



# 14-Bit, Dual, Parallel Input, Multiplying Digital-to-Analog Converter

#### **FEATURES**

• ±0.5LSB DNL

±0.5LSB INL

Low Noise: 12nV/√Hz

• Low Power:  $I_{DD} = 1\mu A$  per channel at 2.7V

• 2mA Full-Scale Current, with V<sub>REF</sub> = 10V

Settling Time: 0.5μs
 14-Bit Monotonic

4-Quadrant Multiplying Reference Inputs

Reference Bandwidth: 10MHz

Reference Input: ±18V

Reference Dynamics: –105 THD
 Midscale or Zero Scale Reset

Analog Power Supply: +2.7V to +5.5V

• TSSOP-38 Package

• Industry-Standard Pin Configuration

Pin Compatible with the 16-Bit DAC8822

Temperature Range: –40°C to +125°C

### **APPLICATIONS**

Automatic Test Equipment

- Instrumentation
- Digitally Controlled Calibration
- Industrial Control PLCs

#### **DESCRIPTION**

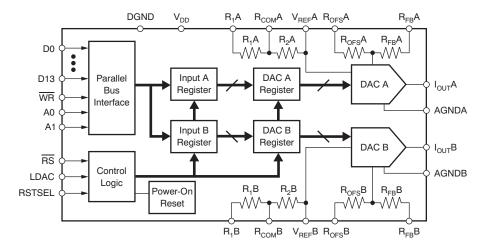
The DAC8805 dual, multiplying digital-to-analog converter (DAC) is designed to operate from a single 2.7V to 5.5V supply.

The applied external reference input voltage  $V_{REF}$  determines the full-scale output current. An internal feedback resistor ( $R_{FB}$ ) provides temperature tracking for the full-scale output when combined with an external, current-to-voltage (I/V) precision amplifier.

A RSTSEL pin allows system reset assertion ( $\overline{RS}$ ) to force all registers to zero code when RSTSEL = '0', or to mid-scale code when RSTSEL = '1'. Additionally, an internal power-on reset forces all registers to zero or mid-scale code at power-up, depending on the state of the RSTSEL pin.

A parallel interface offers high-speed communications. The DAC8805 is packaged in a space-saving TSSOP-38 package and has an industry-standard pinout. The device is specified from –40°C to +125°C.

For a 16-bit, pin-compatible version, see the DAC8822.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

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#### SBAS391A-DECEMBER 2006-REVISED MAY 2007





This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### ORDERING INFORMATION(1)

PRODUCT	RELATIVE ACCURACY (LSB)	DIFFERENTIAL NONLINEARITY (LSB)	PACKAGE-LEAD (DESIGNATOR)	SPECIFIED TEMPERATURE RANGE	PACKAGE MARKING
DAC8805Q	±1	±1	TSSOP-38 (DBT)	-40°C to +125°C	DAC8805

<sup>(1)</sup> For the most current package and ordering information see the Package Option Addendum at the end of this document, or see the TI web site at www.ti.com.

#### **ABSOLUTE MAXIMUM RATINGS**

over operating free-air temperature range (unless otherwise noted) (1)

		DAC8805	UNIT
V <sub>DD</sub> to GND		-0.3 to +7	V
Digital input vo	Itage to GND	-0.3 to +V <sub>DD</sub> + 0.3	V
V (I <sub>OUT</sub> ) to GN	D	-0.3 to +V <sub>DD</sub> + 0.3	V
REF, R <sub>OFS</sub> , R <sub>F</sub>	<sub>B</sub> , R <sub>1</sub> , R <sub>COM</sub> to AGND, DGND	±25	V
Operating temp	perature range	-40 to +125	°C
Storage tempe	rature range	-65 to +150	°C
Junction temper	erature range (T <sub>J</sub> max)	+150	°C
Power dissipat	ion	$(T_J max - T_A) / R_{\theta JA}$	W
Thermal imped	lance, R <sub>eJA</sub>	53	°C/W
CCD roting	Human Body Model (HBM)	4000	V
ESD rating	Charged Device Model (CDM)	500	V

<sup>(1)</sup> Stresses above those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. Exposure to absolute maximum conditions for extended periods may affect device reliability.



## **ELECTRICAL CHARACTERISTICS**

All specifications at  $T_A = -40$ °C to +125°C,  $V_{DD} = +2.7$ V to +5.5V,  $I_{OUT} = virtual$  GND, GND = 0V, and  $V_{REF} = 10$ V, unless otherwise noted.

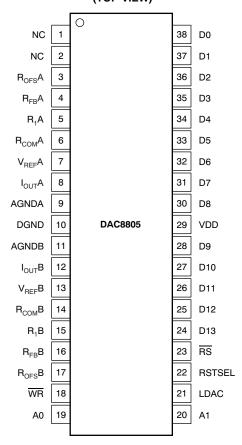
DADAMETER				DAC8805			
PARAMETER		CONDITIONS	MIN	TYP MAX		UNITS	
STATIC PERFORMANCE							
Resolution			14			Bits	
Relative accuracy	INL			±0.5	±1	LSB	
Differential nonlinearity	DNL			±0.5	±1	LSB	
Output leakage current		Data = 0000h, T <sub>A</sub> = +25°C			10	nA	
Output leakage current		Data = 0000h, Full temperature range			20	nA	
- ·		Unipolar, data = 3FFFh		±1	±4	mV	
Full-scale gain error		Bipolar, data = 3FFFh		±1	±4	mV	
Full-scale temperature coefficient				±1	±2	ppm/°C	
D' I		T <sub>A</sub> = +25°C		±1	±3	mV	
Bipolar zero error		Full temperature range		±1	±3	mV	
Power-supply rejection ratio	PSRR	V <sub>DD</sub> = 5V ±10%		±0.1	±0.5	LSB/V	
OUTPUT CHARACTERISTICS(1)							
Output current				2		mA	
Output capacitance		Code dependent		50		pF	
REFERENCE INPUT							
Reference voltage range	$V_{REF}$		-18		18	V	
Input resistance (unipolar)	R <sub>REF</sub>		4	5	6	kΩ	
Input capacitance				5		pF	
R <sub>1</sub> , R <sub>2</sub>			4	5	6	kΩ	
Feedback and offset resistance	R <sub>OFS</sub> , R <sub>FB</sub>		8	10	12	kΩ	
LOGIC INPUTS AND OUTPUT(1)							
	V <sub>IL</sub>	$V_{DD} = +2.7V$			0.6	V	
Input low voltage	V <sub>IL</sub>				0.8	V	
		V <sub>DD</sub> = +2.7V	2.1			V	
Input high voltage	V <sub>IH</sub>		2.4			V	
Input leakage current	I <sub>IL</sub>			0.001	1	μА	
Input capacitance	C <sub>IL</sub>				8	pF	
POWER REQUIREMENTS							
Supply voltage	V <sub>DD</sub>		2.7		5.5	V	
Supply current	I <sub>DD</sub>	Normal operation, logic inputs = 0V		3	6	μА	
V <sub>DD</sub> = +4.5V to +5.5V		$V_{IH} = V_{DD}$ and $V_{IL} = GND$		3	6	<u>.</u> μΑ	
$V_{DD} = +2.7V \text{ to } +3.6V$		$V_{IH} = V_{DD}$ and $V_{IL} = GND$		1	3	<u>.</u> μΑ	
AC CHARACTERISTICS(1)(2)						•	
Output current settling time	t <sub>S</sub>	To 0.1% of full-scale, Data = 0000h to 3FFFh to 0000h		0.3		μs	
	t <sub>S</sub>	To 0.006% of full-scale, Data = 0000h to 3FFFh to 0000h		0.5		μs	
Reference multiplying BW	BW – 3dB	V <sub>REF</sub> = 5V <sub>PP</sub> , Data = 3FFFh, 2-quadrant mode		10		MHz	
DAC glitch impulse		V <sub>REF</sub> = 0V to 10V, Data = 1FFFh to 2000h to 1FFFh		5		nV-s	
Feedthrough error	$V_{OUT}/V_{REF}$	Data = 0000h, $V_{REF}$ = 100kHz, $\pm$ 10 $V_{PP}$ , 2-quadrant mode		-70		dB	
Crosstalk error	$V_{\text{OUT}} A / V_{\text{REF}} B$	Data = 0000h, $V_{REF}B = 100 \text{mV}_{RMS}$ , $f = 100 \text{kHz}$		-100		dB	
Digital feedthrough		LDAC = Logic low, $V_{REF} = -10V$ to + 10V Any code change		1		nV-s	
Total harmonic distortion	THD	$V_{REF} = 6V_{RMS}$ , Data = 3FFFh, f = 1kHz		-105		dB	
Output noise density	e <sub>N</sub>	f = 1kHz, BW = 1Hz, 2-quadrant mode		12		nV/√ <del>Hz</del>	

<sup>(1)</sup> Specified by design and characterization; not production tested.(2) All ac characteristic tests are performed in a closed-loop system using a THS4011 I-to-V converter amplifier.



### **PIN ASSIGNMENTS**

#### DBT PACKAGE TSSOP-38 (TOP VIEW)





# PIN ASSIGNMENTS (continued) Table 1. TERMINAL FUNCTIONS

PIN#	NAME	DESCRIPTION
1, 2	NC	No connection
3	R <sub>OFS</sub> A	Bipolar Offset Resistor A. Accepts up to $\pm 18V$ . In 2-quadrant mode, R <sub>OFS</sub> A ties to R <sub>FB</sub> A. In 4-quadrant mode, R <sub>OFS</sub> A ties to R <sub>1</sub> A and the external reference.
4	$R_{FB}A$	Internal Matching Feedback Resistor A. Connects to the external op amp for I-V conversion.
5	R <sub>1</sub> A	4-Quadrant Resistor. In 2-quadrant mode, $R_1A$ shorts to the $V_{REF}A$ pin. In 4-quadrant mode, $R_1A$ ties to $R_{OFS}A$ and the reference input.
6	R <sub>COM</sub> A	Center Tap Point of the Two 4-Quadrant Resistors, $R_1A$ and $R_2A$ . In 2-quadrant mode, $R_{COM}A$ shorts to the $V_{REF}$ pin. In 4-quadrant mode, $R_{COM}A$ ties to the inverting node of the reference amplifier.
7	$V_{REF}A$	DAC A Reference Input in 2-Quadrant Mode, $R_2$ Terminal in 4-Quadrant Mode. In 2-quadrant mode, $V_{\text{REF}}A$ is the reference input with constant input resistance versus code. In 4-quadrant mode, $V_{\text{REF}}A$ is driven by the external reference amplifier.
8	$I_{OUT}A$	DAC A Current Output. Connects to the inverting terminal of external precision I-V op amp for voltage output.
9	AGNDA	DAC A Analog Ground.
10	DGND	Digital Ground.
11	AGNDB	DAC B Analog Ground.
12	I <sub>OUT</sub> B	DAC B Current Output. Connects to the inverting terminal of external precision I-V op amp for voltage output.
13	$V_{REF}B$	DAC B Reference Input in 2-Quadrant Mode, $R_2$ Terminal in 4-Quadrant Mode. In 2-quadrant mode, $V_{\text{REF}}$ B is the reference input with constant input resistance versus code. In 4-quadrant mode, $V_{\text{REF}}$ B is driven by the external reference amplifier.
14	R <sub>COM</sub> B	Center Tap Point of the Two 4-Quadrant Resistors, $R_1B$ and $R_2B$ . In 2-quadrant mode, $R_{COM}B$ shorts to the $V_{REF}$ pin. In 4-quadrant mode, $R_{COM}B$ ties to the inverting node of the reference amplifier.
15	R <sub>1</sub> B	4-Quadrant Resistor. In 2-quadrant mode, R <sub>1</sub> B shorts to the V <sub>REF</sub> B pin. In 4-quadrant mode, R <sub>1</sub> B ties to R <sub>OFS</sub> B and the reference input.
16	R <sub>FB</sub> B	Internal Matching Feedback Resistor B. Connects to external op amp for I-V conversion.
17	R <sub>OFS</sub> B	Bipolar Offset Resistor B. Accepts up to ±18V. In 2-quadrant mode, R <sub>OFS</sub> B ties to R <sub>FB</sub> B. In 4-quadrant mode, R <sub>OFS</sub> B ties to R <sub>1</sub> B and the external reference.
18	WR	Write Control Digital Input In, Active Low. $\overline{WR}$ enables input registers. Signal level must be $\leq$ V <sub>DD</sub> + 0.3V.
19	A0	Address 0. Signal level must be $\leq$ V <sub>DD</sub> + 0.3V.
20	A1	Address 1. Signal level must be $\leq$ V <sub>DD</sub> + 0.3V.
21	LDAC	Digital Input Load DAC Control. Signal level must be $\leq$ V <sub>DD</sub> + 0.3V. See the Function of Control Inputs table for details.
22	RSTSEL	Power-On Reset State. RSTSEL = 0 corresponds to zero-scale reset. RSTSEL = 1 corresponds to mid-scale reset. The signal level must be $\leq$ V <sub>DD</sub> + 0.3V.
23	RS	Reset. Active low resets both input and DAC registers. Resets to zero-scale if RSTSEL= 0, and to mid-scale if RSTSEL = 1. Signal level must be equal to or less than VDD + 0.3 V.
24-28, 30-38	D0-D13	Digital Input Data Bits D0 to D13. Signal level must be ≤ V <sub>DD</sub> +0.3V. D13 is MSB.
29	$V_{DD}$	Positive Power Supply Input. The specified range of operation is 2.7V to 5.5V.



### TIMING AND FUNCTIONAL INFORMATION

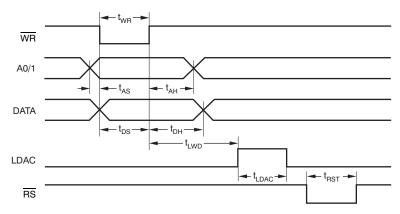


Figure 1. Timing Diagram

# **TIMING CHARACTERISTICS**

All specifications at  $T_A = -40$  °C to +125 °C,  $I_{OUT} = virtual$  GND, GND = 0V, and  $V_{REF} = 10$ V, unless otherwise noted

				DAC8805		
PARAMETER		CONDITIONS	MIN	TYP	MAX	UNITS
Data to WD action time		$V_{DD} = +5.0V$	10	-		ns
Data to WR setup time t <sub>DS</sub>		V <sub>DD</sub> = +2.7V	10			ns
A0/1 to WR setup time		$V_{DD} = +5.0V$	10			ns
AU/1 to WK Setup time	t <sub>AS</sub>	V <sub>DD</sub> = +2.7V	10			ns
Data to WR hold time		$V_{DD} = +5.0V$	0			ns
Data to WK floid time	t <sub>DH</sub>	V <sub>DD</sub> = +2.7V	0			ns
A0/1 to WR hold time		$V_{DD} = +5.0V$	0			ns
AU/T to WK hold time	t <sub>AH</sub>	V <sub>DD</sub> = +2.7V	0			ns
WD sules width		$V_{DD} = +5.0V$	10	-		ns
WR pulse width	t <sub>WR</sub>	V <sub>DD</sub> = +2.7V	10			ns
LDAC pulps width		$V_{DD} = +5.0V$	10	-		ns
LDAC pulse width	t <sub>LDAC</sub>	V <sub>DD</sub> = +2.7V	10			ns
DC mulaa width		$V_{DD} = +5.0V$	10			ns
RS pulse width	t <sub>RST</sub>	$V_{DD} = +2.7V$	10			ns
MD to LDAC delay time		$V_{DD} = +5.0V$	0	-		ns
WR to LDAC delay time	t <sub>LWD</sub>	V <sub>DD</sub> = +2.7V	0	-		ns



### **Table 2. Address Decoder Pins**

A1	Α0	OUTPUT UPDATE
0	0	DAC A
0	1	None
1	0	DAC A and DAC B
1	1	DAC B

# **Table 3. Function of Control Inputs**

C	ONTROL INPU	TS	
RS	WR	LDAC	REGISTER OPERATION
0	х	Х	Asynchronous operation. Reset the input and DAC register to '0' when the RSTSEL pin is tied to DGND, and to midscale when RSTSEL is tied to $V_{DD}$ .
1	0	0	Load the input register with all 14 data bits.
1	1	1	Load the DAC register with the contents of the input register.
1	0	1	The input and DAC register are transparent.
1	L	T	LDAC and WR are tied together and programmed as a pulse. The 14 data bits are loaded into the input register on the falling edge of the pulse and then loaded into the DAC register on the rising edge of the pulse.
1	1	0	No register operation.



# TYPICAL CHARACTERISTICS: V<sub>DD</sub> = +5V

#### Channel A

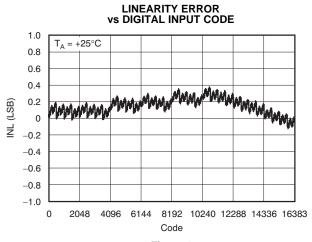


Figure 2.

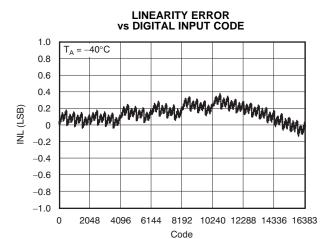


Figure 4.

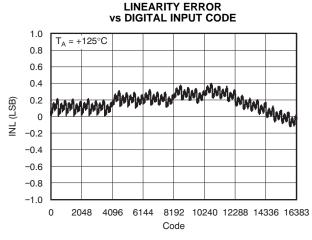


Figure 6.

# DIFFERENTIAL LINEARITY ERROR VS DIGITAL INPUT CODE

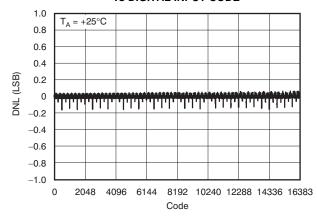


Figure 3.

# DIFFERENTIAL LINEARITY ERROR VS DIGITAL INPUT CODE

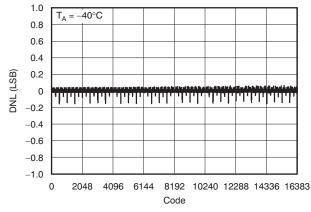


Figure 5.

# DIFFERENTIAL LINEARITY ERROR vs DIGITAL INPUT CODE

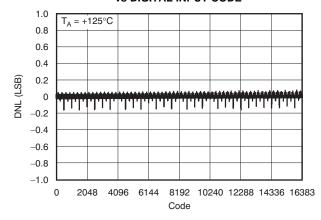


Figure 7.



## TYPICAL CHARACTERISTICS: $V_{DD} = +5V$ (continued)

#### Channel B

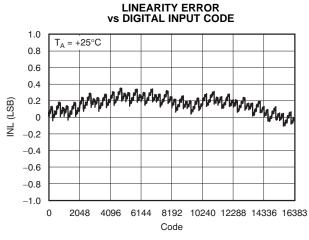
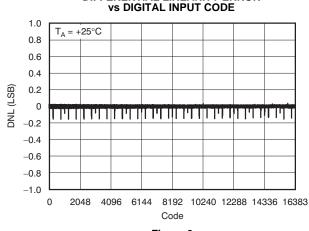


Figure 8.



**DIFFERENTIAL LINEARITY ERROR** 

Figure 9.

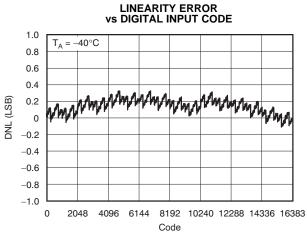


Figure 10.

LINEARITY ERROR

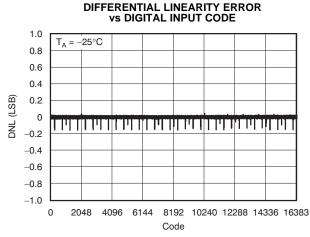


Figure 11.

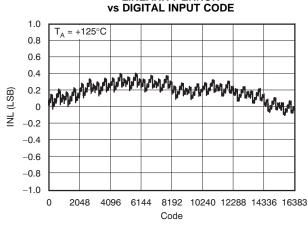


Figure 12.

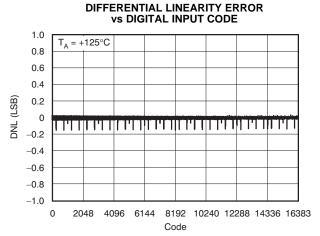


Figure 13.



# TYPICAL CHARACTERISTICS: $V_{DD} = +5V$ (continued)



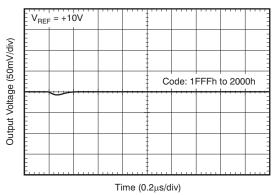


Figure 14.

# MIDSCALE DAC GLITCH

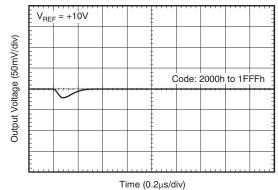


Figure 15.

# FULL-SCALE ERROR vs TEMPERATURE

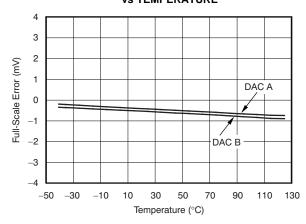


Figure 16.

# BIPOLAR-ZERO ERROR vs TEMPERATURE

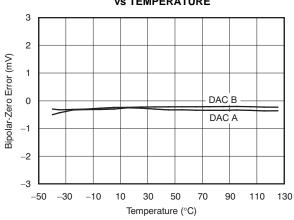


Figure 17.



## TYPICAL CHARACTERISTICS: V<sub>DD</sub> = +2.7V

#### Channel A

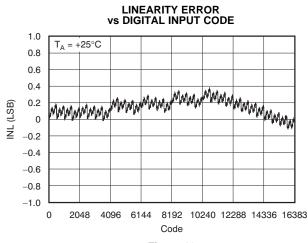


Figure 18.

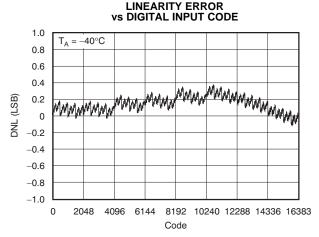


Figure 20.

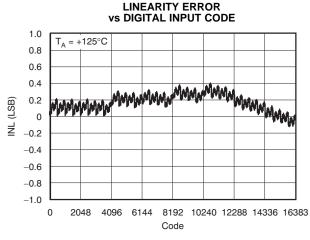


Figure 22.

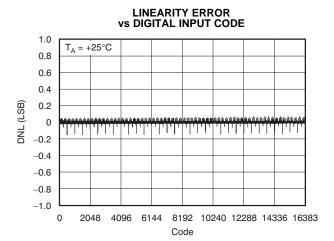


Figure 19.

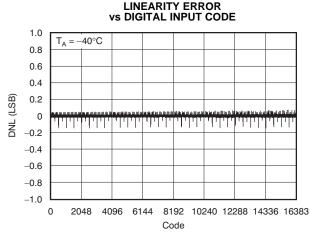


Figure 21.

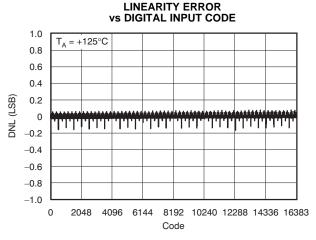


Figure 23.



## TYPICAL CHARACTERISTICS: $V_{DD} = +2.7V$ (continued)

#### Channel B

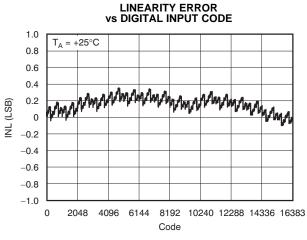


Figure 24.

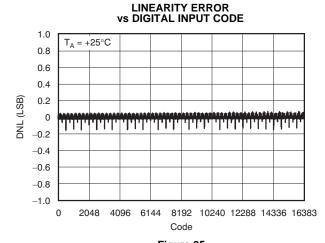


Figure 25.

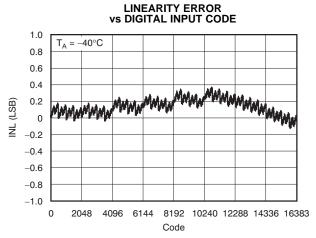


Figure 26.

LINEARITY ERROR

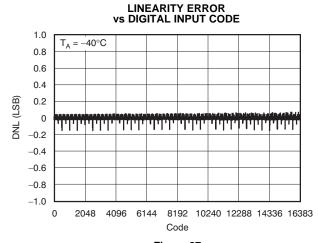


Figure 27.

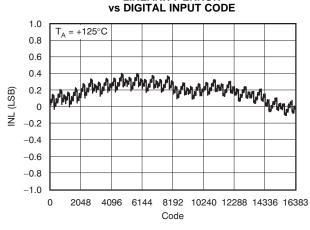


Figure 28.

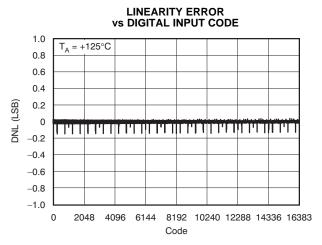


Figure 29.



# TYPICAL CHARACTERISTICS: $V_{DD} = +2.7V$ (continued)

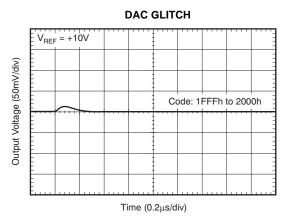
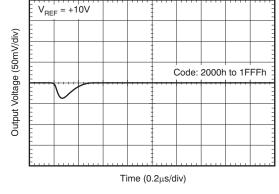


Figure 30.



DAC GLITCH

Figure 31.

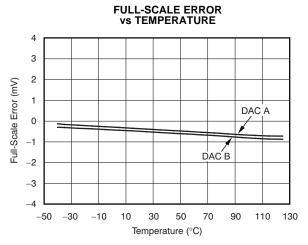


Figure 32.

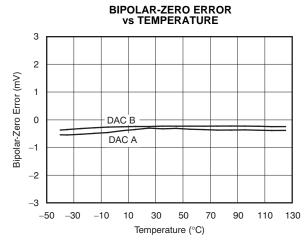
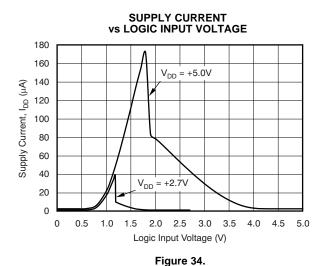


Figure 33.



## TYPICAL CHARACTERISTICS: $V_{DD} = +2.7V$ and +5V



REFERENCE MULTIPLYING BANDWIDTH **UNIPOLAR MODE** 

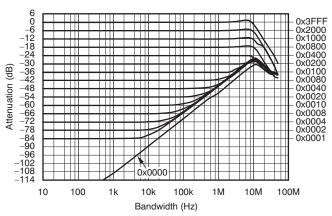


Figure 35.

#### REFERENCE MULTIPLYING BANDWIDTH **BIPOLAR MODE**

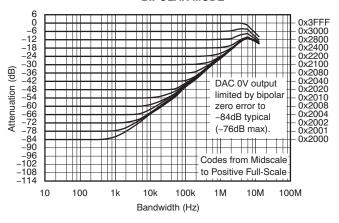


Figure 36.

# REFERENCE MULTIPLYING BANDWIDTH **BIPOLAR MODE**

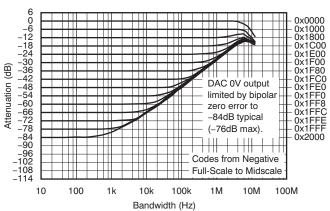


Figure 37.

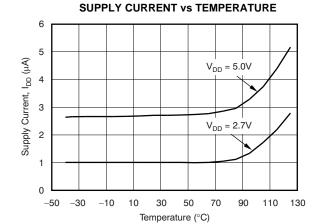


Figure 38.

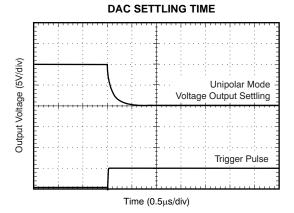


Figure 39.



#### THEORY OF OPERATION

The DAC8805 is a multiplying, dual-channel, current output, 14-bit DAC. The architecture, illustrated in Figure 40, is an R-2R ladder configuration with the three MSBs segmented. Each 2R leg of the ladder is either switched to GND or to the  $I_{OUT}$  terminal. The  $I_{OUT}$  terminal of the DAC is held at a virtual GND potential by the use of an external I/V converter op amp. The R-2R ladder is connected to an external reference input ( $V_{REF}$ ) that determines the DAC full-scale output current. The R-2R ladder presents a code-independent load impedance to the external reference of  $5k\Omega \pm 25\%$ . The external reference voltage can vary in a range of -18V to +18V, thus providing bipolar  $I_{OUT}$  current operation. By using an external I/V converter op amp and the  $R_{FB}$  resistor in the DAC8805, an output voltage range of  $-V_{REF}$  to  $+V_{REF}$  can be generated.

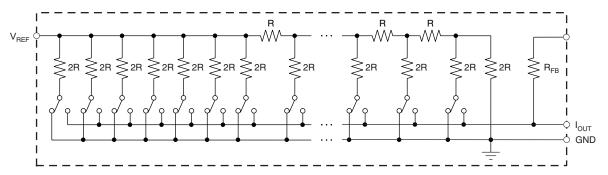


Figure 40. Equivalent R-2R DAC Circuit

The DAC output voltage is determined by V<sub>RFF</sub> and the digital data (D) according to Equation 1:

$$V_{OUT}A/B = -V_{REF} \times \frac{D}{16384}$$
 (1)

Each DAC code determines the 2R-leg switch position to either GND or  $I_{OUT}$ . The external I/V converter op amp noise gain will also change because the DAC output impedance (as seen looking into the  $I_{OUT}$  terminal) changes versus code. Because of this change in noise gain, the external I/V converter op amp must have a sufficiently low offset voltage such that the amplifier offset is not modulated by the DAC  $I_{OUT}$  terminal impedance change. External op amps with large offset voltages can produce INL errors in the transfer function of the DAC8805 because of offset modulation versus DAC code. For best linearity performance of the DAC8805, an op amp (such as the OPA277) is recommended, as shown in Figure 41. This circuit allows  $V_{REF}$  to swing from -10V to +10V.

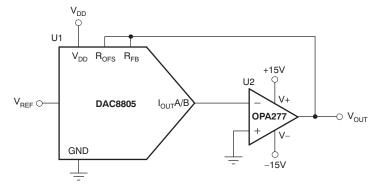


Figure 41. Voltage Output Configuration

#### **APPLICATION INFORMATION**

#### DIGITAL INTERFACE

The parallel bus interface of the DAC8805 is comprised of a 14-bit data bus, D0—D13, address lines A0 and A1, and a  $\overline{\text{WR}}$  control signal. Timing and control functionality are shown in Figure 1, and described in Table 2 and Table 3. The address lines must be set up and stable before the  $\overline{\text{WR}}$  signal goes low, to prevent loading improper data to an undesired input register.

Both channels of the DAC8805 can be simultaneously updated by control of the LDAC signal, as shown in Figure 1. Reset control (RSTSEL) signals are provided to allow user reset ability to either zero scale or midscale codes of both the input and DAC registers.

#### **STABILITY CIRCUIT**

For a current-to-voltage (I/V) design, as shown in Figure 42, the DAC8805 current output ( $I_{OUT}$ ) and the connection with the inverting node of the op amp should be as short as possible and laid out according to correct printed circuit board (PCB) layout design. For each code change, there is an output step function. If the gain bandwidth product (GBP) of the op amp is limited and parasitic capacitance is excessive at the inverting node, then gain peaking is possible. Therefore, a compensation capacitor  $C_1$  (4pF to 20pF, typ) can be added to the design for circuit stability, as shown in Figure 42.

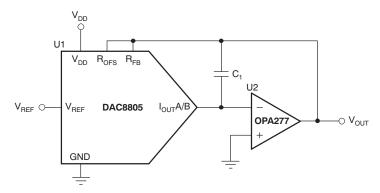


Figure 42. Gain Peaking Prevention Circuit with Compensation Capacitor



#### **APPLICATION INFORMATION (continued)**

#### **BIPOLAR OUTPUT CIRCUIT**

The DAC8805, as a 4-quadrant multiplying DAC, can be used to generate a bipolar output. The polarity of the full-scale output ( $I_{OUT}$ ) is the inverse of the input reference voltage at  $V_{REF}$ .

Using a dual op amp, such as the OPA2277, full 4-quadrant operation can be achieved with minimal components. Figure 43 demonstrates a  $\pm 10 V_{OUT}$  circuit with a fixed +10V reference. The output voltage is shown in Equation 2:

$$V_{OUT} = \left(\frac{D}{8192} - 1\right) \times V_{REF} \tag{2}$$

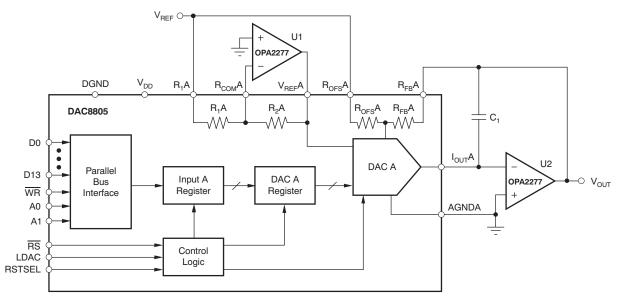


Figure 43. Bipolar Output Circuit



### **APPLICATION INFORMATION (continued)**

#### PROGRAMMABLE CURRENT SOURCE CIRCUIT

The DAC8805 can be integrated into the circuit in Figure 44 to implement an improved Howland current pump for precise V/I conversions. Bidirectional current flow and high-voltage compliance are two features of the circuit. With a matched resistor network, the load current of the circuit is shown by Equation 3:

$$I_{L}A/B = \frac{(R_{2} + R_{3}) / R_{1}}{R_{3}} \times V_{REF} \times \frac{D}{16384}$$
(3)

The value of  $R_3$  in the previous equation can be reduced to increase the output current drive of U3. U3 can drive  $\pm 20$ mA in both directions with voltage compliance limited up to 15V by the U3 voltage supply. Elimination of the circuit compensation capacitor ( $C_1$ ) in the circuit is not suggested as a result of the change in the output impedance ( $Z_0$ ), according to Equation 4:

$$Z_{O} = \frac{R_{1}'R_{3}(R_{1} + R_{2})}{R_{1}(R_{2}' + R_{3}') - R_{1}'(R_{2} + R_{3})}$$
(4)

As shown in Equation 4,  $Z_O$  with matched resistors is infinite and the circuit is optimum for use as a current source. However, if unmatched resistors are used,  $Z_O$  is positive or negative with negative output impedance being a potential cause of oscillation. Therefore, by incorporating  $C_1$  into the circuit, possible oscillation problems are eliminated. The value of  $C_1$  can be determined for critical applications; for most applications, however, a value of several pF is suggested.

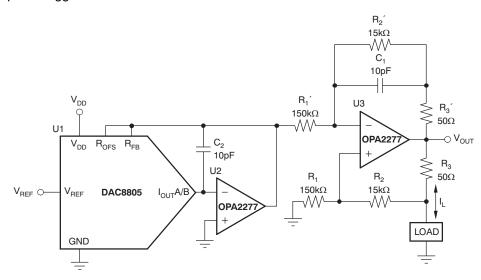


Figure 44. Programmable Bidirectional Current Source Circuit

#### **CROSS-REFERENCE**

The DAC8805 has an industry-standard pinout. Table 4 provides the cross-reference information.

**Table 4. Cross-Reference** 

PRODUCT	BIT	INL (LSB)	DNL (LSB)	SPECIFIED TEMPERATURE RANGE	PACKAGE DESCRIPTION	PACKAGE OPTION	CROSS- REFERENCE PART
DAC8805Q	14	1	1	-40°C to +125°C	TSSOP-38	DBT	AD5557





21-May-2010

#### **PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan <sup>(2)</sup>	Lead/ Ball Finish	MSL Peak Temp <sup>(3)</sup>	Samples (Requires Login)
DAC8805QDBT	ACTIVE	TSSOP	DBT	38	50	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR	
DAC8805QDBTG4	ACTIVE	TSSOP	DBT	38	50	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR	
DAC8805QDBTR	ACTIVE	TSSOP	DBT	38	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR	
DAC8805QDBTRG4	ACTIVE	TSSOP	DBT	38	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR	

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

**Pb-Free** (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes. **Pb-Free** (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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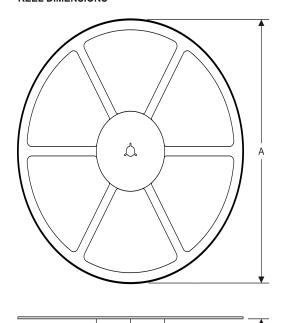
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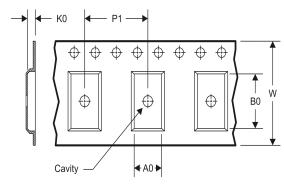
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## TAPE AND REEL INFORMATION

#### **REEL DIMENSIONS**







A0	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

#### TAPE AND REEL INFORMATION

\*All dimensions are nominal

Device	_	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
DAC8805QDBTR	TSSOP	DBT	38	2000	330.0	16.4	6.9	10.2	1.8	12.0	16.0	Q1

# **PACKAGE MATERIALS INFORMATION**

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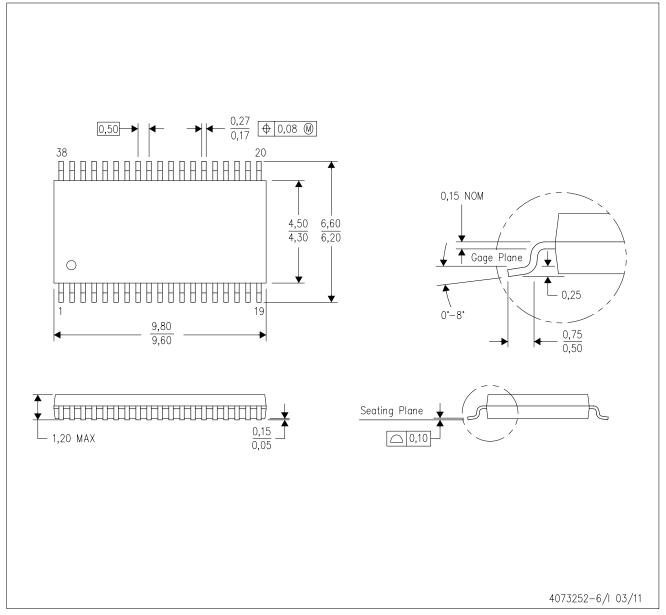


#### \*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)	
DAC8805QDBTR	TSSOP	DBT	38	2000	367.0	367.0	38.0	

DBT (R-PDSO-G38)

# PLASTIC SMALL OUTLINE



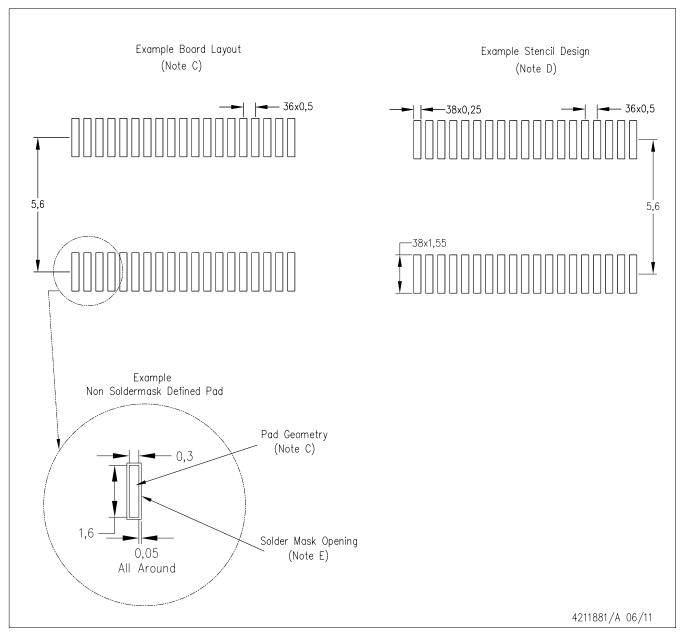
NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994.

- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion.
- D. Falls within JEDEC MO-153.



# DBT (R-PDSO-G38)

# PLASTIC SMALL OUTLINE



NOTES:

- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525.
- E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.



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