Automotive Current Mode PWM Control Circuit

The CS2841B provides all the necessary features to implement off-line fixed frequency current-mode control with a minimum number of external components.

The CS2841B (a variation of the CS2843A) is designed specifically for use in automotive operation. The low start threshold voltage of 8.0 V(typ), and the ability to survive 40 V automotive load dump transients are important for automotive subsystem designs. The CS2841 series has a history of quality and reliability in automotive applications.

The CS2841B incorporates a precision temperature–controlled oscillator with an internally trimmed discharge current to minimize variations in frequency. Duty–cycles greater than 50% are also possible. On board logic ensures that V_{REF} is stabilized before the output stage is enabled. Ion implant resistors provide tighter control of undervoltage lockout.

Features

- Optimized for Off-Line Control
- Internally Trimmed Temperature Compensated Oscillator
- Maximum Duty-Cycle Clamp
- V_{REF} Stabilized Before Output Stage Enabled
- Low Start–Up Current
- Pulse–By–Pulse Current Limiting
- Improved Undervoltage Lockout
- Double Pulse Suppression
- 1.0 % Trimmed Bandgap Reference
- High Current Totem Pole Output



ORDERING INFORMATION

Device	Package	Shipping
CS2841BEN8	DIP-8	50 Units/Rail
CS2841BED14	SO-14	55 Units/Rail
CS2841BEDR14	SO-14	2500 Tape & Reel



Figure 1. Block Diagram

MAXIMUM RATINGS*

Ra	Value	Unit	
Supply Voltage (Low Impedance Source)		40	V
Output Current		±1.0	А
Output Energy (Capacitive Load)		5.0	μJ
Analog Inputs (V _{FB} , Sense)		–0.3 to 5.5	V
Error Amp Output Sink Current		10	mA
Lead Temperature Soldering	Wave Solder (through hole styles only) Note 1 Reflow (SMD styles only) Note 2	260 peak 230 peak	°C °C

1. 10 seconds max.

2. 60 seconds max above $183^{\circ}C$

*The maximum package power dissipation must be observed.

ELECTRICAL CHARACTERISTICS	(–40°C \leq T _A \leq 85°C, R _T = 680 k Ω , C _T = 0.022 μ F for Triangular Mode, V _{CC} = 15 V
(Note 3), R_T = 10 k Ω , C_T = 3.3 nF for Sawt	ooth Mode (see Figure 7); unless otherwise specified.)

Characteristic	Test Conditions	Min	Тур	Max	Unit
Reference Section			·	•	
Output Voltage	T _J = 25°C, I _{OUT} = 1.0 mA	4.9	5.0	5.1	V
Line Regulation	$8.4 \le V_{CC} \le 16 \text{ V}$	-	6.0	20	mV
Load Regulation	$1.0 \le I_{OUT} \le 20 \text{ mA}$	-	6.0	25	mV
Temperature Stability	Note 4	_	0.2	0.4	mV/°C
Total Output Variation	Line, Load, Temp. Note 4	4.82	_	5.18	V
Output Noise Voltage	10 Hz \leq f \leq 10 kHz, T _J = 25°C. Note 4	-	50	-	μV
Long Term Stability	T _A = 125°C, 1000 Hrs. Note 4	-	5.0	25	mV
Output Short Circuit	T _A = 25°C	-30	-100	-180	mA
Oscillator Section		-	1	•	
Initial Accuracy	Sawtooth Mode: $T_J = 25^{\circ}C$. See Figure 7. Sawtooth Mode: $-40^{\circ}C \le T_A \le +85^{\circ}C$ Triangular Mode: $T_J = 25^{\circ}C$. See Figure 7.	47 44 44	52 52 52 52	57 60 60	kHz kHz kHz
Voltage Stability	$8.4 \le V_{CC} \le 16 \text{ V}$	-	0.2	1.0	%
Temperature Stability	Sawtooth Mode: $T_{MIN} \le T_A \le T_{MAX}$. Note 4 Triangular Mode: $T_{MIN} \le T_A \le T_{MAX}$. Note 4	-	5.0 8.0	-	% %
Amplitude	V _{OSC} (Peak to Peak)	-	1.7	-	V
Discharge Current	$\begin{array}{l} T_{J} = 25^{\circ}C \\ T_{MIN} \leq T_{A} \leq T_{MAX} \end{array}$	7.4 7.2	8.3 -	9.2 9.4	mA mA
Error Amp Section					
Input Voltage	$V_{COMP} = 2.5 V$	2.42	2.5	2.58	V
Input Bias Current	V _{FB} = 0 V	-	-0.3	-2.0	μA
A _{VOL}	$2.0 \le V_{OUT} \le 4.0 V$	65	90	-	dB
Unity Gain Bandwidth	Note 4	0.7	1.0	-	MHz
PSRR	$8.4 \text{ V} \leq \text{V}_{CC} \leq 16 \text{ V}$	60	70	-	dB
Output Sink Current	V _{FB} = 2.7 V, V _{COMP} = 1.1 V	2.0	6.0	-	mA
Output Source Current	V _{FB} = 2.3 V, V _{COMP} = 5.0 V	-0.5	-0.8	-	mA
V _{OUT} High	V_{FB} = 2.3 V, R_L = 15 k Ω to Ground	5.0	6.0	-	V
V _{OUT} Low	V_{FB} = 2.7 V, R_L = 15 k\Omega to V_{REF}	-	0.7	1.1	V
Current Sense Section		_ .		-	
Gain	Notes 5 and 6	2.85	3.0	3.15	V/V
Maximum Input Signal	V _{COMP} = 5.0 V. Note 5	0.9	1.0	1.1	V
PSRR	$12 \text{ V} \le \text{V}_{CC} \le 25 \text{ V}$. Note 5	-	70	-	dB
Input Bias Current	V _{Sense} = 0 V	-	-2.0	-10	μΑ
Delay to Output	T _J = 25°C. Note 4	_	150	300	ns

3. Adjust V_{CC} above the start threshold before setting at 15 V.

4. These parameters, although guaranteed, are not 100% tested in production.

5. Parameter measured at trip point of latch with V_{FB} = 0.

6. Gain defined as:

$$A = \frac{\Delta V_{COMP}}{\Delta V_{Sense}}; 0 \le V_{Sense} \le 0.8 V.$$

Characteristic	Test Conditions	Min	Тур	Max	Unit
Output Section				•	•
Output Low Level	I _{SINK} = 20 mA I _{SINK} = 200 mA		0.1 1.5	0.4 2.2	V V
Output High Level	I _{SOURCE} = 20 mA I _{SOURCE} = 200 mA	13 12	13.5 13.5		V V
Rise Time	T _J = 25°C, C _L = 1.0 nF. Note 7	-	50	150	ns
Fall Time	T _J = 25°C, C _L = 1.0 nF. Note 7	-	50	150	ns
Output Leakage	Undervoltage Active, V _{OUT} = 0	-	-0.01	-10	μΑ
Total Standby Current		•	•		
Start–Up Current –		-	0.5	1.0	mA
Operating Supply Current I _{CC}	V_{FB} = V_{Sense} = 0 V, R_T = 10 k Ω , C_T = 3.3 nF	-	11	17	mA
Undervoltage Lockout Section			·		
Start Threshold	-	7.6	8.0	8.4	V
Min. Operating Voltage	After Turn On	7.0	7.4	7.8	V

ELECTRICAL CHARACTERISTICS (continued) ($-40^{\circ}C \le T_A \le 85^{\circ}C$, $R_T = 680 \text{ k}\Omega$, $C_T = 0.022 \mu\text{F}$ for Triangular Mode, $V_{CC} = 15 V_{CC} = 15 V_{CC$
(Note 3), $R_T = 10 k\Omega$, $C_T = 3.3 nF$ for Sawtooth Mode (see Figure 7); unless otherwise specified.)

7. These parameters, although guaranteed, are not 100% tested in production.

PACKAGE PIN DESCRIPTION

PACKA	GE PIN #		
DIP-8	SO-14	PIN SYMBOL	FUNCTION
1	1	COMP	Error amp output, used to compensate error amplifier.
2	3	V _{FB}	Error amp inverting input.
3	5	Sense	Noninverting input to Current Sense Comparator.
4	7	OSC	Oscillator timing network with Capacitor to Ground, resistor to V_{REF}
5	8	GND	Ground.
	9	Pwr GND	Output driver Ground.
6	10	V _{OUT}	Output drive pin.
	11	V _{CC} Pwr	Output driver positive supply.
7	12	V _{CC}	Positive power supply.
8	14	V _{REF}	Output of 5.0 V internal reference.
	2, 4, 6, 13	NC	No connection.

TYPICAL PERFORMANCE CHARACTERISTICS



Figure 4. Test Circuit

CIRCUIT DESCRIPTION

Undervoltage Lockout

During Undervoltage Lockout (Figure 5), the output driver is biased to a high impedance state. The output should be shunted to ground with a resistor to prevent output leakage current from activating the power switch.



Figure 5. Typical Undervoltage Characteristics

PWM Waveform

To generate the PWM waveform, the control voltage from the error amplifier is compared to a current sense signal which represents the peak output inductor current (Figure 6). An increase in V_{CC} causes the inductor current slope to increase, thus reducing the duty cycle. This is an inherent feed–forward characteristic of current mode control, since the control voltage does not have to change during changes of input supply voltage.





When the power supply sees a sudden large output current increase, the control voltage will increase allowing the duty cycle to momentarily increase. Since the duty cycle tends to exceed the maximum allowed to prevent transformer saturation in some power supplies, the internal oscillator waveform provides the maximum duty cycle clamp as programmed by the selection of OSC components.



Timing Parameters







Figure 7. Oscillator Timing Network and Parameters

Setting the Oscillator

Oscillator timing capacitor, C_T , is charged by V_{REF} through R_T and discharged by an internal current source. During the discharge time, the internal clock signal blanks out the output to the Low state, thus providing a user selected maximum duty cycle clamp. Charge and discharge times are determined by the general formulas:

$$t_{C} = R_{T}C_{T} ln \left(\frac{V_{REF} - V_{lower}}{V_{REF} - V_{upper}} \right)$$

$$t_{d} = R_{T}C_{T} ln \left(\frac{V_{REF} - I_{d}R_{T} - V_{lower}}{V_{REF} - I_{d}R_{T} - V_{upper}} \right)$$

Substituting in typical values for the parameters in the above formulas:

 $\begin{array}{l} \mathsf{V}_{\mathsf{REF}} = 5.0 \ \mathsf{V} \\ \mathsf{V}_{\mathsf{upper}} = 2.7 \ \mathsf{V} \\ \mathsf{V}_{\mathsf{lower}} = 1.0 \ \mathsf{V} \\ \mathsf{I}_{\mathsf{d}} = 8.3 \ \mathsf{mA} \\ \mathsf{t}_{\mathsf{c}} \approx 0.5534 \mathsf{R}_{\mathsf{T}}\mathsf{C}_{\mathsf{T}} \end{array}$

The frequency and maximum duty cycle can be determined from the Typical Performance Characteristic graphs.

Grounding

High peak currents associated with capacitive loads necessitate careful grounding techniques. Timing and bypass capacitors should be connected close to GND pin in a single point ground.

The transistor and 5.0 k Ω potentiometer are used to sample the oscillator waveform and apply an adjustable ramp to Sense.



Figure 8. Flyback Application



Figure 9. Boost Application

PACKAGE THERMAL DATA

Paramo	eter	DIP-8	SO-14	Unit
R _{ØJC}	Typical	52	30	°C/W
R _{OJA}	Typical	100	125	°C/W