

Freescale Semiconductor Product Brief

Document Number: MC56F8023PB Rev. 0, 09/2006

# 56F8023 Digital Signal Controller Product Brief

## 1 56F8023 Description

The 56F8023 is a member of the 56800E core-based family of Digital Signal Controllers (DSCs). It combines, on a single chip, the processing power of a DSP and the functionality of a microcontroller with a flexible set of peripherals to create an extremely cost-effective solution. Because of its low cost, configuration flexibility, and compact program code, the 56F8023 is well-suited for many applications. The 56F8023 includes many peripherals that are especially useful for industrial control, motion control, home appliances, general-purpose inverters, smart sensors, fire and security systems, switched-mode power supply, power management, and medical monitoring applications.

The 56800E core is based on a dual Harvard-style architecture consisting of three execution units operating in parallel, allowing as many as six operations per instruction cycle. The MCU-style programming model and optimized instruction set allow straightforward

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### 56F8023 Description

generation of efficient, compact DSP and control code. The instruction set is also highly efficient for C compilers to enable rapid development of optimized control applications.

The 56F8023 supports program execution from internal memories. Two data operands can be accessed from the on-chip data RAM per instruction cycle. The 56F8023 also offers up to 26 General-Purpose Input/Output (GPIO) lines, depending on peripheral configuration.

The 56F8023 Digital Signal Controller includes 32KB of Program Flash and 4KB of Unified Data/Program RAM. Program Flash memory can be independently bulk erased or erased in pages. Program Flash page erase size is 512 Bytes (256 Words).

A full set of programmable peripherals — PWM, ADCs, QSCI, QSPI, I2C, PIT, Quad Timers, DACs, and analog comparators — supports various applications. Each peripheral can be independently shut down to save power. Any pin in these peripherals can also be used as General Purpose Input/Outputs (GPIOs).



Figure 1. 56F8023 Block Diagram

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## 2 Digital Signal Controller Core

- Efficient 16-bit 56800E family Digital Signal Controller (DSC) engine with dual Harvard architecture
- As many as 32 Million Instructions Per Second (MIPS) at 32MHz core frequency
- Single-cycle 16 ¥ 16-bit parallel Multiplier-Accumulator (MAC)
- Four 36-bit accumulators, including extension bits
- 32-bit arithmetic and logic multi-bit shifter
- Parallel instruction set with unique DSP addressing modes
- Hardware DO and REP loops
- Three internal address buses
- Four internal data buses
- Instruction set supports both DSP and controller functions
- Controller-style addressing modes and instructions for compact code
- Efficient C compiler and local variable support
- Software subroutine and interrupt stack with depth limited only by memory
- JTAG/Enhanced On-Chip Emulation (OnCE) for unobtrusive, processor speed-independent, real-time debugging

## 3 Memory

- Dual Harvard architecture permits as many as three simultaneous accesses to program and data memory
- Flash security and protection that prevent unauthorized users from gaining access to the internal Flash
- On-chip memory
  - 32KB of Program Flash
  - 4KB of Unified Data/Program RAM
- EEPROM emulation capability using Flash

## 4 Peripheral Circuits for 56F8023

- One multi-function six-output Pulse Width Modulator (PWM) module
  - Up to 96MHz PWM operating clock
  - 15 bits of resolution
  - Center-aligned and edge-aligned PWM signal mode
  - Four programmable fault inputs with programmable digital filter
  - Double-buffered PWM registers
  - Each complementary PWM signal pair allows selection of a PWM supply source from:
    - PWM generator
    - External GPIO



### Peripheral Circuits for 56F8023

- Internal timers
- Analog comparator outputs
- ADC conversion result which compares with values of ADC high- and low-limit registers to set PWM output
- Two independent 12-bit Analog-to-Digital Converters (ADCs)
  - 2 x 3 channel inputs
  - Supports both simultaneous and sequential conversions
  - ADC conversions can be synchronized by both PWM and timer modules
  - Sampling rate up to 2.67MSPS
  - 16-word result buffer registers
- Two internal 12-bit Digital-to-Analog Converters (DACs)
  - 2 microsecond settling time when output swing from rail to rail
  - Automatic waveform generation generates square, triangle and sawtooth waveforms with programmable period, update rate, and range
- One 16-bit multi-purpose Quad Timer module (TMR)
  - Up to 96MHz operating clock
  - Eight independent 16-bit counter/timers with cascading capability
  - Each timer has capture and compare capability
  - Up to 12 operating modes
- One Queued Serial Communication Interface (QSCI) with LIN Slave functionality
  - Full-duplex or single-wire operation
  - Two receiver wake-up methods:
    - Idle line
    - Address mark
  - Four-bytes-deep FIFOs are available on both transmitter and receiver
- One Queued Serial Peripheral Interfaces (QSPI)
  - Full-duplex operation
  - Master and slave modes
  - Four-words-deep FIFOs available on both transmitter and receiver
  - Programmable Length Transactions (2 to 16 bits)
- One Inter-Integrated Circuit (I<sup>2</sup>C) port
  - Operates up to 400kbps
  - Supports both master and slave operation
  - Supports both 10-bit address mode and broadcasting mode
- One 16-bit Programmable Interval Timer (PIT)
- Two analog Comparators (CMPs)



- Selectable input source includes external pins, DACs
- Programmable output polarity
- Output can drive Timer input, PWM fault input, PWM source, external pin output and trigger ADCs
- Output falling and rising edge detection able to generate interrupts
- Computer Operating Properly (COP)/Watchdog timer capable of selecting different clock sources
- Up to 26 General-Purpose I/O (GPIO) pins with 5V tolerance
- Integrated Power-On Reset and Low-Voltage Interrupt Module
- Phase Lock Loop (PLL) provides a high-speed clock to the core and peripherals
- Clock sources:
  - On-chip relaxation oscillator
  - External clock: Crystal oscillator, ceramic resonator, and external clock source
- JTAG/EOnCE debug programming interface for real-time debugging

## 5 Recommended Operating Conditions

Characteristic	Symbol	Notes	Min	Тур	Max	Unit
Supply voltage	V <sub>DD,</sub> V <sub>DDA</sub>		3	3.3	3.6	V
ADC Reference Voltage High	V <sub>REFHx</sub>		3.0		V <sub>DDA</sub>	V
Voltage difference $V_{DD_{-}IO}$ to $V_{DDA}$	$\Delta V_{DD}$		-0.1	0	0.1	V
Voltage difference $V_{SS\_IO}$ to $V_{SSA}$	$\Delta V_{SS}$		-0.3	0	0.3	V
Device Clock Frequency Using relaxation oscillator Using external clock source	FSYSCLK		1 0		32 32	MHz
Input Voltage High (digital inputs)	V <sub>IH</sub>	Pin Groups 1, 2	2.0		5.5	V
Input Voltage Low (digital inputs)	V <sub>IL</sub>	Pin Groups 1, 2	-0.3		0.8	V
Oscillator Input Voltage High XTAL not driven by an external clock XTAL driven by an external clock source	V <sub>IHOSC</sub>	Pin Group 4	V <sub>DDA</sub> - 0.8 2.0		V <sub>DDA</sub> + 0.3 V <sub>DDA</sub> + 0.3	V

### Table 1. Recommended Operating Conditions

 $(V_{\text{REFL x}}=0V, V_{\text{SSA}}=0V, V_{\text{SS}}=0V)$ 



**Product Documentation** 

Characteristic	Symbol	Notes	Min	Тур	Max	Unit
Oscillator Input Voltage Low	V <sub>ILOSC</sub>	Pin Group 4	-0.3		0.8	V
Analog Input Voltage	V <sub>IA</sub>	Pin Group 3	0.0		V <sub>DDA</sub>	V
Output Source Current High at V <sub>OH</sub> min.) <sup>1</sup> When programmed for low drive strength When programmed for high drive strength	I <sub>OH</sub>	Pin Group 1 Pin Group 1			-4 -8	mA
Output Source Current Low (at V <sub>OL</sub> max.) <sup>1</sup> When programmed for low drive strength When programmed for high drive strength	I <sub>OL</sub>	Pin Groups 1, 2 Pin Groups 1, 2			4 8	mA
Ambient Operating Temperature (Automotive)	Τ <sub>Α</sub>		-40		125	°C
Ambient Operating Temperature (Extended Industrial)	Τ <sub>Α</sub>		-40		105	°C
Flash Endurance (Program Erase Cycles)	N <sub>F</sub>	T <sub>A</sub> = -40°C to 125°C	10,000		_	cycles
Flash Data Retention	Τ <sub>R</sub>	T <sub>J</sub> <= 70°C average	15		_	years

### Table 1. Recommended Operating Conditions (continued) $(V_{BEFL x} = 0V, V_{SSA} = 0V, V_{SS} = 0V)$

<sup>1</sup> Total chip source or sink current cannot exceed 75mA

## 6 Product Documentation

The documents listed in **Table 2** are required for a complete description and proper design with the 56F8023. Documentation is available from local Freescale distributors, Freescale Semiconductor sales offices, Freescale Literature Distribution Centers, or online at:

### http://www.freescale.com

Торіс	Description	Order Number		
DSP56800E Reference Manual	Detailed description of the 56800E family architecture, 16-bit Digital Signal Controller core processor, and the instruction set	DSP56800ERM		
56F802X and 56F803X Peripheral Reference Manual	Detailed description of peripherals of the 56F802x and 56F803x family of devices	MC56F80XXRM		
56F802X and 56F803X Serial Bootloader User Guide	Detailed description of the Serial Bootloader in the 56F802x and 56F803x family of devices	56F80XXBLUG		
56F8023 Technical Data Sheet	Electrical and timing specifications, pin descriptions, and package descriptions (this document)	MC56F8023		
56F8023 Errata	Details any chip issues that might be present	MC56F8023E		

### Table 2. 56F8023 Chip Documentation



### 7 56F8023 Package and Pin-Out



Figure 2. Top View, 56F8023 32-Pin LQFP Package

Peripheral pins in bold identify the reset state in Table 3.



56F8023 Package and Pin-Out

Pin #	Signal Name	Pin #	Signal Name	Pin #	Signal Name	Pin #	Signal Name
1	<b>GPIOB6</b> RXD0 / SDA / CLKIN	9	V <sub>SSA</sub>	17	<b>GPIOB2</b> MISO0 / TA2 / PSRC0	25	V <sub>CAP</sub>
2	GPIOB1 SS0/SDA	10	<b>GPIOC2</b> ANA2 / V <sub>REFHA</sub>	18	<b>GPIOA6</b> FAULT0 / TA0	26	V <sub>DD_IO</sub>
3	<b>GPIOB7</b> TXD0 / SCL	11	GPIOC1 ANA1	19	<b>GPIOB4</b> TA0 / CLKO / PSRC2	27	V <sub>SS_IO</sub>
4	<b>GPIOB5</b> TA1 / FAULT3 / CLKIN	12	GPIOC0 ANA0 & CINA3	20	<b>GPIOA5</b> PWM5 / TA3 / FAULT2	28	<b>GPIOA1</b> <i>PWM1</i>
5	GPIOC4 ANB0 & CINB3	13	V <sub>SS_IO</sub>	21	<b>GPIOB0</b> SCLK0 / SCL	29	<b>GPIOA0</b> <i>PWM0</i>
6	GPIOC5 ANB1	14	<b>TCI</b> GPIOD2	22	<b>GPIOA4</b> PWM4 / TA2 / FAULT1	30	<b>TDI</b> GPIOD0
7	<b>GPIOC6</b> ANB2 / V <sub>REFHB</sub>	15	<b>RESET</b> GPIOA7	23	<b>GPIOA2</b> <i>PWM</i> 2	31	TMS GPIOD3
8	V <sub>DDA</sub>	16	<b>GPIOB3</b> MOSI0 / TA3 / PSRC1	24	GPIOA3 PWM3	32	<b>TDO</b> GPIOD1

<sup>1</sup> Alternate signals are in italic

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- NOTES: 1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
- CONTROLLING DIMENSION: MILLIMETER.
   DATUM PLANE AB– IS LOCATED AT BOTTOM
- OF LEAD AND IS COINCIDENT WITH THE LEAD WHERE THE LEAD EXITS THE PLASTIC BODY AT
- THE BOTTOM OF THE PARTING LINE.
  4. DATUMS -T-, -U-, AND -Z- TO BE DETERMINED AT DATUM PLANE -AB-.
  5. DIMENSIONS S AND V TO BE DETERMINED AT
- SEATING PLANE -AC-.
  DIMENSIONS A AND B DO NOT INCLUDE MOLD
- PROTRUSION. ALLOWABLE PROTRUSION IS 0.250 (0.010) PER SIDE. DIMENSIONS A AND B DO INCLUDE MOLD MISMATCH AND ARE DETERMINED AT DATUM PLANE –AB–. 7. DIMENSION D DOES NOT INCLUDE DAMBAR
- PROTRUSION. DAMBAR PROTRUSION SHALL NOT CAUSE THE D DIMENSION TO EXCEED
- 0.520 (0.020). 8. MINIMUM SOLDER PLATE THICKNESS SHALL BE
- 0.0076 (0.0003).
  EXACT SHAPE OF EACH CORNER MAY VARY FROM DEPICTION.

		IETERS	INCHES			
DIM	MIN	MAX	MIN	MAX		
Α	7.000	BSC	0.276	BSC		
A1	3.500	BSC	0.138	BSC		
В	7.000	BSC	0.276	BSC		
B1	3.500	BSC	0.138	BSC		
С	1.400	1.600	0.055	0.063		
D	0.300	0.450	0.012	0.018		
Е	1.350	1.450	0.053	0.057		
F	0.300	0.400	0.012	0.016		
G	0.800 BSC		0.031	1 BSC		
Н	0.050	0.150	0.002	0.006		
J	0.090	0.200	0.004	0.008		
K	0.500	0.700	0.020	0.028		
М	12°	REF	12°	12° REF		
Ν	0.090	0.160	0.004	0.006		
Ρ	0.400	BSC	0.016	0.016 BSC		
Q	1°	5°	1°	5°		
R	0.150	0.250	0.006	0.010		
S	9.000	9.000 BSC		0.354 BSC		
S1	4.500 BSC		0.177 BSC			
۷	9.000 BSC		0.354 BSC			
V1	4.500	4.500 BSC		0.177 BSC		
W	0.200	REF	0.008 REF			
Х	1.000	REF	0.039	REF		

Figure 3. 56F8023 32-Pin LQFP Mechanical Information

Please see www.freescale.com for the most current case outline.

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