# **CXD2312R**

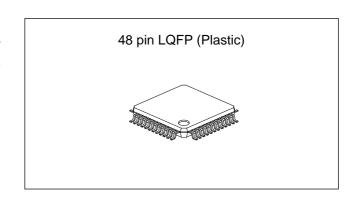
# 9-bit 20MSPS Video A/D Converter

## **Description**

The CXD2312R is a 9-bit CMOS A/D converter for video applications. This IC is ideally suited for the A/D conversion of video signals in TVs, VCRs, camcorders, etc.

#### **Features**

- Resolution: 9-bit ±0.5 LSB (D.L.E.)
- Maximum sampling frequency: 20MSPS
- Low power consumption: 130mW (at 20MSPS typ.)
   (Not including reference current)
- TTL compatible input
- Tri-state TTL compatible output (DVpp = 3.3V)
- · Low input capacitance
- Reference impedance: 300Ω (typ.)



#### **Structure**

Silicon gate CMOS IC

## **Absolute Maximum Ratings** (Ta = 25°C)

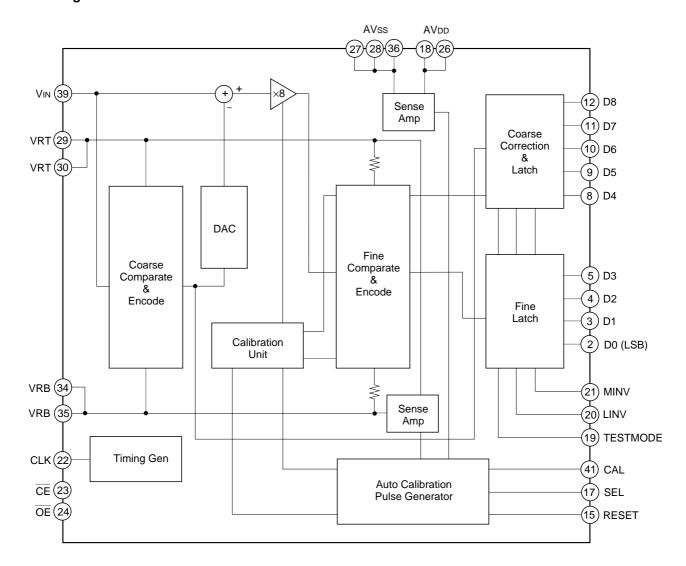
<ul> <li>Supply voltage</li> </ul>	Vdd	7	V
<ul> <li>Reference voltage</li> </ul>	VRT, VRB	$V_{DD} + 0.5 \text{ to } V_{SS} - 0.5$	V
<ul> <li>Input voltage (analog)</li> </ul>	VIN	$V_{DD} + 0.5 \text{ to } V_{SS} - 0.5$	V
<ul> <li>Input voltage (digital)</li> </ul>	VIH, VIL	$V_{DD} + 0.5 \text{ to } V_{SS} - 0.5$	V
<ul> <li>Output voltage (digital)</li> </ul>	Voн, Vol	$V_{DD} + 0.5 \text{ to } V_{SS} - 0.5$	V
Storage temperature	Tstg	-55 to +150	°C

#### **Recommended Operating Conditions**

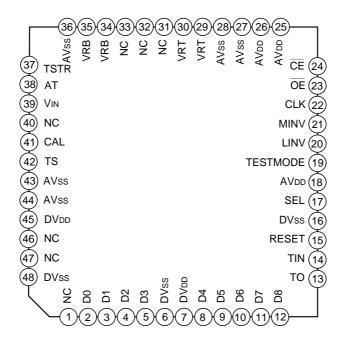
<ul> <li>Supply voltage</li> </ul>	AVDD, AVSS	$5.0 \pm 0.25$	V
	DV <sub>DD</sub> , DVss	3.0 to 5.25	V
	DVss – AVss	0 to 100	mV
Reference input voltage	VRB	More than 1.8	V
	VRT	to AVDD - 0.4	V
<ul> <li>Analog input</li> </ul>	VIN	More than 1.8Vp-p	
<ul> <li>Clock pulse width</li> </ul>	Tpw1	25 (min.)	ns
	T <sub>P</sub> w0	25 (min.)	ns
Operating ambient temper	rature		
	Topr	-20  to  + 75	°C

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#### **Block Diagram**



## **Pin Configuration**



## **Pin Description**

Pin Descript	Symbol	Equivalent circuit	Description
2 to 5 8 to 12	D0 to D8	DVod DVss 777	D0 (LSB) to D8 (MSB) output.
13	то	<u>'</u>	Test pin. TS = High: High impedance state
7, 45	DV <sub>DD</sub>		Digital VDD.
6, 16, 48	DVss		Digital Vss.
27, 28, 36, 43, 44	AVss		Analog Vss.
17	SEL	AVDD W AVSS	Calibration input pulse select after completion of the startup calibration. High: Internal pulse generation Low: External input
22	CLK	AVDD W AVSS	Clock pin.
41	CAL	AVDD W	Calibration pulse input.
15	RESET	AVDD W	Calibration circuit reset and startup calibration restart.

Pin No.	Symbol	Equivalent circuit	Description
14	TIN		Test signal input. Normally fixed to AVDD or AVss.
29, 30	VRT	AVDD AVSS AVSS	Reference top.
34, 35	VRB	34 35	Reference bottom.
38	AT		Test signal output. TS = High: High impedance state
42	TS		Test signal input. Normally fixed to AVDD.
37	TSTR		Test signal input. Normally fixed to AVss.
23	ŌĒ	AVDD AVSS AVSS	D0 to D8 output enable. Low: Output state High: High impedance state
24	CE	AVDD W > AVSS AVSS	Chip enable. Low: Active state High: Standby state

Pin No.	Symbol	Equivalent circuit	Description
19	TESTMODE	AVDD W > AVSS	Test mode. High: Output state Low: Output fixed
20	LINV	AVDD W > AVSS	Output inversion. High: D0 to D7 are inverted and output.
21	MINV	AVDD W > -	Output inversion. High: D8 is inverted and output.
18, 25, 26	AVDD		Analog VDD.
39	Vin	AVDD AVSS AVSS	Analog input.

## **Digital Output**

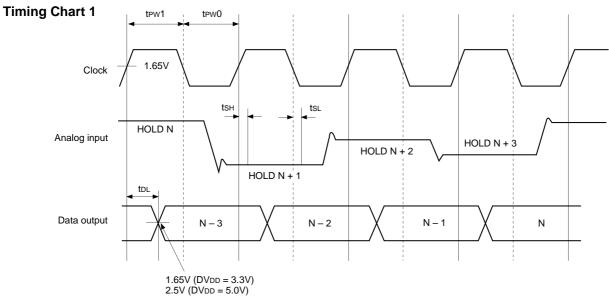
The following table shows the correlation between the analog input voltage and the digital output code (TESTMODE = 1, LINV, MINV = 0)

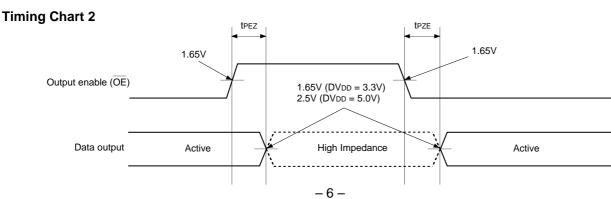
Input signal voltage	Step	Digital output code MSB	LSB
VRT	0	1111111	1
	255 256	1 0 0 0 0 0 0 0 0 0 0 1 1 1 1 1 1 1	0
VRB	511	00000000	0

The following table shows the output state for the combination of TESTMODE, LINV, and MINV states.

TESTMODE	LINV	MINV	D0	D1	D2	D3	D4	D5	D6	D7	D8
1	0	0	Р	Р	Р	Р	Р	Р	Р	Р	Р
1	1	0	N	N	N	N	N	Ν	N	Ν	Р
1	0	1	Р	Р	Р	Р	Р	Р	Р	Р	N
1	1	1	N	N	N	N	N	Ν	N	Ν	N
0	0	0	0	1	0	1	0	1	0	1	0
0	1	0	1	0	1	0	1	0	1	0	0
0	0	1	0	1	0	1	0	1	0	1	1
0	1	1	1	0	1	0	1	0	1	0	1

P: Forward-phase output N: Inverted output



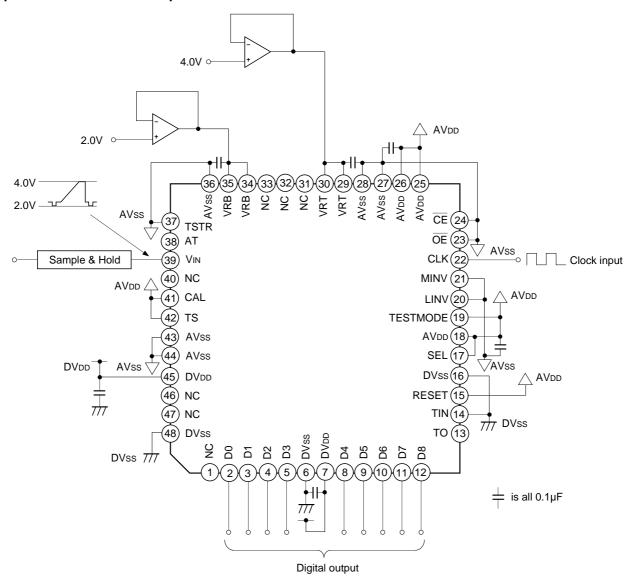


# Electrical Characteristics (Fc = 20MSPS, AVDD = 5V, DVDD = 3.3V, VRB = 2.0V, VRT = 4.0V, Ta = <math>25°C)

Item	Symbol	Co	onditions	Min.	Тур.	Max.	Unit
Max. conversion rate	Fc max	Fin = 1.0kHz		20			MCDC
Min. conversion rate	Fc min	triangular wave input				0.5	MSPS
Supply Analog	IAdd	Fin = 1.0kHz triangular wave input		21	24	28	
current Digital	ID <sub>DD</sub>			1.6	1.7	1.8	mA
Standby Analog	IAst	CE = High				1.0	1
current Digital	IDst					1.0	μΑ
Defense sin summer	IRT			5.0	7.5	10.0	^
Reference pin current	IRB			3.0	5.5	8.0	- mA
Analog input band	BW	-1dB			35		MHz
Analog input capacitance	CIN				10		pF
Reference resistance value (VRT – VRB)	RREF			210	300	390	Ω
Offset voltage	Еот	Eot = theore	etical value-actual alue	-30	8.0	30	- mV
Onset voltage	Еов	EOB = actual measured value- theoretical value		-30	12 30 m		IIIV
Startup calibration start	Vcal1	AVDD-AVSS			2.5		V
voltage	Vcal2	VRT – VRB			1.0		]
Digital input voltage	ViH	AVDD = 4.75V to 5.25V		2.3			│ <sub>∨</sub>
VIL		71188 = 1.761 to 6.261				0.8	٧
Analog input current	Аін	VIN = 4V				20	μA
Analog input current	AıL	Vin = 2V	VIN = 2V				μΛ
Digital input current	Iн	DV <sub>DD</sub> = max VIH = DV <sub>DD</sub>				5	μΑ
Digital input ourront	lı∟	B v bb = max	VIL = 0V			5	μ, τ
Digital output current	Іон	OE = AVss	VOH = DVDD - 0.5V	4.0			mA
Digital output current	lol	DVDD = min	V 011 = 0.1V	3.5			III/
Digital output current	Іохн	$\overline{OE} = AVDD$	Voh = DVdd			1	μA
Digital output outroit	lozl	DV <sub>DD</sub> = max	Vol = 0V			1	μΛ
Tri-state output disable tim	e t <sub>PEZ</sub>	Clock not synchronized for active → high impedance		20	25	30	ns
Tri-state output enable time	e <b>t</b> PZE	Clock not synchronized for high impedance → active		10	15	20	ns
Integral non-linearity error	EL				±0.5	±1.0	LCD
Differential non-linearity erro	or Ed				±0.3	±0.5	LSB
Differential gain error	DG	NTSC 40 IRE mod			1.0		%
Differential phase error	DP	ramp, Fc = 14.3MSPS			0.3		deg
Output data delay	<b>t</b> DL	CL = 20pF		8	13	18	ns
Sampling delay	<b>t</b> sH			0	6		ns
Camping delay	<b>t</b> sL				2	4	115

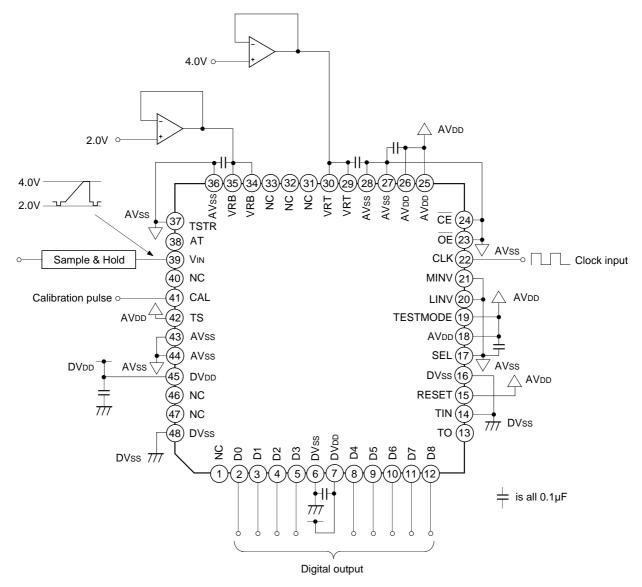
Item	Symbol	Conditions	Min.	Тур.	Max.	Unit
		Fin = 100kHz		53		
		Fin = 500kHz		53		
SNR	SNR	Fin = 1MHz		53		dB
SIVIC	Ortic	Fin = 3MHz		51		ub
		Fin = 7MHz		51		
		Fin = 10MHz		49		
		Fin = 100kHz		68		
		Fin = 500kHz		66		
SFDR	SFDR	Fin = 1MHz		66		dB
SI BIX		Fin = 3MHz		62		ub
		Fin = 7MHz		56		
		Fin = 10MHz		51		

## Application Circuit 1. Startup calibration + internal auto calibration



Application circuits shown are typical examples illustrating the operation of the devices. Sony cannot assume responsibility for any problems arising out of the use of these circuits or for any infringement of third party patent and other right due to same.

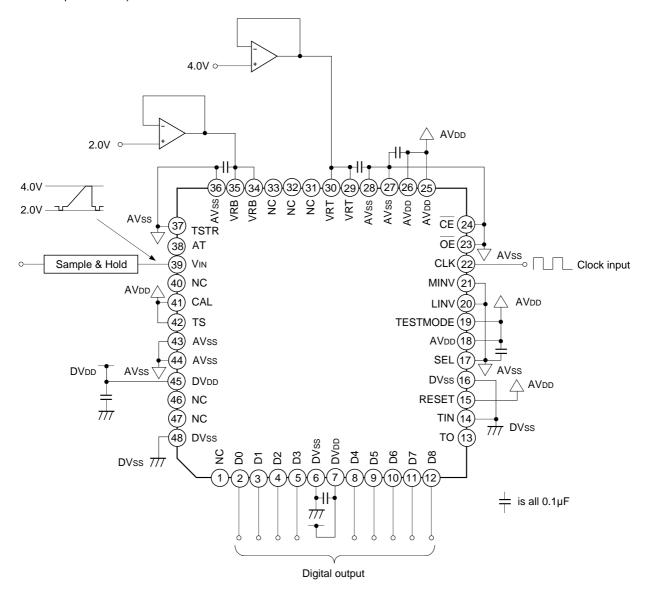
## Application Circuit 2. Startup calibration + external sync calibration



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## Application Circuit 3. Only startup calibration

(Less than supply voltage fluctuation range of  $AVDD = \pm 100 \text{mV}$  and reference voltage fluctuation range of |VRT - VRB| = 200 mV)



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#### 1. Calibration Function

In order to achieve superior linearity, the CXD2312R has a built-in calibration circuit and a calibration pulse auto generation circuit which is used to execute a calibration circuit. Fig. 1 shows a block diagram of the calibration pulse generation circuit.

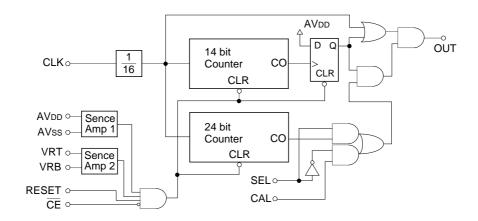
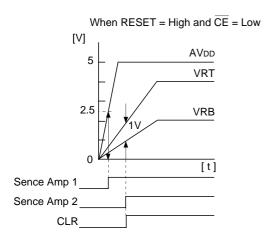


Fig. 1. Calibration Pulse Generation Circuit

### (1) Startup Calibration Function

Over 600 calibration pulses are needed to complete the initial calibration process when the power is first supplied to the IC. The startup calibration function automatically generates these pulses internally and completes the initial calibration process.

The following five conditions must be satisfied to initiate the startup calibration function.



- a) The voltage between AV<sub>DD</sub> and AVss is approximately 2.5V or more.
- b) The voltage between VRT and VRB is approximately 1V or more.
- c) The RESET pin (Pin 15) must is high.
- d) The CE pin (Pin 24) must is low.
- e) Condition b is met after condition a.

Once all five of these conditions have been met, the calibration pulses are generated. The pulses are generated by counting 16 main clock cycles on a 14-bit counter and closing the gate when the carry-out occurs. Therefore, the time required for startup calibration after the above five conditions have been met is determined by the following formula:

Startup calibration time = main clock cycle  $\times$  16  $\times$  16,384

For example, if the main clock frequency is 14.3MHz, the time required for startup calibration is 18ms.

#### (2) Auto Calibration Pulse Generation Function

After startup calibration is completed, this function periodically generates calibration pulses so that calibration can be performed constantly without any need for input of calibration pulses from an external source. This function counts 16 main clock cycles on a 24-bit counter and uses the carry-out as the calibration pulse. The cycle of the calibration pulse generated in this fashion is as follows:

Internal calibration pulse generation cycle = main clock cycle  $\times$  16  $\times$  16,777,216

Therefore, if the main clock frequency is 14.3MHz, the calibration pulse cycle is approximately 19 seconds; since calibration is performed once every seven pulses, the calibration cycle is approximately 130 seconds. In order to use this function, the SEL pin (Pin 17) must be high.

Note that this function cannot be used if fixing the lower bits in the calibration operation as described below will cause problems because this function is executed asynchronously without regard to the input signals.

#### (3) External Calibration Pulse Input Function

If the auto calibration function cannot be used, calibration can be performed in synchronization with the input signals when a calibration pulse is input from the CAL pin (Pin 41) by setting the SEL pin (Pin 17) low.

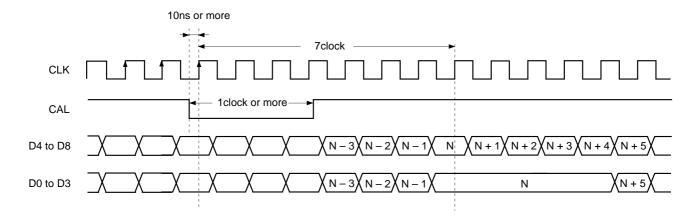
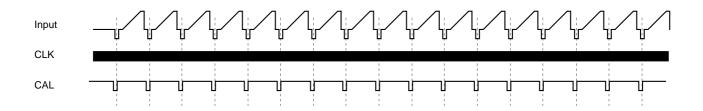


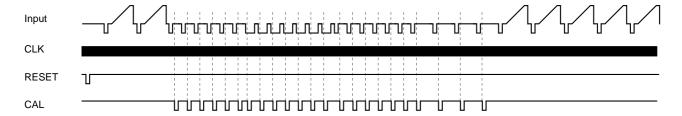
Fig. 2. Calibration Timing Chart

Calibration starts when the falling edge of the pulse input to the CAL pin (Pin 41) is detected. Because the lower comparator is occupied for four clock cycles at this point, the previous lower data is held for four clock cycles after seven clock cycles since the rising edge of the clock cycle in which the falling edge of CAL was detected. Calibration can be performed outside of video intervals by using the sync signal, etc., to input the CAL signal. An example of this is shown below.

#### (1) Inputting CAL every H-sync



## (2) Inputting CAL every V-sync



It is also possible to use only the startup calibration function by leaving the SEL pin (Pin 17) low and fixing the CAL pin (Pin 41) either high or low. Note that this method requires restriction of the fluctuation range of the supply voltage and the reference voltage.

## (4) Re-initiating the Startup Calibration Function

The startup calibration function can be re-initiated after the power and reference voltage are supplied by using the CE pin (Pin 24) and the RESET pin (Pin 15). Particularly in cases where the riseup characteristics of the power supply and the reference voltage are unstable, it is possible to initiate startup calibration properly by connecting a CR and delaying startup until after power supply riseup.

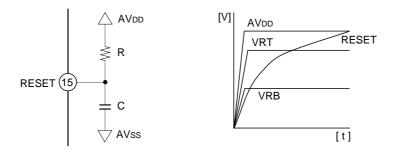


Fig. 3. Initiation of the Startup Calibration Function Using the RESET pin

#### 2. Power supply

To prevent the influence of noise, connect the power supply to a 0.1µF by-pass capacitor as near the device as possible.

#### 3. DVDD

Either a 3.3V or 5.0V digital power supply can be used. Compared to the 5.0V power supply, the 3.3V power supply generates a decreased amount of radiation noise but offers a decreased drive capacity. These two power supplies do not virtually differ in static and dynamic characteristics. Further, the High output level rises up to DVpp.

#### 4. Reference input

The voltage to be supplied to the reference pins must be driven by a buffer having a 10mA or more drive capacity. For supplied voltage stabilization, connect the buffer to a 0.1µF by-pass capacitor as near the pins as possible.

#### 5. Latch-up

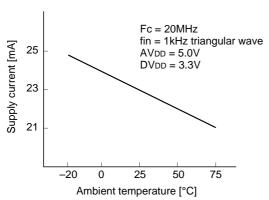
Ensure that the AVDD and DVDD pins share the same power supply on a board to prevent latch-up which may be caused by power ON time-lag.

#### 6. Board

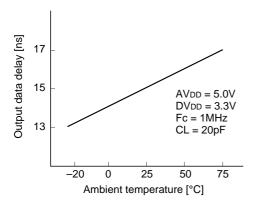
To obtain full-expected performance from this IC, be sure that the mounting board has a large ground pattern for lower impedance. It is recommended that the IC be mounted on a board without using a socket to evaluate its characteristics adequately.

#### **Example of Representative Characteristics**

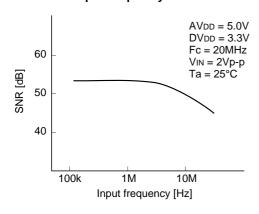
## Supply current vs. Ambient temperature



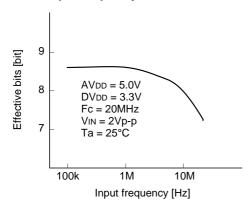
#### Output data delay vs Ambient temperature



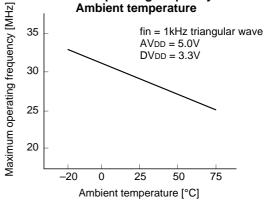
Input frequency vs. SNR



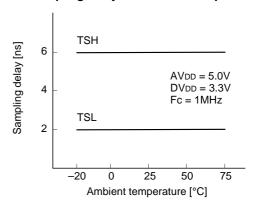
Input frequency vs. Effective bits



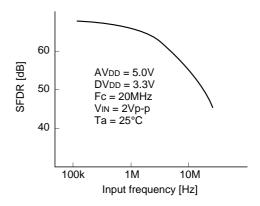
Maximum operating frequency vs. **Ambient temperature** 



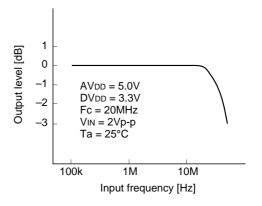
#### Sampling delay vs. Ambient temperature



Input frequency vs. SFDR

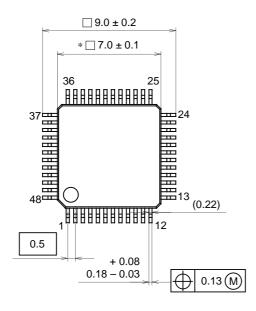


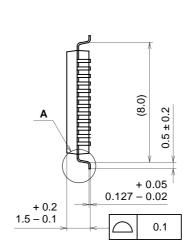
Input band

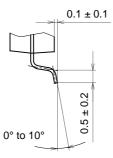


## Package Outline Unit: mm

# 48PIN LQFP (PLASTIC)







NOTE: Dimension "\*" does not include mold protrusion.

DETAIL A

SONY CODE	LQFP-48P-L01
EIAJ CODE	LQFP048-P-0707
JEDEC CODE	

## PACKAGE STRUCTURE

PACKAGE MATERIAL	EPOXY RESIN
LEAD TREATMENT	SOLDER/PALLADIUM PLATING
LEAD MATERIAL	42/COPPER ALLOY
PACKAGE MASS	0.2g