CY54/74FCT2646T
CY54/74FCT2648T

8-Bit Registered Transceivers

Features

- **Function and pinout compatible with FCT and F logic**
- **FCT-C speed at 5.4 ns max. (Com'l) FCT-A speed at 6.3 ns max. (Com'l)**
- **Reduced V_{OH} (typically = 3.3V) versions of equivalent FCT functions**
- **25Ω output series resistors to reduce transmission line reflection noise**
- **Reduced V_{OH} (typically=3.3V) versions of equivalent FCT functions**
- **Edge-rate control circuitry for significantly improved noise characteristics**
- **Power-off disable feature**
- **Matched rise and fall times**
- **ESD > 2000V**
- **Fully compatible with TTL input and output logic levels**
- **Sink current** **12 mA (Com'l), 12 mA (Mil)**
  Source current **15 mA (Com'l), 12 mA (Mil)**
- **Independent register for A and B buses**
- **Three-state output**

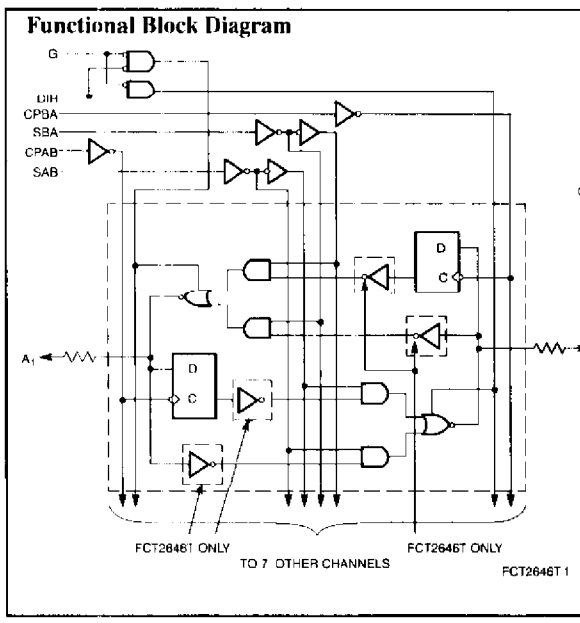
Functional Description

The FCT2646T and FCT2648T consist of a bus transceiver circuit with three-state, D-type flip-flops, and control circuitry arranged for multiplexed transmission of data directly from the input bus or from the internal registers. Data on the A or B bus will be clocked into the registers as the appropriate clock pin goes to a HIGH logic level. Enable Control $\overline{G}$ and direction pins are provided to control the transceiver function. On-chip termination resistors have been added to the outputs to reduce system noise caused by reflections so that the FCT2646T and the FCT2648T can be used to replace the FCT646T and the FCT648T, respectively, in an existing design.

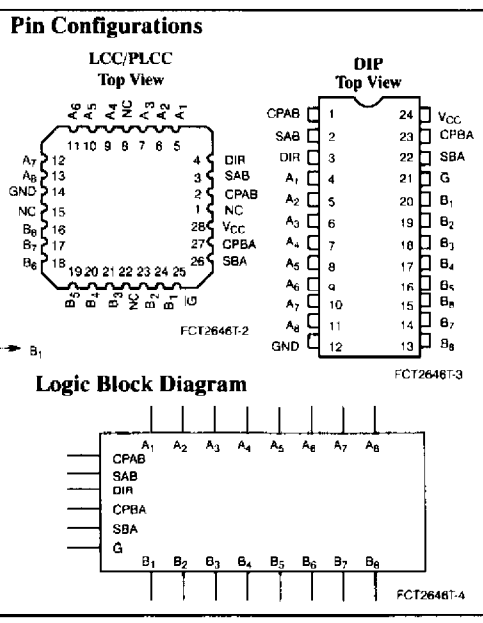
In the transceiver mode, data present at the high impedance port may be stored in either the A or B register, or in both. Select controls can multiplex stored and real-time (transparent mode) data. The direction control determines which bus will receive data when the enable control $\overline{G}$ is Active LOW. In the isolation mode (enable control $\overline{G}$ HIGH), A data may be stored in the B register and/or B data may be stored in the A register.

The outputs are designed with a power-off disable feature to allow for live insertion of boards.

Functional Block Diagram



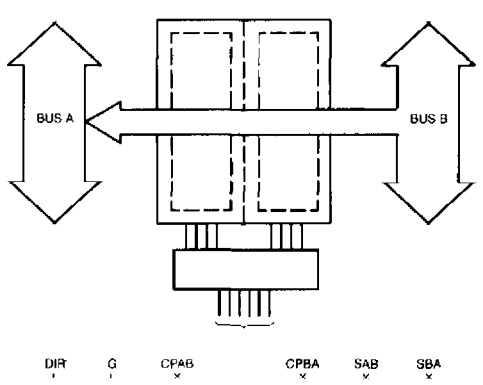
Pin Configurations



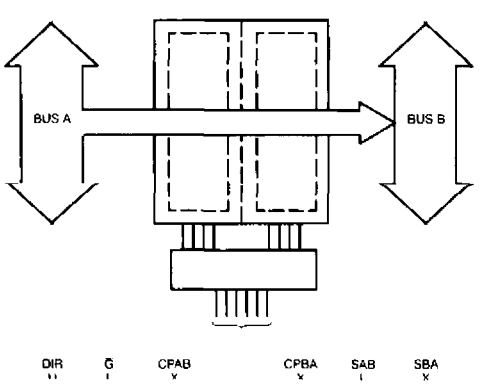
Logic Block Diagram

Pin Description

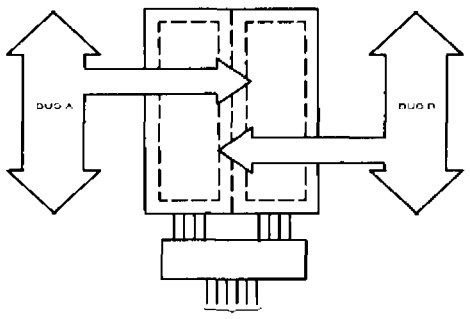
Name	Description
A	Data Register A Inputs, Data Register B Outputs
B	Data Register B Inputs, Data Register A Outputs
CPAB, CPBA	Clock Pulse Inputs
SAB, SBA	Output Data Source Select Inputs
DIR, $\overline{G}$	Output Enable Inputs



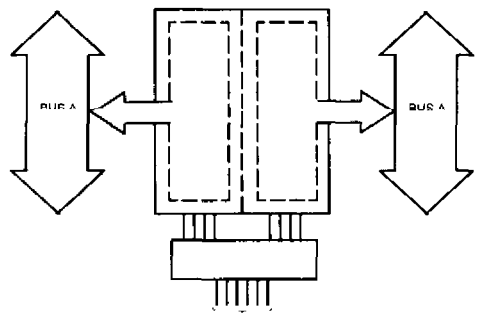
Real-Time Transfer
Bus B to Bus A



Real-Time Transfer
Bus A to Bus B



Storage from
A and/or B



Transfer Stored Data
to A and/or B

9

Function Table[2]

Inputs						Data I/O[3]		Operation or Function	
$\overline{G}$	DIR	CPAB	CPBA	SAB	SBA	A_1 thru A_8	B_1 thru B_8	FCT2646T	FCT2648T
H	X	H or L	H or L	X	X	Input	Input	Isolation	Isolation
H	X	⌐	⌐	X	X			Store A and B Data	Store A and B Data
L	L	X	X	X	L	Output	Input	Real Time B Data to A Bus	Real Time $\overline{B}$ Data to A Bus
L	L	X	H or L	X	H			Stored B Data to A Bus	Stored $\overline{B}$ Data to A Bus
L	H	X	X	L	X	Input	Output	Real Time A Data to B Bus	Real Time $\overline{A}$ Data to B Bus
L	H	H or L	X	H	X			Stored A Data to B Bus	Stored $\overline{A}$ Data to B Bus

Notes:
1. Cannot transfer data to A bus and B bus simultaneously.
2. H = HIGH Voltage Level, L = LOW Voltage Level, X = Don't Care.
3. The data output functions may be enabled or disabled by various signals at the G or DIR inputs. Data input functions are always enabled, i.e., data at the bus pins will be stored on every LOW-to-HIGH transition of the clock inputs.

Power Supply Characteristics

Parameter	Description	Test Conditions	Typ.[7]	Max.	Unit
I_{CC}	Quiescent Power Supply Current	V_{CC}=Max., $V_{IN} \le 0.2V$, $V_{IN} \ge V_{CC}-0.2V$	0.1	0.2	mA
ΔI_{CC}	Quiescent Power Supply Current (TTL inputs HIGH)	V_{CC}=Max., V_{IN}=3.4V[10], f_1=0, Outputs Open	0.5	2.0	mA
I_{CCD}	Dynamic Power Supply Current[11]	V_{CC}=Max., One Input Toggling, 50% Duty Cycle, Outputs Open, $\overline{G}$=DIR=GND, GAB=$\overline{GBA}$=GND, $V_{IN} \le 0.2V$ or $V_{IN} \ge V_{CC}-0.2V$	0.06	0.12	mA/ MHz
I_C	Total Power Supply Current[12]	V_{CC}=Max., f_0=10 MHz, 50% Duty Cycle, Outputs Open, One Bit Toggling at f_1=5 MHz, $\overline{G}$=DIR=GND, GAB=$\overline{GBA}$=GND, $V_{IN} \le 0.2V$ or $V_{IN} \ge V_{CC}-0.2V$	0.7	1.4	mA
		V_{CC}=Max., f_0=10 MHz, 50% Duty Cycle, Outputs Open, One Bit Toggling at f_1=5 MHz, $\overline{G}$=DIR=GND, GAB=$\overline{GBA}$=GND, V_{IN}=3.4V or V_{IN}=GND	1.2	3.4	mA
		V_{CC}=Max., f_0=10 MHz, 50% Duty Cycle, Outputs Open, Eight Bits Toggling at f_1=5 MHz, $\overline{G}$=DIR=GND, GAB=$\overline{GBA}$=GND, $V_{IN} \le 0.2V$ or $V_{IN} \ge V_{CC}-0.2V$	2.8	5.6[13]	mA
		V_{CC}=Max., f_0=10 MHz, 50% Duty Cycle, Outputs Open, Eight Bits Toggling at f_1=5 MHz, $\overline{G}$=DIR=GND, GAB=$\overline{GBA}$=GND, V_{IN}=3.4V or V_{IN}=GND	5.1	14.6[13]	mA

Notes:

10. Per TTL driven input (V_{IN}=3.4V); all other inputs at V_{CC} or GND.
11. This parameter is not directly testable, but is derived for use in Total Power Supply calculations.
12. $I_C = I_{QUIESCENT} + I_{INPUTS} + I_{DYNAMIC}$
    $I_C = I_{CC} + \Delta I_{CC} D_H N_T + I_{CCD}(f_0/2 + f_1 N_1)$
    I_{CC} = Quiescent Current with CMOS input levels
    ΔI_{CC} = Power Supply Current for a TTL HIGH input (V_{IN}=3.4V)
    D_H = Duty Cycle for TTL inputs HIGH
    N_T = Number of TTL inputs at D_H
    I_{CCD} = Dynamic Current caused by an input transition pair (HLH or LHL)
    f_0 = Clock frequency for registered devices, otherwise zero
    f_1 = Input signal frequency
    N_1 = Number of inputs changing at f_1
    All currents are in milliamps and all frequencies are in megahertz.
13. Values for these conditions are examples of the I_{CC} formula. These limits are guaranteed but not tested.

g

Switching Characteristics Over the Operating Range

Parameter	Description	FCT2646T/FCT2648T				FCT2646AT/FCT2648AT				Unit	Fig. No.[15]
		Military		Commercial		Military		Commercial			
		Min.[14]	Max.	Min.[14]	Max.	Min.[14]	Max.	Min.[14]	Max.		
t_{PLH} t_{PHL}	Propagation Delay Bus to Bus	1.5	11.0	1.5	9.0	1.5	7.7	1.5	6.3	ns	1, 3
t_{PZH} t_{PZL}	Output Enable Time Enable to Bus and DIR to A_n or B_n	1.5	15.0	1.5	14.5	1.5	10.5	1.5	9.8	ns	1, 7, 8
t_{PHZ} t_{PLZ}	Output Disable Time $\overline{G}$ to Bus and DIR to Bus	1.5	11.0	1.5	9.0	1.5	7.7	1.5	6.3	ns	1, 7, 8
t_{PLH} t_{PHL}	Propagation Delay Clock to Bus	1.5	10.0	1.5	9.0	1.5	7.0	1.5	6.3	ns	1, 5
t_{PLH} t_{PHL}	Propagation Delay SBA or SAB to A or B	1.5	12.0	1.5	11.0	1.5	8.4	1.5	7.7	ns	1, 5
t_S	Set-Up Time HIGH or LOW, Bus to Clock	4.5		4.0		2.0		2.0		ns	4
t_H	Hold Time HIGH or LOW, Bus to Clock	2.0		2.0		1.5		1.5		ns	4
t_W	Pulse Width,[6] HIGH or LOW	6.0		6.0		5.0		5.0		ns	5

Parameter	Description	FCT2646CT/FCT2648CT				Unit	Fig. No.[15]
		Military		Commercial			
		Min.[14]	Max.	Min.[14]	Max.		
t_{PLH} t_{PHL}	Propagation Delay Bus to Bus	1.5	6.0	1.5	5.4	ns	1, 3
t_{PZH} t_{PZL}	Output Enable Time Enable to Bus and DIR to A_n or B_n	1.5	8.9	1.5	7.8	ns	1, 7, 8
t_{PHZ} t_{PLZ}	Output Disable Time $\overline{G}$ to Bus and DIR to Bus	1.5	7.7	1.5	6.3	ns	1, 7, 8
t_{PLH} t_{PHL}	Propagation Delay Clock to Bus	1.5	6.3	1.5	5.2	ns	1, 5
t_{PLH} t_{PHL}	Propagation Delay SBA or SAB to A or B	1.5	7.0	1.5	6.2	ns	1, 5
t_S	Set-Up Time HIGH or LOW, Bus to Clock	2.0		2.0		ns	4
t_H	Hold Time HIGH or LOW, Bus to Clock	1.5		1.5		ns	4
t_W	Pulse Width,[6] HIGH or LOW	5.0		5.0		ns	5

Notes:
14. Minimum limits are guaranteed but not tested on Propagation Delays.
15. See "Parameter Measurement Information" in the General Information Section.