_{CC} = V_{CC}Max$ $V_{CCQ} = V_{CCQ}Max$ $OE# = V_{IH}, CE# = V_{IL}$	
ICCR	V <sub>CC</sub> Read Current for 0.25 Micron Product	1,2,3	10	18	8	15	9	15	mA	$OE# = V_{IH}$ , $CE# = V_{IL}$ f = 5 MHz, $I_{OUT}=0$ mA Inputs = $V_{IL}$ or $V_{IH}$	
I <sub>PPD</sub>	V <sub>PP</sub> Deep Power- Down Current	1	0.2	5	0.2	5	0.2	5	μA	$\begin{array}{l} RP\#=GND\pm0.2\;V\\ V_{PP}\leqV_{CC} \end{array}$	
1	V <sub>PP</sub> Read Current	1,4	2	±15	2	±15	2	±15	μA	$V_{PP} \le V_{CC}$	
I <sub>PPR</sub>		1,4	50	200	50	200	50	200	μA	$V_{PP} > V_{CC}$	
	V <sub>CC</sub> + V <sub>PP</sub> Program Current for 0.13	1,4	0.05	0.1	18	55	18	55	mA	V <sub>PP</sub> =V <sub>PP1,</sub> Program in Progress	
I <sub>CCW+</sub>	and 0.18 Micron Product	.,-	8	22	10	30	10	30	mA	$V_{PP} = V_{PP2 (12v)}$ Program in Progress	
I <sub>PPW</sub>	V <sub>CC</sub> + V <sub>PP</sub> Program Current for 0.25	1,4	0.05	0.1	18	55	18	55	mA	V <sub>PP</sub> =V <sub>PP1,</sub> Program in Progress	
	Micron Product	1,4	8	22	10	30	10	30	mA	V <sub>PP</sub> = V <sub>PP2 (12v)</sub> Program in Progress	

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		v <sub>cc</sub>	2.7 V-	-3.6 V	2.7 V-	-2.85 V	2.7 V-	-3.3 V		
Sym	Parameter	V <sub>CCQ</sub>	2.7 V-	-3.6 V	1.65 V	/-2.5 V	1.8 V-	-2.5 V	Unit	Test Conditions
		Note	Тур	Max	Тур	Max	Тур	Max		
	V <sub>CC</sub> + V <sub>PP</sub> Erase Current for 0.13	1,4	0.05	0.1	21	45	21	45	mA	V <sub>PP</sub> = V <sub>PP1,</sub> Erase in Progress
I <sub>CCE</sub>	and 0.18 Micron Product	1,4	8	22	16	45	16	45	mA	V <sub>PP</sub> = V <sub>PP2 (12v)</sub> , Erase in Progress
+I <sub>PPE</sub>	V <sub>CC</sub> + V <sub>PP</sub> Erase Current for 0.25	1,4	0.05	0.1	21	45	21	45	mA	V <sub>PP</sub> = V <sub>PP1,</sub> Erase in Progress
	Micron Product	1,4	8	22	16	45	16	45	mA	$V_{PP} = V_{PP2 (12v)}$ , Erase in Progress
	V <sub>CC</sub> + V <sub>PP</sub> Program or Erase Suspend Current for 0.13	1,4	0.05	0.1	21	45	21	45	μA	V <sub>PP</sub> = V <sub>PP1,</sub> Program or Erase Suspend in Progress
I <sub>PPES +</sub>	and 0.18 Micron Product	1,4	50	200	50	200	50	200	μA	$V_{PP} = V_{PP2 (12v)}$ , Program or Erase Suspend in Progress
I <sub>PPWS</sub>	V <sub>CC</sub> + V <sub>PP</sub> Program or Erase Suspend	1,4	0.05	0.1	21	45	21	45	μA	V <sub>PP</sub> = V <sub>PP1,</sub> Program or Erase Suspend in Progress
	Current for 0.25 Micron Product	1,4	50	200	50	200	50	200	μA	$V_{PP} = V_{PP2 (12v)}$ , Program or Erase Suspend in Progress
V <sub>IL</sub>	Input Low Voltage		-0.4	V <sub>CC</sub> * 0.22 V	-0.4	0.4	-0.4	0.4	V	
V <sub>IH</sub>	Input High Voltage		2.0	V <sub>CCQ</sub> +0.3V	V <sub>CCQ</sub> -0.4V	V <sub>CCQ</sub> +0.3V	V <sub>CCQ</sub> -0.4V	V <sub>CCQ</sub> +0.3V	V	
V <sub>OL</sub>	Output Low Voltage		-0.1	0.1	-0.1	0.1	-0.1	0.1	V	$\label{eq:V_CC} \begin{split} V_{CC} &= V_{CC} Min \\ V_{CCQ} &= V_{CCQ} Min \\ I_{OL} &= 100 \ \mu A \end{split}$
V <sub>OH</sub>	Output High Voltage		V <sub>CCQ</sub> -0.1V		V <sub>CCQ</sub> -0.1V		V <sub>CCQ</sub> -0.1V		V	$V_{CC} = V_{CC}Min$ $V_{CCQ} = V_{CCQ}Min$ $I_{OH} = -100 \ \mu A$
V <sub>PPLK</sub>	V <sub>PP</sub> Lock-Out Voltage	6		1.0		1.0		1.0	V	Complete Write Protection
V <sub>PP1</sub>	V <sub>PP</sub> during	6	1.65	3.6					V	
V <sub>PP2</sub>	Program / Erase Operations	6, 7			11.4	12.6			V	
V <sub>LKO</sub>	V <sub>CC</sub> Prog/Erase Lock Voltage		1.5		1.5		1.5		V	
V <sub>LKO2</sub>	V <sub>CCQ</sub> Prog/Erase Lock Voltage		1.2		1.2		1.2		V	

#### NOTES:

All currents are in RMS unless otherwise noted. Typical values at nominal V<sub>CC</sub>, T<sub>A</sub> = +25 °C.
 The test conditions V<sub>CC</sub>Max, V<sub>CCQ</sub>Max, V<sub>CC</sub>Min, and V<sub>CCQ</sub>Min refer to the maximum or minimum V<sub>CC</sub> or V<sub>CCQ</sub> voltage listed at the top of each column. V<sub>CC</sub>Max = 3.3 V for 0.25µm 32-Mbit devices.
 Automatic Power Savings (APS) reduces I<sub>CCR</sub> to approximately standby levels in static operation (CMOS

inputs).

4. Sampled, not 100% tested.

 5. I<sub>CCES</sub> and I<sub>CCWS</sub> are specified with device de-selected. If device is read while in erase suspend, current draw is sum of I<sub>CCES</sub> and I<sub>CCR</sub>. If the device is read while in program suspend, current draw is the sum of I<sub>CCWS</sub> and I<sub>CCR</sub>.

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- 6. Erase and Program are inhibited when V<sub>PP</sub> < V<sub>PPLK</sub> and not guaranteed outside the valid V<sub>PP</sub> ranges of V<sub>PP1</sub> and V<sub>PP2</sub>.
  7. Applying V<sub>PP</sub> = 11.4 V–12.6 V during program/erase can only be done for a maximum of 1000 cycles on the main blocks and 2500 cycles on the parameter blocks. V<sub>PP</sub> may be connected to 12 V for a total of 80 hours maximum. See Section 3.4 for details.



## Figure 7. Input/Output Reference Waveform



## Figure 8. Test Configuration



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Test Configuration	C <sub>L</sub> (pF)	<b>R<sub>1</sub> (</b> Ω)	<b>R<sub>2</sub> (</b> Ω)
2.7 V–3.6 V Standard Test	50	25K	25K

**NOTE:**  $C_L$  includes jig capacitance.
#### 4.5 **AC Characteristics—Read Operations**

			Den	sity				8 N	lbit				
#	C	Parameter	Pro	duct		90	ns			110	) ns		Unit
#	Sym	Parameter	V	cc	3.0 V ·	- 3.6 V	2.7 V – 3.6 V		3.0 V – 3.6 V		2.7 V – 3.6 V		Unit
				Note	Min	Max	Min	Max	Min	Max	Min	Max	
R1	t <sub>AVAV</sub>	Read Cycle Time			80		90		100		110		ns
R2	t <sub>AVQV</sub>	Address to Outpu	t Delay			80		90		100		110	ns
R3	t <sub>ELQV</sub>	CE# to Output De	elay	1		80		90		100		110	ns
R4	t <sub>GLQV</sub>	OE# to Output De	elay	1		30		30		30		30	ns
R5	t <sub>PHQV</sub>	RP# to Output De	elay			150		150		150		150	ns
R6	t <sub>ELQX</sub>	CE# to Output in	Low Z	2	0		0		0		0		ns
R7	t <sub>GLQX</sub>	OE# to Output in	Low Z	2	0		0		0		0		ns
R8	t <sub>EHQZ</sub>	CE# to Output in	High Z	2		20		20		20		20	ns
R9	t <sub>GHQZ</sub>	OE# to Output in	High Z	2		20		20		20		20	ns
R10	t <sub>OH</sub>	Output Hold from Address, CE#, or Change, Whichev Occurs First	OE#	2	0		0		0		0		ns

### NOTES:

1. OE# may be delayed up to  $t_{ELQV}t_{GLQV}$  after the falling edge of CE# without impact on  $t_{ELQV}$ . 2. Sampled, but not 100% tested.

See Figure 9, "AC Waveform: Read Operations" on page 35. See Figure 7, "Input/Output Reference Waveform" on page 30 for timing measurements and maximum allowable input slew rate.



			Density						16	Mbit						
#	Sym	Para-	Product	70	ns	80	ns		90	ns			110	) ns		Unit
#	Sym	meter	V <sub>cc</sub>	2.7 V-	-3.6 V	2.7 V-	-3.6 V	3.0 V-	-3.6 V	2.7 V-	-3.6 V	3.0 V-	-3.6 V	2.7 V-	-3.6 V	Unit
				Min	Max											
R1	t <sub>AVAV</sub>	Read C	ycle Time	70		80		80		90		100		110		ns
R2	t <sub>AVQV</sub>	Addres Delay	s to Output		70		80		80		90		100		110	ns
R3	t <sub>ELQV</sub>	CE# to Delay <sup>(1</sup>	Output		70		80		80		90		100		110	ns
R4	t <sub>GLQV</sub>	OE# to Delay <sup>(1</sup>	Output		20		20		30		30		30		30	ns
R5	t <sub>PHQV</sub>	RP# to Delay	Output		150		150		150		150		150		150	ns
R6	t <sub>ELQX</sub>	CE# to Low Z <sup>(2</sup>	Output in	0		0		0		0		0		0		ns
R7	t <sub>GLQX</sub>	OE# to Low Z <sup>(2</sup>	Output in	0		0		0		0		0		0		ns
R8	t <sub>EHQZ</sub>	CE# to High Z <sup>(</sup>	Output in		20		20		20		20		20		20	ns
R9	t <sub>GHQZ</sub>	OE# to High Z <sup>(</sup>	Output in		20		20		20		20		20		20	ns
R10	t <sub>ОН</sub>	Addres OE# Ch	Hold from s, CE#, or nange, ver Occurs	0		0		0		0		0		0		ns

## AC Characteristics—Read Operations, continued

#### NOTES:

OE# may be delayed up to t<sub>ELQV</sub>-t<sub>GLQV</sub> after the falling edge of CE# without impact on t<sub>ELQV</sub>.
 Sampled, but not 100% tested.

See Figure 9, "AC Waveform: Read Operations" on page 35. See Figure 7, "Input/Output Reference Waveform" on page 30 for timing measurements and maximum allowable input slew rate.



			Density						32	Nbit						
#	Sym	Para- meter	Product	70	ns	90	ns		100	ns			110	) ns		Unit
#	Sym		V <sub>cc</sub>	2.7 V-	-3.6 V	2.7 V-	-3.6 V	3.0 V-	-3.3 V	2.7 V-	-3.3 V	3.0 V-	-3.3 V	2.7 V-	-3.3 V	onne
				Min	Max											
R1	t <sub>AVAV</sub>	Read Cyc	cle Time	70		90		90		100		100		110		ns
R2	t <sub>AVQV</sub>	Address t Delay	to Output		70		90		90		100		100		110	ns
R3	t <sub>ELQV</sub>	CE# to O Delay <sup>(1)</sup>	utput		70		90		90		100		100		110	ns
R4	t <sub>GLQV</sub>	OE# to O Delay <sup>(1)</sup>	utput		20		20		30		30		30		30	ns
R5	t <sub>PHQV</sub>	RP# to O	utput Delay		150		150		150		150		150		150	ns
R6	t <sub>ELQX</sub>	CE# to O Low Z <sup>(2)</sup>	utput in	0		0		0		0		0		0		ns
R7	t <sub>GLQX</sub>	OE# to O Low Z <sup>(2)</sup>	utput in	0		0		0		0		0		0		ns
R8	t <sub>EHQZ</sub>	CE# to O High Z <sup>(2)</sup>	utput in		20		20		20		20		20		20	ns
R9	t <sub>GHQZ</sub>	OE# to O High Z <sup>(2)</sup>	utput in		20		20		20		20		20		20	ns
R10	t <sub>ОН</sub>	Output He Address, OE# Cha Whicheve First <sup>(2)</sup>	CE#, or nge,	0		0		0		0		0		0		ns

## AC Characteristics—Read Operations, continued

**NOTES:** 1. OE# may be delayed up to  $t_{ELQV}-t_{GLQV}$  after the falling edge of CE# without impact on  $t_{ELQV}$ . 2. Sampled, but not 100% tested.

See Figure 9, "AC Waveform: Read Operations" on page 35. See Figure 7, "Input/Output Reference Waveform" on page 30 for timing measurements and maximum allowable input slew rate.



## AC Characteristics—Read Operations, continued

		Dens	sity		64	Mbit		
#	Cum	Parameter	uct	80	ns	100	ns	Unit
#	Sym	V <sub>C</sub>	с	2.7 V-	-3.6 V	2.7 V-	-3.6 V	Unit
			Note	Min	Max	Min	Max	
R1	t <sub>AVAV</sub>	Read Cycle Time		80		100		ns
R2	t <sub>AVQV</sub>	Address to Output Delay			80		100	ns
R3	t <sub>ELQV</sub>	CE# to Output Delay	1		80		100	ns
R4	t <sub>GLQV</sub>	OE# to Output Delay	1		20		20	ns
R5	t <sub>PHQV</sub>	RP# to Output Delay			150		150	ns
R6	t <sub>ELQX</sub>	CE# to Output in Low Z	2	0		0		ns
R7	t <sub>GLQX</sub>	OE# to Output in Low Z	2	0		0		ns
R8	t <sub>EHQZ</sub>	CE# to Output in High Z	2		20		20	ns
R9	t <sub>GHQZ</sub>	OE# to Output in High Z	2		20		20	ns
R10	t <sub>OH</sub>	Output Hold from Address, CE#, or OE# Change, Whichever Occurs First	2	0		0		ns

#### NOTES:

1. OE# may be delayed up to  $t_{ELQV}$ - $t_{GLQV}$  after the falling edge of CE# without impact on  $t_{ELQV}$ . 2. Sampled, but not 100% tested.

See Figure 9, "AC Waveform: Read Operations" on page 35. See Figure 7, "Input/Output Reference Waveform" on page 30 for timing measurements and maximum allowable input slew rate.







#### **AC Characteristics—Write Operations** 4.6

			Densit	y		8 N	lbit		
			Produc	ct	90	ns	110	ns	
#	Sym	Parameter	3.0 V – 3	.6 V	80		100		Unit
			2.7 V – 3	.6 V		90		110	
				Note	Min	Min	Min	Min	
W1	t <sub>PHWL</sub> / t <sub>PHEL</sub>	RP# High Recovery to WE# (CE	#) Going Low		150	150	150	150	ns
W2	t <sub>ELWL</sub> / t <sub>WLEL</sub>	CE# (WE#) Setup to WE# (CE#	) Going Low		0	0	0	0	ns
W3	t <sub>WLWH</sub> / t <sub>ELEH</sub>	WE# (CE#) Pulse Width		1	50	60	70	70	ns
W4	t <sub>DVWH</sub> / t <sub>DVEH</sub>	Data Setup to WE# (CE#) Going	g High	2	50	50	60	60	ns
W5	t <sub>AVWH</sub> / t <sub>AVEH</sub>	Address Setup to WE# (CE#) G	oing High	2	50	60	70	70	ns
W6	t <sub>WHEH</sub> / t <sub>EHWH</sub>	CE# (WE#) Hold Time from WE	# (CE#) High		0	0	0	0	ns
W7	t <sub>WHDX</sub> / t <sub>EHDX</sub>	Data Hold Time from WE# (CE#	<sup>ŧ</sup> ) High	2	0	0	0	0	ns
W8	t <sub>WHAX</sub> / t <sub>EHAX</sub>	Address Hold Time from WE# (0	CE#) High	2	0	0	0	0	ns
W9	t <sub>WHWL</sub> / t <sub>EHEL</sub>	WE# (CE#) Pulse Width High		1	30	30	30	30	ns
W10	t <sub>VPWH</sub> / t <sub>VPEH</sub>	V <sub>PP</sub> Setup to WE# (CE#) Going	High	3	200	200	200	200	ns
W11	t <sub>QVVL</sub>	V <sub>PP</sub> Hold from Valid SRD		3	0	0	0	0	ns
W12	t <sub>BHWH</sub> / t <sub>BHEH</sub>	NP# Setup to WE# (CE#) Going High		3	0	0	0	0	ns
W13	t <sub>QVBL</sub>	WP# Hold from Valid SRD		3	0	0	0	0	ns
W14	t <sub>WHGL</sub>	WE# High to OE# Going Low		3	30	30	30	30	ns

#### NOTES:

1. Write pulse width ( $t_{WP}$ ) is defined from CE# or WE# going low (whichever goes low last) to CE# or WE# going high (whichever goes high first). Hence,  $t_{WP} = t_{WLWH} = t_{ELEH} = t_{WLEH} = t_{ELWH}$ . Similarly, write pulse width high (t<sub>WPH</sub>) is defined from CE# or WE# going high (whichever goes high first) to CE# or WE# going low (whichever goes low first). Hence,  $t_{WPH} = t_{WHWL} = t_{EHEL} = t_{WHEL} = t_{EHWL}$ . 2. Refer to Table 5, "Command Bus Operations" on page 15 for valid A<sub>IN</sub> or D<sub>IN</sub>.

3. Sampled, but not 100% tested.

Write timing characteristics during erase suspend are the same as during Write-only operations. See Figure 7, "Input/Output Reference Waveform" on page 30 for timing measurements and maximum allowable input slew rate.

See Figure 9, "AC Waveform: Read Operations" on page 35.

4.  $V_{CC}Max = 3.3 V$  for 32-Mbit and 64-Mbit densities.

110 ns

100

Unit



			Density			16	Vibit	
			Product	70 ns	80 ns	90	ns	Γ
#	Sym	Parameter	3.0 V – 3.6 V			80		
			2.7 V – 3.6 V	70	80		90	
			Nete	Min	Min	Min	Min	

## AC Characteristics—Write Operations, continued

#### 110 Note Min Min Min Min Min Min **RP# High Recovery to WE#** t<sub>PHWL</sub> / 150 W1 150 150 150 150 150 ns (CE#) Going Low t<sub>PHEL</sub> CE# (WE#) Setup to WE# t<sub>ELWL</sub> / W2 0 0 0 0 0 0 ns (CE#) Going Low tWLEL t<sub>WLWH</sub> / W3 WE# (CE#) Pulse Width 1 45 50 50 60 70 70 ns t<sub>ELEH</sub> Data Setup to WE# (CE#) t<sub>DVWH</sub> / W4 2 40 40 50 50 60 60 ns Going High t<sub>DVEH</sub> Address Setup to WE# (CE#) t<sub>AVWH</sub> / W5 2 50 50 50 60 70 70 ns Going High t<sub>AVEH</sub> CE# (WE#) Hold Time from t<sub>WHEH</sub> / W6 0 0 0 0 0 0 ns WE# (CE#) High t<sub>EHWH</sub> Data Hold Time from WE# t<sub>WHDX</sub> / W7 2 0 0 0 0 0 0 ns (CE#) High t<sub>EHDX</sub> Address Hold Time from WE# t<sub>WHAX</sub> / W8 2 0 0 0 0 0 0 ns (CE#) High t<sub>EHAX</sub> t<sub>WHWL/</sub> W9 WE# (CE#) Pulse Width High 1 25 30 30 30 30 30 ns t<sub>EHEL</sub> t<sub>VPWH</sub> / V<sub>PP</sub> Setup to WE# (CE#) W10 3 200 200 200 200 200 200 ns Going High t<sub>VPEH</sub> VPP Hold from Valid SRD W11 3 0 0 0 0 0 0 ns t<sub>QVVL</sub> WP# Setup to WE# (CE#) t<sub>BHWH</sub> / W12 3 0 0 0 0 0 0 ns Going High t<sub>BHEH</sub> W13 WP# Hold from Valid SRD 3 0 0 0 0 0 0 t<sub>QVBL</sub> ns W14 WE# High to OE# Going Low 30 30 t<sub>WHGL</sub> 3 30 30 30 30 ns

#### NOTES:

1. Write pulse width (t<sub>WP</sub>) is defined from CE# or WE# going low (whichever goes low last) to CE# or WE# going high (whichever goes high first). Hence, t<sub>WP</sub> = t<sub>WLWH</sub> = t<sub>ELEH</sub> = t<sub>WLEH</sub> = t<sub>ELWH</sub>. Similarly, write pulse width high (twpp) is defined from CE# or WE# going high (whichever goes high first) to CE# or WE# going low (which ever goes low first). Hence, t<sub>WPH</sub> = t<sub>WHWL</sub> = t<sub>EHEL</sub> = t<sub>WHEL</sub> = t<sub>EHWL</sub>.
 Refer to Table 5, "Command Bus Operations" on page 15 for valid A<sub>IN</sub> or D<sub>IN</sub>.

3. Sampled, but not 100% tested.

Write timing characteristics during erase suspend are the same as during Write-only operations. See Figure 7, "Input/Output Reference Waveform" on page 30 for timing measurements and maximum allowable input slew rate.

See Figure 9, "AC Waveform: Read Operations" on page 35.

4.  $V_{CC}Max = 3.3 V$  for 32-Mbit and 64-Mbit densities.



### AC Characteristics—Write Operations, continued

			De	ensity			32	Mbit			
			Pro	oduct	70 ns	90 ns	100	) ns	110	ns	
#	Sym	Parameter	3.0 V	- 3.6 V <sup>(4)</sup>			90		100		Unit
			2.7 V	- 3.6 V <sup>(4)</sup>	70	90		100		110	
				Note	Min	Min	Min	Min	Min	Min	
W1	t <sub>PHWL</sub> / t <sub>PHEL</sub>	RP# High Recovery to V (CE#) Going Low	VE#		150	150	150	150	150	150	ns
W2	t <sub>ELWL</sub> / t <sub>WLEL</sub>	CE# (WE#) Setup to WE (CE#) Going Low	Ξ#		0	0	0	0	0	0	ns
W3	t <sub>WLWH</sub> / t <sub>ELEH</sub>	WE# (CE#) Pulse Width	I	1	45	60	60	70	70	70	ns
W4	t <sub>DVWH</sub> / t <sub>DVEH</sub>	Data Setup to WE# (CE Going High	#)	2	40	40	50	60	60	60	ns
W5	t <sub>AVWH</sub> / t <sub>AVEH</sub>	Address Setup to WE# ( Going High	(CE#)	2	50	60	60	70	70	70	ns
W6	t <sub>WHEH</sub> / t <sub>EHWH</sub>	CE# (WE#) Hold Time fi WE# (CE#) High	rom		0	0	0	0	0	0	ns
W7	t <sub>WHDX</sub> / t <sub>EHDX</sub>	Data Hold Time from WI (CE#) High	E#	2	0	0	0	0	0	0	ns
W8	t <sub>WHAX</sub> / t <sub>EHAX</sub>	Address Hold Time from (CE#) High	n WE#	2	0	0	0	0	0	0	ns
W9	t <sub>WHWL</sub> /	WE# (CE#) Pulse Width	High	1	25	30	30	30	30	30	ns
W10	t <sub>VPWH</sub> / t <sub>VPEH</sub>	V <sub>PP</sub> Setup to WE# (CE# Going High	V <sub>PP</sub> Setup to WE# (CE#) Going High		200	200	200	200	200	200	ns
W11	t <sub>QVVL</sub>	V <sub>PP</sub> Hold from Valid SRI	/ <sub>PP</sub> Hold from Valid SRD		0	0	0	0	0	0	ns
W12	t <sub>BHWH</sub> / t <sub>BHEH</sub>	WP# Setup to WE# (CE#) Going High		3	0	0	0	0	0	0	ns
W13	t <sub>QVBL</sub>	WP# Hold from Valid SR	WP# Hold from Valid SRD		0	0	0	0	0	0	ns
W14	t <sub>WHGL</sub>	WE# High to OE# Going	g Low	3	30	30	30	30	30	30	ns

### NOTES:

1. Write pulse width (t<sub>WP</sub>) is defined from CE# or WE# going low (whichever goes low last) to CE# or WE# going high (whichever goes high first). Hence,  $t_{WP} = t_{WLWH} = t_{ELEH} = t_{WLEH} = t_{ELWH}$ . Similarly, write pulse width high ( $t_{WPH}$ ) is defined from CE# or WE# going high (whichever goes high first) to CE# or WE# going low (whichever goes low first). Hence, t<sub>WPH</sub> = t<sub>WHWL</sub> = t<sub>EHEL</sub> = t<sub>WHEL</sub> = t<sub>EHWL</sub>.
 2. Refer to Table 5, "Command Bus Operations" on page 15 for valid A<sub>IN</sub> or D<sub>IN</sub>.

3. Sampled, but not 100% tested.

Write timing characteristics during erase suspend are the same as during Write-only operations. See Figure 7, "Input/Output Reference Waveform" on page 30 for timing measurements and maximum allowable input slew rate.

See Figure 9, "AC Waveform: Read Operations" on page 35.

4.  $V_{CC}Max = 3.3 V$  for 0.25 $\mu$ m 32-Mbit devices.

## int

## AC Characteristics—Write Operations, continued

			Densit	у	64	Mbit	
#	Sum	Parameter	Produ	ct	80 ns	100 ns	Unit
#	Sym	Parameter	2.7 V – 3	.6 V	80	100	Unit
				Note	Min	Min	
W1	t <sub>PHWL</sub> / t <sub>PHEL</sub>	RP# High Recovery to WE# (CE#	#) Going Low		150	150	ns
W2	t <sub>ELWL</sub> / t <sub>WLEL</sub>	CE# (WE#) Setup to WE# (CE#)		0	0	ns	
W3	t <sub>WLWH</sub> / t <sub>ELEH</sub>	WE# (CE#) Pulse Width		1	60	70	ns
W4	t <sub>DVWH</sub> / t <sub>DVEH</sub>	Data Setup to WE# (CE#) Going	High	2	40	40	ns
W5	t <sub>AVWH</sub> / t <sub>AVEH</sub>	Address Setup to WE# (CE#) Go	ing High	2	60	60	ns
W6	t <sub>WHEH</sub> / t <sub>EHWH</sub>	CE# (WE#) Hold Time from WE#	(CE#) High		0	0	ns
W7	t <sub>WHDX</sub> / t <sub>EHDX</sub>	Data Hold Time from WE# (CE#)	High	2	0	0	ns
W8	t <sub>WHAX</sub> / t <sub>EHAX</sub>	Address Hold Time from WE# (C	E#) High	2	0	0	ns
W9	t <sub>WHWL</sub> / t <sub>EHEL</sub>	WE# (CE#) Pulse Width High		1	30	30	ns
W10	t <sub>VPWH</sub> / t <sub>VPEH</sub>	V <sub>PP</sub> Setup to WE# (CE#) Going F	ligh	3	200	200	ns
W11	t <sub>QVVL</sub>	V <sub>PP</sub> Hold from Valid SRD		3	0	0	ns
W12	t <sub>BHWH</sub> / t <sub>BHEH</sub>	WP# Setup to WE# (CE#) Going	High	3	0	0	ns
W13	t <sub>QVBL</sub>	WP# Hold from Valid SRD		3	0	0	ns
W14	t <sub>WHGL</sub>	WE# High to OE# Going Low		3	30	30	ns

### NOTES:

1. Write pulse width (t<sub>WP</sub>) is defined from CE# or WE# going low (whichever goes low last) to CE# or WE# going high (whichever goes high first). Hence,  $t_{WP} = t_{WLWH} = t_{ELEH} = t_{WLEH} = t_{ELWH}$ . Similarly, write pulse width high ( $t_{WPH}$ ) is defined from CE# or WE# going high (whichever goes high first) to CE# or WE# going low (whichever goes low first). Hence,  $t_{WH} = t_{WHW} = t_{EHEL} = t_{WHEL} = t_{EHWL}$ . 2. Refer to Table 5, "Command Bus Operations" on page 15 for valid  $A_{IN}$  or  $D_{IN}$ . 3. Sampled, but not 100% tested.

Write timing characteristics during erase suspend are the same as during Write-only operations. See Figure 7, "Input/Output Reference Waveform" on page 30 for timing measurements and maximum allowable input slew rate.

See Figure 9, "AC Waveform: Read Operations" on page 35.



#### **Erase and Program Timings** 4.7

Complexed	Parameter	V <sub>PP</sub>	1.65 V	–3.6 V	11.4 V-	-12.6 V	11
Symbol	Parameter	Note	Typ <sup>(1)</sup>	Max	Typ <sup>(1)</sup>	Max	Unit
t <sub>BWPB</sub>	4-KW Parameter Block Word Program Time	2, 3	0.10	0.30	0.03	0.12	s
t <sub>BWMB</sub>	32-KW Main Block Word Program Time	2, 3	0.8	2.4	0.24	1	s
+ /+	Word Program Time for 0.13 and 0.18 Micron Product	2, 3	12	200	8	185	μs
t <sub>WHQV1</sub> / t <sub>EHQV1</sub>	Word Program Time for 0.25 Micron Product	2, 3	22	200	8	185	μs
t <sub>WHQV2</sub> / t <sub>EHQV2</sub>	4-KW Parameter Block Erase Time	2, 3	0.5	4	0.4	4	s
t <sub>WHQV3</sub> / t <sub>EHQV3</sub>	32-KW Main Block Erase Time	2, 3	1	5	0.6	5	s
t <sub>WHRH1</sub> / t <sub>EHRH1</sub>	Program Suspend Latency	3	5	10	5	10	μs
t <sub>WHRH2</sub> / t <sub>EHRH2</sub>	Erase Suspend Latency	3	5	20	5	20	μs

### NOTES:

Typical values measured at T<sub>A</sub> = +25 °C and nominal voltages.
 Excludes external system-level overhead.
 Sampled, but not 100% tested.



### Figure 10. AC Waveform: Program and Erase Operations

### NOTES:

- 1. CE# must be toggled low when reading Status Register Data. WE# must be inactive (high) when reading Status Register Data.
- a. V<sub>CC</sub> Power-Up and Standby.b. Write Program or Erase Setup Command.
- c. Write Valid Address and Data (for Program) or Erase Confirm Command.
- d. Automated Program or Erase Delay.
- e. Read Status Register Data (SRD): reflects completed Program/Erase operation.
- f. Write Read Array Command.



#### **Reset Operations** 4.8





## Table 11. Reset Specifications

Symbol	Parameter	Notes	V <sub>CC</sub> 2.7	V – 3.6 V	Unit
Symbol	Falaneter	NOLES	Min	Max	Unit
t <sub>PLPH</sub>	RP# Low to Reset during Read (If RP# is tied to V <sub>CC</sub> , this specification is not applicable)	2,4	100		ns
t <sub>PLRH1</sub>	RP# Low to Reset during Block Erase	3,4		22	μs
t <sub>PLRH2</sub>	RP# Low to Reset during Program	3,4		12	μs

#### NOTES:

If t<sub>PLPH</sub> is < 100 ns the device may still reset but this is not guaranteed.</li>
 If RP# is asserted while a Block Erase or Word Program operation is not executing, the reset will complete within 100 ns.

3. Sampled, but not 100% tested.

See Section 3.1.4 for a full description of these conditions.

## 5.0 Ordering Information



### VALID COMBINATIONS (All Extended Temperature)

	48-Lead TSOP	48-Ball µBGA* CSP	48-Ball VF BGA	Easy BGA
Extended	TE28F640C3TC80 TE28F640C3BC80		GE28F640C3TC80 GE28F640C3BC80	RC28F640C3TC80 RC28F640C3BC80
64 Mbit	TE28F640C3TC100 TE28F640C3BC100		GE28F640C3TC100 GE28F640C3BC100	RC28F640C3TC100 RC28F640C3BC100
			GE28F320C3TD70 GE28F320C3BD70	RC28F320C3TD70 RC28F320C3BD70
Extended	TE28F320C3TC90 TE28F320C3BC90		GE28F320C3TC90 GE28F320C3BC90	RC28F320C3TC90 RC28F320C3BC90
32 Mbit	TE28F320C3TA100 TE28F320C3BA100	GT28F320C3TA100 GT28F320C3BA100		RC28F320C3TA100 RC28F320C3BA100
	TE28F320C3TA110 TE28F320C3BA110	GT28F320C3TA110 GT28F320C3BA110		RC28F320C3TA110 RC28F320C3BA110
	TE28F160C3TC70 TE28F160C3BC70		GE28F160C3TC70 GE28F160C3BC70	RC28F160C3TC70 RC28F160C3BC70
Extended	TE28F160C3TC80 TE28F160C3BC80		GE28F160C3TC80 GE28F160C3BC80	RC28F160C3TC80 RC28F160C3BC80
16 Mbit	TE28F160C3TA90 TE28F160C3BA90	GT28F160C3TA90 GT28F160C3BA90		RC28F160C3TA90 RC28F160C3BA90
	TE28F160C3TA110 TE28F160C3BA110	GT28F160C3TA110 GT28F160C3BA110		RC28F160C3TA110 RC28F160C3BA110
Extended	TE28F800C3TA90 TE28F800C3BA90			RC28F800C3TA90 RC28F800C3BA90
8 Mbit	TE28F800C3TA110 TE28F800C3BA110			RC28F800C3TA110 RC28F800C3BA110

NOTE:



 The second line of the 48-ball μBGA package top side mark specifies assembly codes. For samples only, the first character signifies either "E" for engineering samples or "S" for silicon daisy chain samples. All other assembly codes without an "E" or "S" as the first character are production units.

### 6.0 **Additional Information**

Order Number	Document/Tool
297938	3 Volt Advanced+ Boot Block Flash Memory Specification Update
292216	AP-658 Designing for Upgrade to the Advanced+ Boot Block Flash Memory
292215	AP-657 Designing with the Advanced+ Boot Block Flash Memory Architecture
Contact your Intel Representative	Intel <sup>®</sup> Flash Data Integrator (IFDI) Software Developer's Kit
297874	IFDI Interactive: Play with Intel <sup>®</sup> Flash Data Integrator on Your PC

### NOTES:

Please call the Intel Literature Center at (800) 548-4725 to request Intel documentation. International customers should contact their local Intel or distribution sales office.
 Visit Intel's World Wide Web home page at 'http://www.intel.com/design/flash' for technical documentation

and tools.



## Appendix A WSM Current/Next States, Sheet 1 of 2

					C	Command Inpu	t (and Next State	)		
Current State	SR. 7	Data When Read	Read Array (FFH)	Program Setup (10/ 40H)	Erase Setup (20H)	Erase Confirm (D0H)	Prog/Ers Suspend (B0H)	Prog/Ers Resume (D0)	Read Status (70H)	Clear Status (50H)
Read Array	"1"	Array	Read Array	Prog. Setup	Ers. Setup	Read Array			Read Sts.	Read Array
Read Status	"1"	Status	Read Array	Prog. Setup	Ers. Setup		Read Array		Read Sts.	Read Array
Read Config.	"1"	Config	Read Array	Prog. Setup	Ers. Setup		Read Array		Read Sts.	Read Array
Read Query	"1"	CFI	Read Array	Prog. Setup	Ers. Setup		Read Array		Read Sts.	Read Array
Lock Setup	"1"	Status	Lo	ck Command Eri	ror	Lock (Done)	Lock Cmd. Error	Lock (Done)	Lock Cr	nd. Error
Lock Cmd. Error	"1"	Status	Read Array	Prog. Setup	Ers. Setup		Read Array		Read Sts.	Read Array
Lock Oper. (Done)	"1"	Status	Read Array	Prog. Setup	Ers. Setup		Read Array		Read Sts.	Read Array
Prot. Prog. Setup	"1"	Status				Protection Re	egister Program			
Prot. Prog. (Not Done)	"0"	Status			Pro	tection Register	Program (Not Do	ne)		
Prot. Prog. (Done)	"1"	Status	Read Array	Prog. Setup	Ers. Setup		Read Array		Read Sts.	Read Array
Prog. Setup	"1"	Status				Pro	ogram			
Program (Not Done)	"0"	Status		Program (N	Not Done)		Prog. Sus. Status	P	rogram (Not Dor	ne)
Prog. Susp. Status	"1"	Status	Prog. Sus. Read Array	Program Read		Prog. (Not Done)	Prog. Sus. Rd. Array	Program (Not Done)	Prog. Sus. Status	Prog. Sus. Rd. Array
Prog. Susp. Read Array	"1"	Array	Prog. Sus. Read Array	Program Read	Suspend Array	Prog. (Not Done)	Prog. Sus. Rd. Array	Program (Not Done)	Prog. Sus. Status	Prog. Sus. Rd. Array
Prog. Susp. Read Config	"1"	Config	Prog. Sus. Read Array	Program Read		Prog. (Not Done)	Prog. Sus. Rd. Array	Program (Not Done)	Prog. Sus. Status	Prog. Sus. Rd. Array
Prog. Susp. Read Query	"1"	CFI	Prog. Sus. Read Array	Program Read		Prog. (Not Done)	Prog. Sus. Rd. Array	Program (Not Done)	Prog. Sus. Status	Prog. Sus. Rd. Array
Program (Done)	"1"	Status	Read Array	Prog. Setup	Ers. Setup		Read Array		Read Status	Read Array
Erase Setup	"1"	Status	Era	se Command Er	rror	Erase (Not Done)	Erase Cmd. Error	Erase (Not Done)	Erase Corr	mand Error
Erase Cmd. Error	"1"	Status	Read Array	Prog. Setup	Ers. Setup		Read Array		Read Status	Read Array
Erase (Not Done)	"0"	Status		Erase (No	ot Done)	•	Erase Sus. Status		Erase (Not Done	:)
Ers. Susp. Status	"1"	Status	Erase Sus. Read Array	Prog. Setup	Ers. Sus. Rd. Array	Erase	Ers. Sus. Rd. Array	Erase	Erase Sus. Status	Ers. Sus. Rd. Array
Erase Susp. Array	"1"	Array	Erase Sus. Read Array	Prog. Setup	Ers. Sus. Rd. Array	Erase	Ers. Sus. Rd. Array	Erase	Erase Sus. Status	Ers. Sus. Rd. Array
Ers. Susp. Read Config	"1"	Config	Erase Sus. Read Array	Prog. Setup	Ers. Sus. Rd. Array	Erase	Ers. Sus. Rd. Array	Erase	Erase Sus. Status	Ers. Sus. Rd. Array
Ers. Susp. Read Query	"1"	CFI	Erase Sus. Read Array	Prog. Setup	Ers. Sus. Rd. Array	Erase	Ers. Sus. Rd. Array	Erase	Erase Sus. Status	Ers. Sus. Rd. Array
Erase (Done)	"1"	Status	Read Array	Prog. Setup	Ers. Setup		Read Array		Read Sts.	Read Array

## Appendix A: WSM Current/Next States, Sheet 2 of 2

			Com	mand Input (and Next	State)		
Current State	Read Config (90H)	Read Query (98H)	Lock Setup (60H)	Prot. Prog. Setup (C0H)	Lock Confirm (01H)	Lock Down Confirm (2FH)	Unlock Confirm (D0H)
Read Array	Read Config.	Read Query	Lock Setup	Prot. Prog. Setup		Read Array	
Read Status	Read Config.	Read Query	Lock Setup	Prot. Prog. Setup		Read Array	
Read Config.	Read Config.	Read Query	Lock Setup	Prot. Prog. Setup		Read Array	
Read Query	Read Config.	Read Query	Lock Setup	Prot. Prog. Setup		Read Array	
Lock Setup		Locking Cor	nmand Error	T	L	ock Operation (Don	e)
Lock Cmd. Error	Read Config.	Read Query	Lock Setup	Prot. Prog. Setup		Read Array	
Lock Oper. (Done)	Read Config.	Read Query	Lock Setup	Prot. Prog. Setup		Read Array	
Prot. Prog. Setup			Pr	otection Register Progr	ram		
Prot. Prog. (Not Done)			Protectio	on Register Program (N	Not Done)		
Prot. Prog. (Done)	Read Config.	Read Query	Lock Setup	Prot. Prog. Setup		Read Array	
Prog. Setup		•		Program			
Program (Not Done)				Program (Not Done)			
Prog. Susp. Status	Prog. Susp. Read Config.	Prog. Susp. Read Query		Program Suspe	end Read Array		Program (Not Done)
Prog. Susp. Read Array	Prog. Susp. Read Config.	Prog. Susp. Read Query		Program Suspe	end Read Array		Program (Not Done)
Prog. Susp. Read Config.	Prog. Susp. Read Config.	Prog. Susp. Read Query	Program Suspend Read Arra				Program (Not Done)
Prog. Susp. Read Query.	Prog. Susp. Read Config.	Prog. Susp. Read Query		Program Suspe	end Read Array		Program (Not Done)
Program (Done)	Read Config.	Read Query	Lock Setup	Prot. Prog. Setup		Read Array	
Erase Setup			Erase Cor	nmand Error			Erase (Not Done)
Erase Cmd. Error	Read Config.	Read Query	Lock Setup	Prot. Prog. Setup		Read Array	
Erase (Not Done)				Erase (Not Done)			
Erase Susp. Status	Ers. Susp. Read Config.	Erase Suspend Read Query	Lock Setup	Era	ase Suspend Read Arr	ay	Erase (Not Done)
Erase Suspend Array	Ers. Susp. Read Config.	Erase Suspend Read Query	Lock Setup	Era	ase Suspend Read Array Erase (Not Done)		
Eras Sus. Read Config	Erase Suspend Read Config.	Erase Suspend Read Query	Lock Setup	Era	rase Suspend Read Array Erase (Not Done)		
Eras Sus. Read Query	Erase Suspend Read Config.	Erase Suspend Read Query	Lock Setup	Era	ase Suspend Read Arr	ay	Erase (Not Done)
Ers.(Done)	Read Config.	Read Query	Lock Setup	Prot. Prog. Setup		Read Array	



## **Appendix B Program/Erase Flowcharts**







## Figure 13. Program Suspend/Resume Flowchart





### Figure 14. Automated Block Erase Flowchart



## Figure 15. Erase Suspend/Resume Flowchart





Comments

D0H (Unlock Block)

2FH (Lockdown Block)

Data= 01H (Lock Block)

Addr=Within block to lock

Block Lock Status Data Addr = Second addr of block

Confirm Locking Change on  $DQ_1$ ,  $DQ_0$ . (See Block Locking State Table for valid combinations.)

Data = 60H Addr = X

Data = 90H

Addr = X

#### Bus Operation Start Command ¥ Write Config. Setup Write 60H (Configuration Setup) Lock, Unlock, Write or Lockdown Write 01H, D0H, or 2FH Write Read (Optional) Configuration Read (Optional) Block Lock Status Write 90H (Read Configuration) Standby (Optional) Read Block Lock Status Optional Locking Change Confirmed? No Write FFh (Read Array) Locking Change Complete

## Figure 16. Locking Operations Flowchart

## Figure 17. Protection Register Programming Flowchart





## Appendix C Common Flash Interface Query Structure

This appendix defines the data structure or "database" returned by the Common Flash Interface (CFI) Query command. System software should parse this structure to gain critical information such as block size, density, x8/x16, and electrical specifications. Once this information has been obtained, the software will know which command sets to use to enable flash writes, block erases, and otherwise control the flash component. The Query is part of an overall specification for multiple command set and control-interface descriptions called Common Flash Interface, or CFI.

## C.1 Query Structure Output

The Query "database" allows system software to gain information for controlling the flash component. This section describes the device's CFI-compliant interface that allows the host system to access Query data.

Query data are always presented on the lowest order data outputs  $(DQ_{0-7})$  only. The numerical offset value is the address relative to the maximum bus width supported by the device. On this family of devices, the Query table device starting address is a 10h, which is a word address for x16 devices.

For a word-wide (x16) device, the first two bytes of the Query structure, "Q" and "R" in ASCII, appear on the low byte at word addresses 10h and 11h. This CFI-compliant device outputs 00H data on upper bytes. Thus, the device outputs ASCII "Q" in the low byte ( $DQ_{0-7}$ ) and 00h in the high byte ( $DQ_{8-15}$ ).

At Query addresses containing two or more bytes of information, the least significant data byte is presented at the lower address, and the most significant data byte is presented at the higher address.

In all of the following tables, addresses and data are represented in hexadecimal notation, so the "h" suffix has been dropped. In addition, since the upper byte of word-wide devices is always "00h," the leading "00" has been dropped from the table notation and only the lower byte value is shown. Any x16 device outputs can be assumed to have 00h on the upper byte in this mode.

## Table 12. Summary of Query Structure Output As a Function of Device and Mode

Device	Hex Offset	Code	ASCII Value
	10:	51	"Q"
Device Addresses	11:	52	"R"
	12:	59	"Y"

	Word Addressing			Byte Addressing	
Offset	Hex Code	Value	Offset	Hex Code	Value
A <sub>15</sub> -A <sub>0</sub>	D <sub>15</sub>	-D <sub>0</sub>	A <sub>7</sub> -A <sub>0</sub>	D <sub>7</sub>	-D <sub>0</sub>
0010h	0051	"Q"	10h	51	"Q"
0011h	0052	"R"	11h	52	"R"
0012h	0059	"Y"	12h	59	"Y"
0013h	P_ID <sub>LO</sub>	PrVendor	13h	P_ID <sub>LO</sub>	PrVendor
0014h	P_ID <sub>HI</sub>	ID #	14h	P_ID <sub>LO</sub>	ID #
0015h	P <sub>LO</sub>	PrVendor	15h	P_ID <sub>HI</sub>	ID #
0016h	P <sub>HI</sub>	TblAdr	16h		
0017h	A_ID <sub>LO</sub>	AltVendor	17h		
0018h	A_ID <sub>HI</sub>	ID #	18h		

## Table 13. Example of Query Structure Output of x16 and x8 Devices

## C.2 Query Structure Overview

The Query command causes the flash component to display the Common Flash Interface (CFI) Query structure or "database." The structure sub-sections and address locations are summarized below.

## Table 14. Query Structure<sup>(1)</sup>

Offset	Sub-Section Name	Description
00h		Manufacturer Code
01h		Device Code
(BA+2)h <sup>(2)</sup>	Block Status Register	Block-Specific Information
04-0Fh	Reserved	Reserved for Vendor-Specific Information
10h	CFI Query Identification String	Command Set ID and Vendor Data Offset
1Bh	System Interface Information	Device Timing and Voltage Information
27h	Device Geometry Definition	Flash Device Layout
P <sup>(3)</sup>	Primary Intel-Specific Extended Query Table	Vendor-Defined Additional Information Specific to the Primary Vendor Algorithm

#### NOTES:

1. Refer to the Query Structure Output section and offset 28h for the detailed definition of offset address as a function of device bus width and mode.

2. BA = The beginning location of a Block Address (e.g., 08000h is the beginning location of block 1 when the block size is 32 Kword).

3. Offset 15 defines "P" which points to the Primary Intel-specific Extended Query Table.



## C.3 Block Lock Status Register

The block-status register indicates whether an Erase operation completed successfully or whether a given block is locked or can be accessed for flash Program/Erase operations.

Block Erase Status (BSR.1) allows system software to determine the success of the last Block Erase operation. BSR.1 can be used just after power-up to verify that the  $V_{CC}$  supply was not accidentally removed during an Erase operation. This bit is reset only by issuing another Erase operation to the block. The block-status register is accessed from word address 02h within each block.

## Table 15. Block Status Register

Offset	Length	Description	Add.	Value
(BA+2)h <sup>(1)</sup>	1	Block Lock Status Register	BA+2:	00 or01
		BSR.0 Block Lock Status 0 = Unlocked 1 = Locked	BA+2:	(bit 0): 0 or 1
		BSR.1 Block Lock-Down Status 0 = Not locked down 1 = Locked down	BA+2:	(bit 1): 0 or 1
		BSR 2–7: Reserved for future use	BA+2:	(bit 2–7): 0

#### NOTE:

1. BA = The beginning location of a Block Address (i.e., 008000h is the beginning location of block 1 in word mode.)

## C.4 CFI Query Identification String

The Identification String provides verification that the component supports the Common Flash Interface specification. It also indicates the specification version and supported vendor-specified command set(s).

Offset	Length	Description	Add.	Hex Code	Value
10h	3	Query-unique ASCII string "QRY"	10 11: 12:	51 52 59	"Q" "R" "Y"
13h	2	Primary vendor command set and control interface ID code 16-bit ID code for vendor-specified algorithms	13: 14:	03 00	
15h	2	Extended Query Table primary algorithm address	15: 16:	35 00	
17h	2	Alternate vendor command set and control interface ID code 0000h means no second vendor-specified algorithm exists	17: 18:	00 00	
19h	2	Secondary algorithm Extended Query Table address 0000h means none exists	19: 1A:	00 00	

## Table 16. CFI Identification

## C.5 System Interface Information

Offset	Length	Description	Add.	Hex Code	Value
1Bh	1	V <sub>CC</sub> logic supply minimum program/erase voltage bits 0–3 BCD 100 mV bits 4–7 BCD volts	1B:	27	2.7 V
1Ch	1	V <sub>CC</sub> logic supply maximum program/erase voltage bits 0–3 BCD 100 mV bits 4–7 BCD volts	1C:	36	3.6 V
1Dh	1	V <sub>PP</sub> [programming] supply minimum program/erase voltage bits 0–3 BCD 100 mV bits 4–7 HEX volts	1D:	B4	11.4 V
1Eh	1	V <sub>PP</sub> [programming] supply maximum program/erase voltage bits 0–3 BCD 100 mV bits 4–7 HEX volts	1E:	C6	12.6 V
1Fh	1	"n" such that typical single word program time-out = $2^n \mu s$	1F:	05	32 µs
20h	1	"n" such that typical max. buffer write time-out = $2^{n} \mu s$	20:	00	NA
21h	1	"n" such that typical block erase time-out = 2 <sup>n</sup> ms	21:	0A	1 s
22h	1	"n" such that typical full chip erase time-out = $2^{n}$ ms	22:	00	NA
23h	1	"n" such that maximum word program time-out = $2^{n}$ times typical	23:	04	512µs
24h	1	"n" such that maximum buffer write time-out = 2 <sup>n</sup> times typical	24:	00	NA
25h	1	"n" such that maximum block erase time-out = 2 <sup>n</sup> times typical	25:	03	8s
26h	1	"n" such that maximum chip erase time-out = $2^{n}$ times typical	26:	00	NA

## Table 17. System Interface Information



## C.6 Device Geometry Definition

## Table 18. Device Geometry Definition

Offset	Length	Description	S	Code See table below	
27h	1	"n" such that device size = $2^{n}$ in number of bytes	27:		
28h	2	Flash device interface: <u>x8 async x16 async x8/x16 async</u>	28:	01	x16
		28:00,29:00 28:01,29:00 28:02,29:00	29:	00	
2Ah	2	"n" such that maximum number of bytes in write buffer = $2^{n}$	2A: 2B:	00 00	0
2Ch	1	<ul> <li>Number of erase block regions within device:</li> <li>1. x = 0 means no erase blocking; the device erases in "bulk"</li> <li>2. x specifies the number of device or partition regions with one or more contiguous same-size erase blocks.</li> <li>3. Symmetrically blocked partitions have one blocking region</li> <li>4. Partition size = (total blocks) x (individual block size)</li> </ul>	2C:	02	2
2Dh	4	Erase Block Region 1 Information bits 0–15 = y, y+1 = number of identical-size erase blocks bits 16–31 = z, region erase block(s) size are z x 256 bytes	2D: 2E: 2F: 30:		
31h	4	Erase Block Region 2 Information bits 0–15 = y, y+1 = number of identical-size erase blocks bits 16–31 = z, region erase block(s) size are z x 256 bytes	31: 32: 33: 34:		

			Device	Geometry De	finition			
Address	8 N	8 Mbit		Vibit	32 Mbit		64	Vibit
Audress	-B	-т	-В	-т	- <b>B</b>	-Т	-B	-Т
27:	14	14	15	15	16	16	17	17
28:	01	01	01	01	01	01	01	01
29:	00	00	00	00	00	00	00	00
2A:	00	00	00	00	00	00	00	00
2B:	00	00	00	00	00	00	00	00
2C:	02	02	02	02	02	02	02	02
2D:	07	0E	07	1E	07	3E	07	7E
2E:	00	00	00	00	00	00	00	00
2F:	20	00	20	00	20	00	20	00
30:	00	01	00	01	00	01	00	01
31:	0E	07	1E	07	3E	07	7E	07
32:	00	00	00	00	00	00	00	00
33:	00	20	00	20	00	20	00	20
34:	01	00	01	00	01	00	01	00

## C.7 Intel-Specific Extended Query Table

Certain flash features and commands are optional. The Intel-Specific Extended Query table specifies this and other similar types of information.

Offset(1) P = 35h	Length	Description (Optional Flash Features and Commands)	Address	Hex Code	Value
(P+0)h (P+1)h (P+2)h	3	Primary extended query table Unique ASCII string "PRI"	35: 36: 37:	50 52 49	"P" "R" "I"
(P+3)h	1	Major version number, ASCII	38:	31	"1"
(P+4)h	1	Minor version number, ASCII	39:	30	"0"
		Optional feature and command support (1=yes, 0=no) bits 9–31 are reserved; undefined bits are "0." If bit 31 is "1" then another 31 bit field of optional features follows at the end of the bit-30 field.	3A: 3B: 3C: 3D:	66 00 00 00	
(P+5)h (P+6)h (P+7)h (P+8)h	4	bit 0 Chip erase supported bit 1 Suspend erase supported bit 2 Suspend program supported bit 3 Legacy lock/unlock supported bit 4 Queued erase supported bit 5 Instant individual block locking supported bit 6 Protection bits supported bit 7 Page mode read supported bit 8 Synchronous read supported	bit 4 bit 5 bit 6	= 1 = 1 = 0 = 0 = 1 = 1 = 0	No Yes No No Yes Yes No No
(P+9)h	1	Supported functions after suspend: Read Array, Status, Query Other supported operations are: bits 1–7 reserved; undefined bits are "0"	3E:	01	
		bit 0 Program supported after erase suspend	bit 0	= 1	Yes
		Plack status register meak	3F:	03	
(P+A)h	2	Block status register mask bits 2–15 are Reserved; undefined bits are "0"	40:	00	
(P+B)h	2	bit 0 Block Lock-Bit Status Register active bit 1 Block Lock-Down Bit Status active	bit 0	= 1	Yes
			bit 1	= 1	Yes
(P+C)h	1	V <sub>CC</sub> logic supply highest performance program/ erase voltage bits 0–3 BCD value in 100 mV bits 4–7 BCD value in volts	41:	33	3.3 V
(P+D)h	1	V <sub>PP</sub> optimum program/erase supply voltage bits 0–3 BCD value in 100 mV bits 4–7 HEX value in volts	42:	C0	12.0 V

## Table 19. Primary-Vendor Specific Extended Query

Table		ction Register information			
Offset(1) P = 35h	Length	Description (Optional Flash Features and Commands)	Address	Hex Code	Value
(P+E)h	1	Number of Protection register fields in JEDEC ID space. "00h," indicates that 256 protection bytes are available	43:	01	01
(P+F)h (P+10)h (P+11)h		Protection Field 1: Protection Description	44: 45: 46:	80 00 03	80h 00h 8 byte
(P+12)h	4	This field describes user-available One Time Programmable (OTP) Protection register bytes. Some are pre-programmed with device- unique serial numbers. Others are user programmable. Bits 0–15 point to the Protection register Lock byte, the section's first byte. The following bytes are factory pre-programmed and user- programmable. bits 0–7 = Lock/bytes JEDEC-plane physical low address bits 8–15 = Lock/bytes JEDEC -plane physical high address bits 16–23 = "n" such that $2^n$ = factory pre-programmed bytes bits 24–31 = "n" such that $2^n$ = user programmable bytes	47:	03	8 byte
(P+13)h		Reserved for future use	48:		

### Table 20. Protection Register Information

**NOTE:** 1. The variable P is a pointer which is defined at CFI offset 15h.



## Appendix D Architecture Block Diagram



## Appendix E Word-Wide Memory Map Diagrams

	8-Mbit Word-Wide Memory Addressing							
		Top Boot	Bottom Boot					
Size (KW)	8 Mbit		Size (KW)	8 Mbit				
4	7F000-7FFFF		32	78000-7FFFF				
4	7E000-7EFFF		32	70000-77FFF				
4	7D000-7DFFF		32	68000-6FFFF				
4	7C000-7CFFF		32	60000-67FFF				
4	7B000-7BFFF		32	58000-5FFFF				
4	7A000-7AFFF		32	50000-57FFF				
4	79000-79FFF		32	48000-4FFFF				
4	78000-78FFF		32	40000-47FFF				
32	70000-77FFF		32	38000-3FFFF				
32	68000-6FFFF		32	30000-37FFF				
32	60000-67FFF		32	28000-2FFFF				
32	58000-5FFFF		32	20000-27FFF				
32	50000-57FFF		32	18000-1FFFF				
32	48000-4FFFF		32	10000-17FFF				
32	40000-47FFF		32	08000-0FFFF				
32	38000-3FFFF		4	07000-07FFF				
32	30000-37FFF		4	06000-06FFF				
32	28000-2FFFF		4	05000-05FFF				
32	20000-27FFF		4	04000-04FFF				
32	18000-1FFFF		4	03000-03FFF				
32	10000-17FFF		4	02000-02FFF				
32	08000-0FFFF		4	01000-01FFF				
32	00000-07FFF		4	00000-00FFF				

	16-Mbit, 32-Mbit, and 64-Mbit Word-Wide Memory Addressing									
Top Boot Bottom Boot										
Size (KW)	16 Mbit	32 Mbit	64 Mbit	Size (KW)	16 Mbit	32 Mbit	64 Mbit			
4	FF000-FFFFF	1FF000-1FFFFF	3FF000-3FFFFF	32			3F8000-3FFFFF			
4	FE000-FEFFF	1FE000-1FEFFF	3FE000-3FEFFF	32			3F0000-3F7FFF			
4	FD000-FDFFF	1FD000-1FDFFF	3FD000-3FDFFF	32			3E8000-3EFFFF			
4	FC000-FCFFF	1FC000-1FCFFF	3FC000-3FCFFF	32			3E0000-3E7FFF			
4	FB000-FBFFF	1FB000-1FBFFF	3FB000-3FBFFF	32			3D8000-3DFFFF			
4	FA000-FAFFF	1FA000-1FAFFF	3FA000-3FAFFF	32			3D0000-3D7FFF			
4	F9000-F9FFF	1F9000-1F9FFF	3F9000-3F9FFF	32			3C8000-3CFFFF			
4	F8000-F8FFF	1F8000-1F8FFF	3F8000-3F8FFF	32			3C0000-3C7FFF			
32	F0000-F7FFF	1F0000-1F7FFF	3F0000-3F7FFF	32			3B8000-3BFFFF			
32	E8000-EFFFF	1E8000-1EFFFF	3E8000-3EFFFF	32			3B0000-3B7FFF			
32	E0000-E7FFF	1E0000-1E7FFF	3E0000-3E7FFF	32			3A8000-3AFFFF			
32	D8000-DFFFF	1D8000-1DFFFF	3D8000-3DFFFF	32			3A0000-3A7FFF			
32	D0000-D7FFF	1D0000-1D7FFF	3D0000-3D7FFF	32			398000-39FFFF			
32	C8000-CFFFF	1C8000-1CFFFF	3C8000-3CFFFF	32			390000-397FFF			
32	C0000-C7FFF	1C0000-1C7FFF	3C0000-3C7FFF	32			388000-38FFFF			
32	B8000-BFFFF	1B8000-1BFFFF	3B8000-3BFFFF	32			380000-387FFF			
32	B0000-B7FFF	1B0000-1B7FFF	3B0000-3B7FFF	32			378000-37FFFF			
32	A8000-AFFFF	1A8000-1AFFFF	3A8000-3AFFFF	32			370000-377FFF			
32	A0000-A7FFF	1A0000-1A7FFF	3A0000-3A7FFF	32			368000-36FFFF			
32	98000-9FFFF	198000-19FFFF	398000-39FFFF	32			360000-367FFF			
32	90000-97FFF	190000-197FFF	390000-397FFF	32			358000-35FFFF			
32	88000-8FFFF	188000-18FFFF	388000-38FFFF	32			350000-357FFF			
32	80000-87FFF	180000-187FFF	380000-387FFF	32			348000-34FFFF			
32	78000-7FFFF	178000-17FFFF	378000-37FFFF	32			340000-347FFF			
32	70000-77FFF	170000-177FFF	370000-377FFF	32			338000-33FFFF			
32	68000-6FFFF	168000-16FFFF	368000-36FFFF	32			330000-337FFF			
32	60000-67FFF	160000-167FFF	360000-367FFF	32			328000-32FFFF			
32	58000-5FFFF	158000-15FFFF	358000-35FFFF	32			320000-327FFF			
32	50000-57FFF	150000-157FFF	350000-357FFF	32			318000-31FFFF			
32	48000-4FFFF	148000-14FFFF	348000-34FFFF	32			310000-317FFF			
32	40000-47FFF	140000-147FFF	340000-347FFF	32			308000-30FFFF			
32	38000-3FFFF	138000-13FFFF	338000-33FFFF	32			300000-307FFF			
32	30000-37FFF	130000-137FFF	330000-337FFF	32			2F8000-2FFFFF			
32	28000-2FFFF	128000-12FFFF	328000-32FFFF	32			2F0000-2F7FFF			
32	20000-27FFF	120000-127FFF	320000-327FFF	32			2E8000-2EFFFF			
32	18000-1FFFF	118000-11FFFF	318000-31FFFF	32			2E0000-2E7FFF			
32	10000-17FFF	110000-117FFF	310000-317FFF	32			2D8000-2DFFFF			
32	08000-0FFFF	108000-10FFFF	308000-30FFFF	32			2D0000-2D7FFF			
32	00000-07FFF	100000-107FFF	300000-307FFF	32			2C8000-2CFFFF			
32		0F8000-0FFFFF	2F8000-2FFFFF	32			2C0000-2C7FFF			
32		0F0000-0F7FFF	2F0000-2F7FFF	32			2B8000-2BFFFF			
32		0E8000-0EFFFF	2E8000-2EFFFF	32			2B0000-2B7FFF			
32		0E0000-0E7FFF	2E0000-2E7FFF	32			2A8000-2AFFFF			
32		0D8000-0DFFFF	2D8000-2DFFFF	32			2A0000-2A7FFF			
32		0D0000-0D7FFF	2D0000-2D7FFF	32			298000-29FFFF			
32		0C8000-0CFFFF	2C8000-2CFFFF	32			290000-297FFF			
32		0C0000-0C7FFF	2C0000-2C7FFF	32			288000-28FFFF			
32		0B8000-0BFFFF	2B8000-2BFFFF	32			280000-287FFF			
32		0B0000-0B7FFF	2B0000-2B7FFF	32			278000-27FFFF			
32		0A8000-0AFFFF	2A8000-2AFFFF	32			270000-277FFF			
	This colum	nn continues on next p	age		This column	continues on next p	bage			

		Top Boot		Bottom Boot				
Size				Sizo				
(KW)	16 Mbit	32 Mbit	64 Mbit	(KW)	16 Mbit	32 Mbit	64 Mbit	
32		0A0000-0A7FFF	2A0000-2A7FFF	32			268000-26FFFF	
32		098000-09FFFF	298000-29FFFF	32			260000-267FFF	
32		090000-097FFF	290000-297FFF	32			258000-25FFFF	
32		088000-08FFFF	288000-28FFFF	32			250000-257FFF	
32		080000-087FFF	280000-287FFF	32			248000-24FFFF	
32		078000-07FFFF	278000-27FFFF	32			240000-247FFF	
32		070000-077FFF	270000-277FFF	32			238000-23FFFF	
32		068000-06FFFF	268000-26FFFF	32			230000-237FFF	
32		060000-067FFF	260000-267FFF	32			228000-22FFFF	
32		058000-05FFFF	258000-25FFFF	32			220000-227FFF	
32		050000-057FFF	250000-257FFF	32			218000-21FFFF	
32		048000-04FFFF	248000-24FFFF	32			210000-217FFF	
32		040000-047FFF	240000-247FFF	32			208000-20FFFF	
32		038000-03FFFF	238000-23FFFF	32			200000-207FFF	
32		030000-037FFF	230000-237FFF	32		1F8000-1FFFFF	1F8000-1FFFFF	
32		028000-02FFFF	228000-22FFFF	32		1F0000-1F7FFF	1F0000-1F7FFF	
32		020000-027FFF	220000-227FFF	32		1E8000-1EFFFF	1E8000-1EFFFF	
32		018000-01FFFF	218000-21FFFF	32		1E0000-1E7FFF	1E0000-1E7FFF	
32		010000-017FFF	210000-217FFF	32		1D8000-1DFFFF	1D8000-1DFFFF	
32		008000-00FFFF	208000-21FFFF	32		1D0000-1D7FFF	1D0000-1D7FFF	
32		000000-007FFF	200000-207FFF	32		1C8000-1CFFFF	1C8000-1CFFFF	
32			1F8000-1FFFFF	32		1C0000-1C7FFF	1C0000-1C7FFF	
32			1F0000-1F7FFF	32		1B8000-1BFFFF	1B8000-1BFFFF	
32			1E8000-1EFFFF	32		1B0000-1B7FFF	1B0000-1B7FFF	
32			1E0000-1E7FFF	32		1A8000-1AFFFF	1A8000-1AFFFF	
32			1D8000-1DFFFF	32		1A0000-1A7FFF	1A0000-1A7FFF	
32			1D0000-1D7FFF	32		198000-19FFFF	198000-19FFFF	
32			1C8000-1CFFFF	32		190000-197FFF	190000-197FFF	
32			1C0000-1C7FFF	32		188000-18FFFF	188000-18FFFF	
32			1B8000-1BFFFF	32		180000-187FFF	180000-187FFF	
32			1B0000-1B7FFF	32		178000-17FFFF	178000-17FFFF	
32			1A8000-1AFFFF	32		170000-177FFF	170000-177FFF	
32			1A0000-1A7FFF	32		168000-16FFFF	168000-16FFFF	
32			198000-19FFFF	32		160000-167FFF	160000-167FFF	
32			190000-197FFF	32		158000-15FFFF	158000-15FFFF	
32			188000-18FFFF	32		150000-157FFF	150000-157FFF	
				-			148000-14FFFF	
32 32			180000-187FFF	32 32		148000-14FFFF 140000-147FFF	140000-14FFFF	
			178000-17FFFF 170000-177FFF				138000-13FFFF	
32				32		138000-13FFFF		
32			168000-16FFFF	32		130000-137FFF	130000-137FFF	
32			160000-167FFF	32		128000-12FFFF	128000-12FFFF	
32			158000-15FFFF	32		120000-127FFF	120000-127FFF	
32			150000-157FFF	32		118000-11FFFF	118000-11FFFF	
32			148000-14FFFF	32		110000-117FFF	110000-117FFF	
32			140000-147FFF	32		108000-10FFFF	108000-10FFFF	
32			138000-13FFFF	32		100000-107FFF	100000-107FFF	
32			130000-137FFF	32	F8000-FFFFF	F8000-FFFFF	F8000-FFFFF	
32			128000-12FFFF	32	F0000-F7FFF	F0000-F7FFF	F0000-F7FFF	
32			120000-127FFF	32	E8000-EFFFF	E8000-EFFFF	E8000-EFFFF	
32			118000-11FFFF	32	E0000-E7FFF	E0000-E7FFF	E0000-E7FFF	
32			110000-117FFF	32	D8000-DFFFF	D8000-DFFFF	D8000-DFFFF	
32			108000-10FFFF	32	D0000-D7FFF	D0000-D7FFF	D0000-D7FFF	
32			100000-107FFF	32	C8000-CFFFF	C8000-CFFFF	C8000-CFFFF	
32			0F8000-0FFFFF	32	C0000-C7FFF	C0000-C7FFF	C0000-C7FFF	

Top Boot					Bottom Boot				
Size (KW)	16 Mbit	32 Mbit	64 Mbit	Size (KW)			64 Mbit		
32			0F0000-0F7FFF	32	B8000-BFFFF	B8000-BFFFF	B8000-BFFFF		
32			0E8000-0EFFFF	32	B0000-B7FFF	B0000-B7FFF	B0000-B7FFF		
32			0E0000-0E7FFF	32	A8000-AFFFF	A8000-AFFFF	A8000-AFFFF		
32			0D8000-0DFFFF	32	A0000-A7FFF	A0000-A7FFF	A0000-A7FFF		
32			0D0000-0D7FFF	32	98000-9FFFF	98000-9FFFF	98000-9FFFF		
32			0C8000-0CFFFF	32	90000-97FFF	90000-97FFF	90000-97FFF		
32			0C0000-0C7FFF	32	88000-8FFFF	88000-8FFFF	88000-8FFFF		
32			0B8000-0BFFFF	32	80000-87FFF	80000-87FFF	80000-87FFF		
32			0B0000-0B7FFF	32	78000-7FFFF	78000-7FFFF	78000-7FFFF		
32			0A8000-0AFFFF	32	70000-77FFF	70000-77FFF	70000-77FFF		
32			0A0000-0A7FFF	32	68000-6FFFF	68000-6FFFF	68000-6FFFF		
32			098000-09FFFF	32	60000-67FFF	60000-67FFF	60000-67FFF		
32			090000-097FFF	32	58000-5FFFF	58000-5FFFF	58000-5FFFF		
32			088000-08FFFF	32	50000-57FFF	50000-57FFF	50000-57FFF		
32			080000-087FFF	32	48000-4FFFF	48000-4FFFF	48000-4FFFF		
32			078000-07FFFF	32	40000-47FFF	40000-47FFF	40000-47FFF		
32			070000-077FFF	32	38000-3FFFF	38000-3FFFF	38000-3FFFF		
32			068000-06FFFF	32	30000-37FFF	30000-37FFF	30000-37FFF		
32			060000-067FFF	32	28000-2FFFF	28000-2FFFF	28000-2FFFF		
32			058000-05FFFF	32	20000-27FFF	20000-27FFF	20000-27FFF		
32			050000-057FFF	32	18000-1FFFF	18000-1FFFF	18000-1FFFF		
32			048000-04FFFF	32	10000-17FFF	10000-17FFF	10000-17FFF		
32			040000-047FFF	32	08000-0FFFF	08000-0FFFF	08000-0FFFF		
32			038000-03FFFF	4	07000-07FFF	07000-07FFF	07000-07FFF		
32			030000-037FFF	4	06000-06FFF	06000-06FFF	06000-06FFF		
32			028000-02FFFF	4	05000-05FFF	05000-05FFF	05000-05FFF		
32			020000-027FFF	4	04000-04FFF	04000-04FFF	04000-04FFF		
32			018000-01FFFF	4	03000-03FFF	03000-03FFF	03000-03FFF		
32			010000-017FFF	4	02000-02FFF	02000-02FFF	02000-02FFF		
32			008000-00FFFF	4	01000-01FFF	01000-01FFF	01000-01FFF		
32			000000-007FFF	4	00000-00FFF	00000-00FFF	00000-00FFF		

## 16-Mbit, 32-Mbit, and 64-Mbit Word-Wide Memory Addressing

## Appendix F Device ID Table

Read Configuration Addresses and Data							
ltem	Address	Data					
Manufacturer Code	x16	00000	0089				
Device Code							
8-Mbit x 16-T	x16	00001	88C0				
8-Mbit x 16-B	x16	00001	88C1				
16-Mbit x 16-T	x16	00001	88C2				
16-Mbit x 16-B	x16	00001	88C3				
32-Mbit x 16-T	x16	00001	88C4				
32-Mbit x 16-B	x16	00001	88C5				
64-Mbit x 16-T	x16	00001	88CC				
64-Mbit x 16-B	x16	00001	88CD				

NOTE: Other locations within the configuration address space are reserved by Intel for future use.

## Appendix G Protection Register Addressing

Word	Use	A7	<b>A6</b>	A5	A4	A3	A2	A1	A0
LOCK	Both	1	0	0	0	0	0	0	0
0	Factory	1	0	0	0	0	0	0	1
1	Factory	1	0	0	0	0	0	1	0
2	Factory	1	0	0	0	0	0	1	1
3	Factory	1	0	0	0	0	1	0	0
4	User	1	0	0	0	0	1	0	1
5	User	1	0	0	0	0	1	1	0
6	User	1	0	0	0	0	1	1	1
7	User	1	0	0	0	1	0	0	0

### Word-Wide Protection Register Addressing

**NOTE:** All address lines not specified in the above table must be 0 when accessing the Protection Register, i.e.,  $A_{21}$ – $A_8$  = 0.

1.0	Intro	oduction	1	1						
	1.1	Produc	ct Overview	2						
2.0	Proc	duct De	scription	3						
	2.1	Packag	ge Pinouts	3						
	2.2	Block (	Organization	9						
		2.2.1	Parameter Blocks	9						
		2.2.2	Main Blocks	9						
3.0	Principles of Operation									
	3.1	Bus Op	peration	9						
		3.1.1	Read							
		3.1.2	Output Disable	10						
		3.1.3	Standby							
		3.1.4	Reset							
		3.1.5	Write							
	3.2		of Operation							
		3.2.1	Read Array							
		3.2.2	Read Configuration							
		3.2.3	Read Status Register							
		3.2.4	Read Query							
		3.2.5	Program Mode							
	3.3	3.2.6	Erase Mode							
	3.3	3.3.1	e Block Locking Locking Operation							
		3.3.1	Unlocked State							
		3.3.2	Lock-Down State							
		3.3.4	Reading Block-Lock Status							
		3.3.5	Locking Operations during Erase Suspend							
		3.3.6	Status Register Error Checking							
	3.4		t Protection Register							
	011	3.4.1	Reading the Protection Register							
		3.4.2	Programming the Protection Register							
		3.4.3	Locking the Protection Register							
	3.5	V <sub>PP</sub> Pr	ogram and Erase Voltages							
		3.5.1	Improved 12-Volt Production Programming							
		3.5.2	VPP £ VPPLK for Complete Protection							
	3.6	Power	Consumption	22						
		3.6.1	Active Power (Program/Erase/Read)							
		3.6.2	Automatic Power Savings (APS)	23						
		3.6.3	Standby Power							
		3.6.4	Deep Power-Down Mode							
	3.7		-Up/Down Operation							
		3.7.1	RP# Connected to System Reset							
		3.7.2	VCC, VPP and RP# Transitions							
	3.8	Power	Supply Decoupling	24						
4.0	Elec	trical S	pecifications	25						
	4.1		ite Maximum Ratings							
	4.2	•	ting Conditions							
	4.3		itance							
	4.4	DC Ch	aracteristics	27						

	4.5 AC Characteristics—Read Operations	
	4.6 AC Characteristics—Write Operations	
	4.7 Erase and Program Timings	
	4.8 Reset Operations	
5.0	Ordering Information	
6.0	Additional Information	
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