

DS100BR111A Ultra Low Power 10.3 Gbps 2-Channel Repeaters with Input Equalization and Output De-Emphasis

Check for Samples: [DS100BR111A](#)

FEATURES

- Two channel repeater for up to 10.3 Gbps
 - DS100BR111 : 1x bidirectional lane
 - DS100BR111A : 1x bidirectional lane
- Low 65mW/channel (typical) power consumption, with option to power down unused channels
- Advanced signal conditioning features
 - Receive equalization up to +36 dB
 - Transmit de-emphasis up to -12 dB
 - Transmit VOD control: 600 to 1200 mVp-p
 - < 0.25 UI of residual DJ at 10 Gbps
- Programmable via pin selection, EEPROM or SMBus interface

- Single supply operation selectable: 2.5V or 3.3V
- Flow-thru pinout in 4mmx4mm 24-pin leadless WQFN package
- >5kV HBM ESD rating
- Industrial -40 to 85°C operating temperature range

APPLICATIONS

- High-speed active copper cable modules and FR-4 backplane in communication systems
- 10GE, FC, SAS, SATA 3/6 Gbps (with OOB detection), InfiniBand, CPRI, RXAUI and many others

DESCRIPTION

The DS100BR111A is an extremely low power, high performance dual-channel repeater for serial links with data rates up to 10.3 Gbps. The DS100BR210A features one bidirectional lane (one transmit, one receive channel).

The DS100BR111A features a powerful continuous time linear equalizer (CTLE) to provide a boost of up to +36 dB at 5 GHz and open an input eye that is completely closed due to inter-symbol interference (ISI) induced by the interconnect mediums such as an FR-4 backplane or AWG-30 cables. The transmitter features a programmable output de-emphasis driver with up to -12 dB and allows amplitude voltage levels to be selected from 600 mVp-p to 1200 mVp-p to suit multiple application scenarios.

The programmable settings can be applied via pin settings, SMBus (I2C) protocol or an external EEPROM. When operating in the EEPROM mode, the configuration information is automatically loaded on power up – This eliminates the need for an external microprocessor or software driver.

Part of the PowerWise family of energy efficient devices, the DS100BR111A consumes just 65 mW/channel (typical), and allow the option to turn-off unused channels. This ultra low power consumption eliminates the need for external heat sinks and simplifies thermal management in active cable applications.



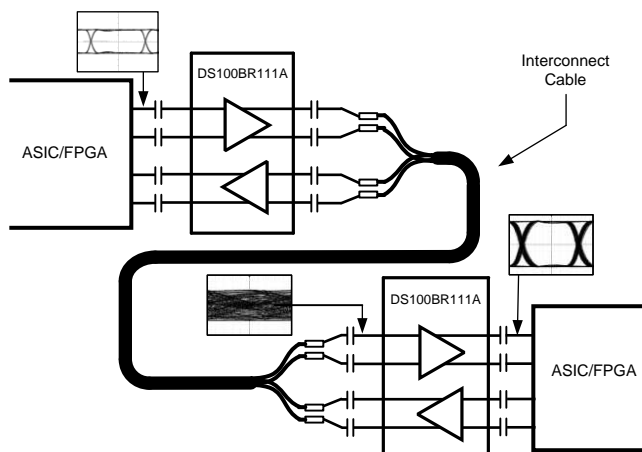
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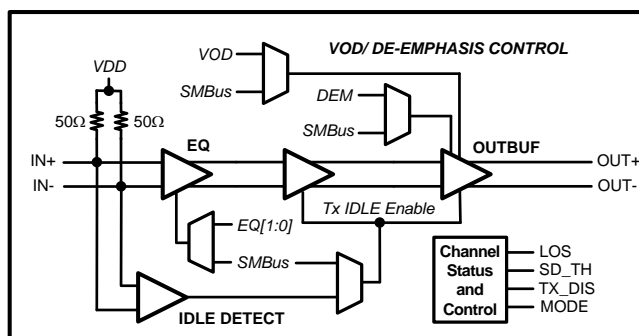
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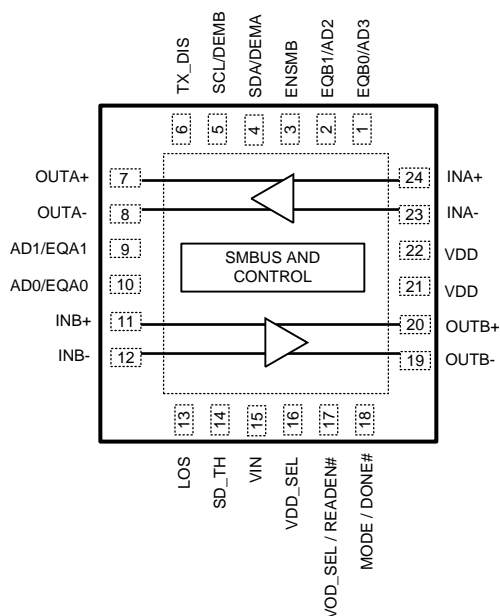
Typical Application



Block Diagram - Detail View Of Channel (1 Of 2)



Pin Diagram



The center DAP on the package bottom is the device GND connection. This pad must be connected to GND through multiple (minimum of 4) vias to ensure optimal electrical and thermal performance.

Figure 1. DS100BR111A Pin Diagram 24 lead

Pin Descriptions⁽¹⁾⁽²⁾

Pin Name	Pin Number	I/O, Type	Pin Description
Differential High Speed I/O's			
INA+, INA-, INB+, INB-,	24, 23 11, 12	I, CML	Inverting and non-inverting CML differential inputs to the equalizer. An on-chip 50Ω termination resistor connects INx+ to VDD and INx- to VDD when enabled.
OUTA+, OUTA-, OUTB+, OUTB-,	7, 8 20, 19	O, CML	Inverting and non-inverting 50Ω driver outputs with de-emphasis. Compatible with AC coupled CML inputs.
Control Pins			
ENSMB	3	I, LVCMOS Float	System Management Bus (SMBus) enable pin Tie HIGH = Register Access, SMBus Slave mode FLOAT = SMBus Master read from External EEPROM Tie LOW = External Pin Control Mode
ENSMB = 1 (SMBUS MODE)			
SCL	5	I, LVCMOS O, Open Drain	ENSMB Master or Slave mode SMBus clock input pin is enabled. A clock input in Slave mode. Can also be a clock output in Master mode.
SDA	4	I, LVCMOS, O, Open Drain	ENSMB Master or Slave mode The SMBus bidirectional SDA pin is enabled. Data input or open drain (pull-down only) output.
AD0-AD3	10, 9, 2, 1	I, LVCMOS, Float (4-Levels)	ENSMB Master or Slave mode SMBus Slave Address Inputs. In SMBus mode, these pins are the user set SMBus slave address inputs. There are 16 addresses supported by these pins. Pins must be tied LOW or HIGH when used to define the device SMBus address. (3)
READEN#	17	I, LVCMOS	When using an External EEPROM, a transition from high to low starts the load from the external EEPROM
DONE#	18	IO, LVCMOS, Float (4-Levels)	EEPROM Download Status HIGH indicates Error / Still Loading LOW indicates download complete. No Error.
ENSMB = 0 (PIN MODE)			
EQA0, EQA1 EQB0, EQB1	10, 9 1, 2	I, LVCMOS, Float (4-Levels)	EQA/B, 0/1 control the level of equalization of each channel. The EQA/B pins are active only when ENSMB is de-asserted (LOW). When ENSMB goes high the SMBus registers provide independent control of each lane, and the EQB0/B1 pins are converted to SMBUS AD2/AD3 inputs. Table 2
DEMA, DEMB	4, 5	IO, LVCMOS, Float (4-Levels)	DEMA/B controls the level of de-emphasis. The DEMA/B pins are only active when ENSMB is de-asserted (LOW). Each of the 4 A/B channels have the same level unless controlled by the SMBus control registers. When ENSMB goes high the SMBus registers provide independent control of each lane and the DEM pins are converted to SMBUS SCL and SDA pins. Table 3
TX_DIS	6	I, LVCMOS	DS100BR111A High = OUTA Enabled /OUTB Disabled Low = OUTA/B Enabled
VOD_SEL	17	I, LVCMOS, Float (4-Levels)	VOD select. High = (VOD = 950 mV / 1150 mV) Float = (VOD = 850 mV) 20K = (VOD = 1050 mV) Low = (VOD = 575 mV) (4)See Table 4 for additional information. (3)
VDD_SEL	16	I, Internal Pull-up	Enables the 3.3V to 2.5V internal regulator Low = 3.3 V Operation Float = 2.5 V Operation
MODE	18	I, LVCMOS, Float (4-Levels)	Controls Device Mode of Operation High = Continuous Talk (no output IDLE) Float = Slow OOB 20KΩ = eSATA Mode, Fast OOB, Auto Low Power on 100 uS of inactivity. SD stays active. Low = SAS Mode, Fast OOB

- (1) LVCMOS inputs without the "Float" conditions must be driven to a logic low or high at all times or operation is not guaranteed. Unless the "Float" level is desired; 4-Level input pins require a minimum 1K resistor to GND, VDD (in 2.5V mode), or VIN (in 3.3V mode).
- (2) Input edge rate for LVCMOS/FLOAT inputs must be faster than 50 ns from 10–90%.
- (3) Setting VOD_SEL = High in SMBus Mode will force the SMBus Address = B0'h
- (4) DS100BR111A OUTA is limited to 575mV in pin mode

Pin Descriptions⁽¹⁾⁽²⁾ (continued)

Pin Name	Pin Number	I/O, Type	Pin Description
Status Output			
LOS	13	O, Open Drain	When HIGH, indicates Loss of Signal (Default is LOS on INA). Can be modified via SMBus registers.
LOS Threshold Input			
SD_TH	14	I, LVCMOS, Float (4-Levels)	The SD_TH pin controls LOS threshold setting: Assert (mV), Deassert (mV) 20K = 160 mV, 100 mV Float = 180 mV, 110 mV (Default) High = 190 mV, 130 mV Low = 210 mV, 150 mV ⁽⁵⁾
Power			
VDD	21, 22	Power	Power supply pins 2.5V mode connect to 2.5V 3.3V mode do not connect to any supply voltage. Should be used to attach external decoupling to device, 100 - 200 nF recommended. See Applications Information section for additional information.
VIN	15	Power	VIN = 3.3V +/-10% (input to internal LDO regulator) ⁽⁶⁾ See Applications Information section for additional information.
GND	DAP	Power	Ground pad (DAP - die attach pad).

(5) Using values less than the default level can extend the time required to detect LOS and are not recommended.

(6) Must FLOAT for 2.5V operation.



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

Absolute Maximum Ratings ⁽¹⁾

Supply Voltage (VDD)		-0.5V to +2.75V
Supply Voltage (VIN)		-0.5V to +4.0V
LVCMOS Input/Output Voltage		-0.5V to +4.0V
CML Input Voltage		-0.5V to (VDD+0.5)
CML Input Current		-30 to +30 mA
Junction Temperature		125°C
Storage Temperature		-40°C to +125°C
ESD Rating	HBM, STD - JESD22-A114F	> 5 kV
	MM, STD - JESD22-A115-A	100 V
	CDM, STD - JESD22-C101-D	1250 V
Package Thermal Resistance	θJC	3.2°C/W
	θJA, No Airflow, 4 layer JEDEC	33.0°C/W
For soldering specifications: See product folder at www.national.com www.national.com/ms/MS/MS-SOLDERING.pdf		

(1) "Absolute Maximum Ratings" indicate limits beyond which damage to the device may occur, including inoperability and degradation of device reliability and/or performance. Functional operation of the device and/or non-degradation at the Absolute Maximum Ratings or other conditions beyond those indicated in the Recommended Operating Conditions is not implied.

Recommended Operating Conditions⁽¹⁾

	Min	Typ	Max	Units
Supply Voltage (2.5V mode)	2.375	2.5	2.625	V
Supply Voltage (3.3V mode)	3.0	3.3	3.6	V
Ambient Temperature	-40	25	+85	°C
SMBus (SDA, SCL)			3.6	V

(1) The Recommended Operating Conditions indicate conditions at which the device is functional and the device should not be operated beyond such conditions. Absolute Maximum Numbers are guaranteed for a junction temperature range of -40°C to +125°C. Models are validated to Maximum Operating Voltages only.

Electrical Characteristics

Parameter		Test Conditions	Min	Typ	Max	Units
POWER SUPPLY CURRENT						
IDD	Supply Current	TX_DIS = LOW, EQ = ON VOD_SEL = Float (1000 mV)		50	63	mA
		Auto Low Power Mode TX_DIS = LOW, MODE = 20K VID_CHA and CHB = 0.0V VOD_SEL = Float (1000 mV)		12	15	
		TX_DIS = HIGH (BR111A)		25	35	
LVCMOS DC SPECIFICATIONS						
V _{IH}	Voltage Input High		2.0		VDD	V
V _{IL}	Voltage Input Low		GND		0.7	V
V _{OH}	Voltage Output High	I _{OH} = -4.0 mA ⁽¹⁾	2.0			V
V _{OL}	Voltage Output Low	I _{OL} = 4.0 mA			0.4	V
I _{IN}	Input Leakage Current	Vinput = 0V or VDD VDD_SEL = Float	-15		+15	uA
		Vinput = 0V or VIN VDD_SEL = Low	-15		-15	
I _{IN-P}	Input Leakage Current 4-Level Input ⁽²⁾	Vinput = 0V or VDD - 0.05V VDD_SEL = Float Vinput = 0V or VIN - 0.05V VDD_SEL = Low	-160		+80	uA
LOS AND ENABLE / DISABLE TIMING						
T _{LOS_OFF}	Input IDLE to Active RX_LOS response time	See ⁽³⁾		0.035		uS
T _{LOS_ON}	Input Active to IDLE RX_LOS response time	See ⁽³⁾		0.4		uS
T _{OFF}	TX Disable assert Time TX_DIS = HIGH to Output OFF	See ⁽³⁾		0.005		uS
T _{ON}	TX Disable negateTime TX_DIS = LOW to Output ON	See ⁽³⁾		0.150		uS
T _{LP_EXIT}	Auto Low Power Exit ALP to Normal Operation	See ⁽³⁾		150		nS
T _{LP_ENTER}	Auto Low Power Enter Normal Operation to Auto Low Power	See ⁽³⁾		100		uS
CML RECEIVER INPUTS						
V _{TX}	Source Transmit Launch Signal Level	Default power-up conditions ENSMB = 0 or 1	190	800	1600	mV
RL _{RX-IN}	RX return loss	SDD11 @ 4.1 GHz		-12		dB
		SDD11 @ 11.1 GHz		-8		
		SCD11 @ 11.1 GHz		-10		

(1) Typical jitter reported is determined by jitter decomposition software on the DSA8200 Oscilloscope.

(2) Input is held to a maximum of 50 mV below VDD or VIN to simulate the use of a 1K resistor on the input.

(3) Parameter not tested in production.

Electrical Characteristics (continued)

Parameter		Test Conditions	Min	Typ	Max	Units
HIGH SPEED TRANSMITTER OUTPUTS						
V _{OD1}	Output Voltage Differential Swing	OUT+ and OUT- AC coupled and terminated by 50Ω to GND VOD_SEL = LOW DE = LOW	425	575	725	mVp-p
V _{OD2}	Output Voltage Differential Swing	OUT+ and OUT- AC coupled and terminated by 50Ω to GND VOD_SEL = FLOAT DE = LOW	675	850	1025	
V _{OD3}	Output Voltage Differential Swing	OUT+ and OUT- AC coupled and terminated by 50Ω to GND VOD_SEL = 20K DE = LOW	850	1050	1275	
V _{OD_DE1}	De-Emphasis Levels	OUT+ and OUT- AC coupled and terminated by 50Ω to GND VOD_SEL = FLOAT DE = FLOAT		- 3.5		dB
V _{OD_DE2}	De-Emphasis Levels	OUT+ and OUT- AC coupled and terminated by 50Ω to GND VOD_SEL = FLOAT DE = 20K		- 6.0		dB
V _{OD_DE3}	De-Emphasis Levels	OUT+ and OUT- AC coupled and terminated by 50Ω to GND VOD_SEL = FLOAT DE = HIGH		- 9.0		dB
V _{CM-AC}	Output Common-Mode Voltage	AC Common Mode Voltage DE = 0 dB		4.5		mV (RMS)
V _{CM-DC}	Output DC Common-Mode Voltage	DC Common Mode Voltage	0	1.1	1.9	V
V _{IDLE}	TX IDLE Output Voltage				30	mV
RL _{TX-DIFF}	TX return loss	SDD22 @ 4.1 GHz		-13		dB
		SDD22 @ 11.1 GHz		-9		
		SCC22 @ 2.5 GHz		-22		
		SCC22 @ 11.1 GHz		-10		
delta Z _M	Transmitter Termination Mismatch	DC, I _{FORCE} = +/- 100 uA ⁽⁴⁾		2.5		%
T _{R/F}	Transmitter Rise and Fall Time	Measurement points at 20% - 80% ⁽⁵⁾		38		ps
T _{PD}	Propagation Delay	Measured at 50% crossing EQ = 00		230		ps
T _{CCSK}	Inter-pair Channel Skew	T = 25°C, VDD = 2.5V		7		ps
T _{PPSK}	Part to Part Channel Skew	T = 25°C, VDD = 2.5V		20		ps
T _{TX-IDLE-SET-TO-IDLE}	Max time to transition to idle after differential signal	VIN = 1Vpp, 10 Gbps EQ = 00, DE = 0		6.5		ns
T _{TX-IDLE-TO-DIFF-DATA}	Max time to transition to valid differential signal after idle	VIN = 1Vpp, 10 Gbps EQ = 00, DE = 0		3.2		ns
T _{ENVELOPE_DISTORT}	Active OOB timing distortion, input active time vs. output active time			3.3		ns

(4) Force +/- 100 uA on output, measure delta V on the Output and calculate impedance. Mismatch is the percentage difference of OUTn+ and OUTn- impedance driving the same logic state.

(5) Default VOD used for testing. DE = -1.5 dB level used to compensate for fixture attenuation.

Electrical Characteristics (continued)

Parameter		Test Conditions	Min	Typ	Max	Units
OUTPUT JITTER SPECIFICATIONS ⁽⁶⁾						
R _J	Random Jitter	No Media Source Amplitude = 700 mV, PRBS15 pattern, 10.3125 Gbps VOD = 850 mV, EQ = minimum, DE = 0 dB		0.3		ps (RMS)
D _{J1}	Deterministic Jitter			0.09		UI
EQUALIZATION						
D _{JE1}	Residual Deterministic Jitter 10.3125 Gbps	8 meter 30AWG Cable on Inputs Source = 700 mV, PRBS15 pattern EQ = 2B'h		0.23		UI
D _{JE2}	Residual Deterministic Jitter 10.3125 Gbps	30" FR4 on Inputs Source = 700 mV, PRBS15 pattern EQ = 17'h		0.15		UI
DE-EMPHASIS						
D _{JD1}	Residual Deterministic Jitter 10.3125 Gbps	10" 4 mil stripline FR4 on Outputs Source = 700 mV, PRBS15 pattern EQ = Min, VOD = 1050, DE = 010		0.14		UI

(6) Typical jitter reported is determined by jitter decomposition software on the DSA8200 Oscilloscope.

Electrical Characteristics — Serial Management Bus Interface

Over recommended operating supply and temperature ranges unless other specified.

Parameter		Test Conditions	Min	Typ	Max	Units
SERIAL BUS INTERFACE DC SPECIFICATIONS: ⁽¹⁾						
V _{IL}	Data, Clock Input Low Voltage				0.8	V
V _{IH}	Data, Clock Input High Voltage		2.1		3.6	V
I _{PULLUP}	Current Through Pull-Up Resistor or Current Source	High Power Specification	4			mA
V _{DD}	Nominal Bus Voltage		2.375		3.6	V
I _{LEAK-Bus}	Input Leakage Per Bus Segment	See ⁽²⁾	-200		+200	μA
C _I	Capacitance for SDA and SCL	See ⁽²⁾ ⁽³⁾ ⁽⁴⁾			10	pF
R _{TERM}	External Termination Resistance pull to V _{DD} = 2.5V ± 5% OR 3.3V ± 10%	Pullup V _{DD} = 3.3V, ⁽²⁾ ⁽³⁾ ⁽⁵⁾		2000		Ω
		Pullup V _{DD} = 2.5V, ⁽²⁾ ⁽³⁾ ⁽⁵⁾		1000		Ω
SERIAL BUS INTERFACE TIMING SPECIFICATIONS						
FSMB	Bus Operating Frequency	ENSMB = VDD (Slave Mode)			400	kHz
		ENSMB = FLOAT (Master Mode) ⁽⁶⁾	280	400	520	kHz
TBUF	Bus Free Time Between Stop and Start Condition		1.3			μs
THD:STA	Hold time after (Repeated) Start Condition. After this period, the first clock is generated.	At I _{PULLUP} , Max	0.6			μs
TSU:STA	Repeated Start Condition Setup Time		0.6			μs
TSU:STO	Stop Condition Setup Time		0.6			μs
THD:DAT	Data Hold Time		0			ns
TSU:DAT	Data Setup Time		100			ns

(1) Compliant to SMBus 2.0 physical layer specification. See System Management Bus (SMBus) Specification Version 2.0, section 3.1.1 SMBus common AC specifications for details.

(2) Recommended value.

(3) Recommended maximum capacitance load per bus segment is 400pF.

(4) Guaranteed by Design. Parameter not tested in production.

(5) Maximum termination voltage should be identical to the device supply voltage.

(6) EEPROM interface requires 400 KHz capable EEPROM device.

Electrical Characteristics — Serial Management Bus Interface (continued)

Over recommended operating supply and temperature ranges unless other specified.

Parameter		Test Conditions	Min	Typ	Max	Units
T_{LOW}	Clock Low Period		1.3			μ s
T_{HIGH}	Clock High Period	See ⁽¹⁾	0.6		50	μ s
t_F	Clock/Data Fall Time	See ⁽¹⁾			300	ns
t_R	Clock/Data Rise Time	See ⁽¹⁾			300	ns
t_{POR}	Time in which a device must be operational after power-on reset	See ⁽¹⁾ ⁽⁴⁾			500	ms

TIMING DIAGRAMS

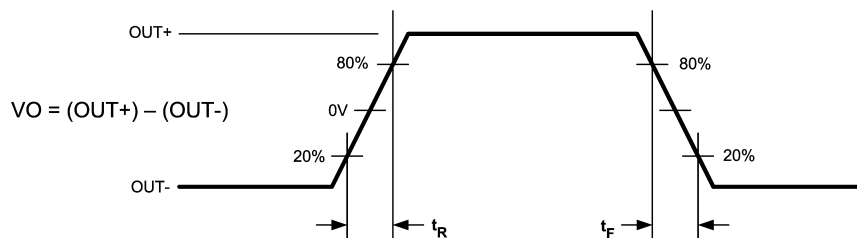


Figure 2. CML Output Transition Times

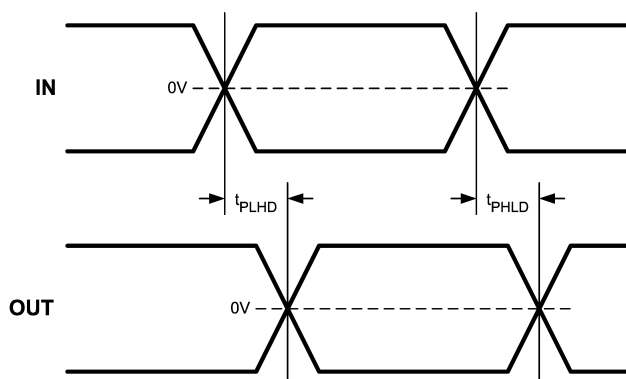


Figure 3. Propagation Delay Timing Diagram

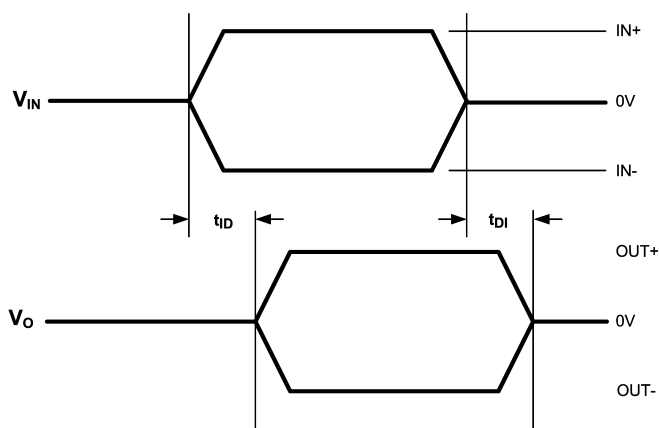


Figure 4. Idle Timing Diagram

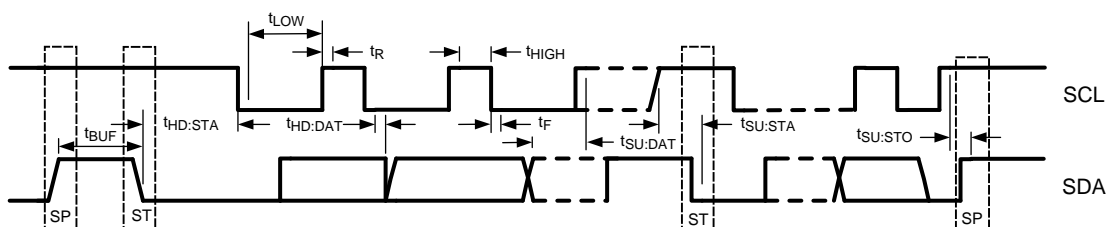


Figure 5. SMBus Timing Parameters

FUNCTIONAL DESCRIPTION

The DS100BR111A is a high performance circuit capable of delivering excellent performance. Careful attention must be paid to the details associated with high-speed design as well as providing a clean power supply. Refer to the information below and Revision 4 of the LVDS Owner's Manual for more detailed information on high speed design tips to address signal integrity design issues.

The control pins have been enhanced to have 4 different levels and provide a wider range of control settings. Refer to [Table 1](#).

Table 1. 4-Level Control Pin Settings

Pin Setting	Description
0	Tie pin to GND through a 1 K Ω resistor
R	Tie pin to ground through 20 K Ω resistor
Float	Float the pin (no connection)
1	Tie pin to VDD through a 1 K Ω resistor

NOTE

4-Level IO pins require a 1K resistance to GND or VDD/VIN. It is possible to tie multiple 4-level IO pins together with a single resistor to GND or VDD/VIN. When multiple IOs are connected in parallel, the resistance to GND or VDD/VIN should be adjusted to compensate. For 2 pins the optimal resistance is 500 Ohms, 3 pins = 330 Ohms, and 4 pins = 250 Ohms.

NOTE

For 2.5V mode the control pin logic 1 level is VDD (pins 21 and 22), in 3.3V mode the control pin logic 1 level is defined by VIN (pin 15).

Table 2. Equalizer Settings

Level	EQA1/EQB1	EQA0/EQB0	EQ — 8 bits [7:0]	dB Boost at 5 Ghz	Suggested Media
1	0	0	0000 0000 = 0x00	2.5	FR4 < 5 inch trace
2	0	R	0000 0001 = 0x01	6.5	FR4 5 inch trace
3	0	Float	0000 0010 = 0x02	9	FR4 10 inch trace
4	0	1	0000 0011 = 0x03	11.5	FR4 15 inch trace
5	R	0	0000 0111 = 0x07	14	FR4 20 inch trace
6	R	R	0001 0101 = 0x15	15	FR4 25 inch trace
7	R	Float	0000 1011 = 0x0B	17	FR4 25 inch trace
8	R	1	0000 1111 = 0x0F	19	7m 30AWG Cable
9	Float	0	0101 0101 = 0x55	20	FR4 30 inch trace
10	Float	R	0001 1111 = 0x1F	23	8m 30 AWG Cable FR4 35 inch trace
11	Float	Float	0010 1111 = 0x2F	25	10m 30 AWG Cable
12	Float	1	0011 1111 = 0x3F	27	10m - 12m, Cable
13	1	0	1010 1010 = 0xAA	30	
14	1	R	0111 1111 = 0x7F	31	
15	1	Float	1011 1111 = 0xBF	33	
16	1	1	1111 1111 = 0xFF	34	

NOTE

Settings are approximate and will change based on PCB material, trace dimensions, and driver waveform characteristics.

Table 3. De-emphasis and Output Voltage Settings

Level	VOD_SEL	DEMA/B	SMBus Register DEM Level	SMBus Register VOD Level	VOD (mV)	DEM (dB)
1	0	0	000	000	575	0
2	0	Float	010	000	575	- 3.5
3	0	R	011	000	575	- 6
4	0	1	101	000	575	- 9
5	Float	0	000	011	850	0
6	Float	Float	010	011	850	- 3.5
7	Float	R	011	011	850	- 6
8	Float	1	101	011	850	- 9
9	R	0	000	101	1050	- 0
10	R	Float	010	101	1050	- 3.5
11	R	R	011	101	1050	- 6
12	R	1	101	101	1050	- 9
13	1	0	000	100	950	0
14	1	Float	001	100	950	- 1.5
15	1	R	001	110	1150	- 1.5
16	1	1	010	110	1150	- 3.5

NOTE

Below 850mV output setting De-emphasis gain is reduced.

NOTE

The DS100BR111A VOD for OUTPUT A is limited to 575 mV in pin mode (ENSMB=0). With ENSMB = 1 or FLOAT, the VOD for OUTPUT A can be adjusted with SMBus register 0x23 [4:2] as shown in [Table 8](#).

NOTE

In SMBus Mode if VOD_SEL is in the Logic 1 state (1K resistor to VIN/VDD) the DS100BR111A AD0-AD3 pins are internally forced to 0'h

Table 4. Signal Detect Threshold Level⁽¹⁾

SD_TH	SMBus REG bit [3:2] and [1:0]	Assert Level (Typical)	De-assert Level (Typical)
0	10	210 mV	150 mV
20K to GND	01	160 mV	100 mV
Float (Default)	00	180 mV	110 mV
1	11	190 mV	130 mV

(1) VDD = 2.5V, 25°C, and 010101 pattern at 10 Gbps

APPLICATIONS INFORMATION

4-Level Input Configuration Guidelines

The 4-level input pins utilize a resistor divider to help set the 4 valid levels. There is an internal 30K pull-up and a 60K pull-down connected to the package pin. These resistors, together with the external resistor connection combine to achieve the desired voltage level. Using the 1K pull-up, 1K pull-down, no connect, and 20K pull-down provide the optimal voltage levels for each of the four input states.

Table 5. 4-Level Input Voltage

Level	Setting	3.3V Mode	2.5V Mode
0	01K to GND	0.1 V	0.08 V
R	20K to GND	$0.33 * V_{IN}$	$0.33 * V_{DD}$
F	FLOAT	$0.67 * V_{IN}$	$0.67 * V_{DD}$
1	1K to V_{DD}/V_{IN}	$V_{IN} - 0.05V$	$V_{IN} - 0.04V$

- Typical 4-Level Input Thresholds
 - Level 1 - 2 = $0.2 V_{IN}$ or V_{DD}
 - Level 2 - 3 = $0.5 V_{IN}$ or V_{DD}
 - Level 3 - 4 = $0.8 V_{IN}$ or V_{DD}

In order to minimize the startup current associated with the integrated 2.5V regulator the 1K pull-up / pull-down resistors are recommended. If several 4 level inputs require the same setting, it is possible to combine two or more 1K resistors into a single lower value resistor. As an example; combining two inputs with a single 500Ω resistor is a good way to save board space.

PCB Layout Guidelines

The CML inputs and outputs have been optimized to work with interconnects using a controlled differential impedance of 85 - 100Ω. It is preferable to route differential lines exclusively on one layer of the board, particularly for the input traces. The use of vias should be avoided if possible. If vias must be used, they should be used sparingly and must be placed symmetrically for each side of a given differential pair. Whenever differential vias are used the layout must also provide for a low inductance path for the return currents as well. Route the differential signals away from other signals and noise sources on the printed circuit board. See [SNOA401Q AN-1187](#) for additional information on WQFN packages.

Different transmission line topologies can be used in various combinations to achieve the optimal system performance. Impedance discontinuities at vias can be minimized or eliminated by increasing the swell around each hole and providing for a low inductance return current path. When the via structure is associated with thick backplane PCB, further optimization such as back drilling is often used to reduce the detrimental high frequency effects of stubs on the signal path.

Power Supply Configuration Guidelines

The DS100BR111A can be configured for 2.5V operation or 3.3V operation. The lists below outline required connections for each supply selection.

3.3V Mode of Operation

- Tie $V_{DD_SEL} = 0$ with 1K resistor to GND.
- Feed 3.3V supply into VIN pin. Local 1.0 uF decoupling at VIN is recommended.
- See information on VDD bypass below.
- SDA and SCL pins should connect pull-up resistor to VIN
- Any 4-Level input which requires a connection to "Logic 1" should use a 1K resistor to VIN

2.5V Mode of Operation

- $V_{DD_SEL} = \text{Float}$
- VIN = Float
- Feed 2.5V supply into VDD pins.

9. See information on VDD bypass below.
10. SDA and SCL pins connect pull-up resistor to VDD for 2.5V uC SMBus IO
11. SDA and SCL pins connect pull-up resistor to VDD for 3.3V uC SMBus IO
12. Any 4-Level input which requires a connection to "Logic 1" should use a 1K resistor to VIN

NOTE

The DAP (bottom solder pad) is the GND connection.

Power Supply Bypass

Two approaches are recommended to ensure that the DS100BR111A is provided with an adequate power supply. First, the supply (VDD) and ground (GND) pins should be connected to power planes routed on adjacent layers of the printed circuit board. The layer thickness of the dielectric should be minimized so that the V_{DD} and GND planes create a low inductance supply with distributed capacitance. Second, careful attention to supply bypassing through the proper use of bypass capacitors is required. A 0.1 μ F bypass capacitor should be connected to each V_{DD} pin such that the capacitor is placed as close as possible to the device. Smaller body size capacitors can help facilitate proper component placement.

System Management Bus (SMBus) and Configuration Registers

The System Management Bus interface is compatible to SMBus 2.0 physical layer specification. ENSMB must be pulled high to enable SMBus mode and allow access to the configuration registers.

The DS100BR111A has AD[3:0] inputs in SMBus mode. These pins are the user set SMBus slave address inputs. When pulled low the AD[3:0] = 0000'b, the device default address byte is B0'h. Based on the SMBus 2.0 specification, this configuration results in a 7-bit slave address of 1011000'b. The LSB is set to 0'b (for a WRITE), thus the 8-bit value is 1011 0000'b or B0'h. The device address byte can be set with the use of the AD[3:0] inputs.

Shown in the form of an expression:

Slave Address [7:4] = The DS100BR111A hardware address (1011'b) + Address pin AD[3]

Slave Address [3:1] = Address pins AD[2:0]

Slave Address [0] = 0'b for a WRITE or 1'b for a READ

Slave Address Examples:

- AD[3:0] = 0001'b, the device slave address byte is B2'h
 - Slave Address [7:4] = 1011'b + 0'b = 1011'b or B'h
 - Slave Address [3:1] = 001'b
 - Slave Address [0] = 0'b for a WRITE
- AD[3:0] = 0010'b, the device slave address byte is B4'h
 - Slave Address [7:4] = 1011'b + 0'b = 1011'b or B'h
 - Slave Address [3:1] = 010'b
 - Slave Address [0] = 0'b for a WRITE
- AD[3:0] = 0100'b, the device slave address byte is B8'h
 - Slave Address [7:4] = 1011'b + 0'b = 1011'b or B'h
 - Slave Address [3:1] = 100'b
 - Slave Address [0] = 0'b for a WRITE
- AD[3:0] = 1000'b, the device slave address byte is C0'h
 - Slave Address [7:4] = 1011'b + 1'b = 1100'b or C'h
 - Slave Address [3:1] = 000'b
 - Slave Address [0] = 0'b for a WRITE

TRANSFER OF DATA VIA THE SMBus

During normal operation the data on SDA must be stable during the time when SCL is High.

There are three unique states for the SMBus:

START: A High-to-Low transition on SDA while SCL is High indicates a message START condition.

STOP: A Low-to-High transition on SDA while SCL is High indicates a message STOP condition.

IDLE: If SCL and SDA are both High for a time exceeding t_{BUF} from the last detected STOP condition or if they are High for a total exceeding the maximum specification for t_{HIGH} then the bus will transfer to the IDLE state.

SMBus TRANSACTIONS

The device supports WRITE and READ transactions. See [Table 8](#) for register address, type (Read/Write, Read Only), default value and function information.

WRITING A REGISTER

To write a register, the following protocol is used (see SMBus 2.0 specification).

1. The Host drives a START condition, the 7-bit SMBus address, and a “0” indicating a WRITE.
2. The Device (Slave) drives the ACK bit (“0”).
3. The Host drives the 8-bit Register Address.
4. The Device drives an ACK bit (“0”).
5. The Host drive the 8-bit data byte.
6. The Device drives an ACK bit (“0”).
7. The Host drives a STOP condition.

The WRITE transaction is completed, the bus goes IDLE and communication with other SMBus devices may now occur.

READING A REGISTER

To read a register, the following protocol is used (see SMBus 2.0 specification).

1. The Host drives a START condition, the 7-bit SMBus address, and a “0” indicating a WRITE.
2. The Device (Slave) drives the ACK bit (“0”).
3. The Host drives the 8-bit Register Address.
4. The Device drives an ACK bit (“0”).
5. The Host drives a START condition.
6. The Host drives the 7-bit SMBus Address, and a “1” indicating a READ.
7. The Device drives an ACK bit “0”.
8. The Device drives the 8-bit data value (register contents).
9. The Host drives a NACK bit “1” indicating end of the READ transfer.
10. The Host drives a STOP condition.

The READ transaction is completed, the bus goes IDLE and communication with other SMBus devices may now occur.

Please see [Table 8](#) for more information.

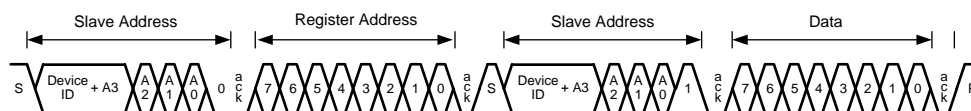


Figure 6. Typical SMBus Write Operation

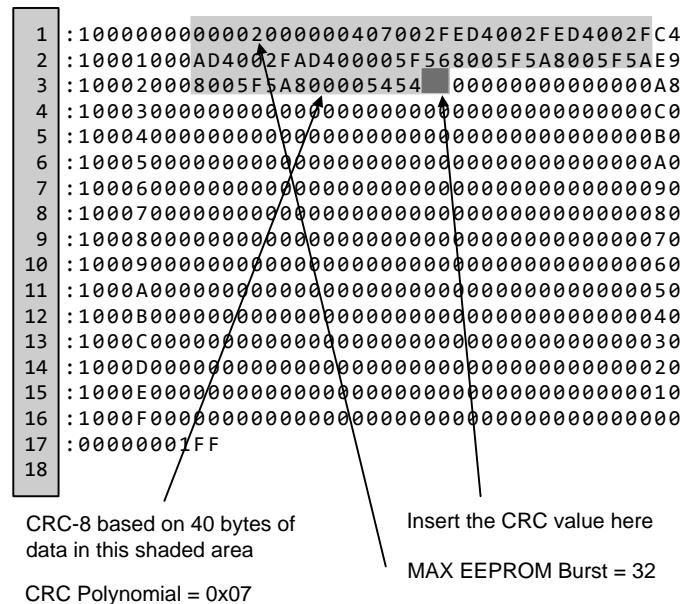
EEPROM Modes in DS100BR111A Devices

The DS100BR111A supports reading directly from an external EEPROM device by implementing SMBus Master mode. When using the SMBus master mode, the DS100BR111A will read directly from specific location in the external EEPROM. When designing a system for using the external EEPROM, the user needs to follow these specific guidelines.

- Set the DS100BR111A into SMBus Master Mode
 - Float ENSMB (PIN 3)
- The external EEPROM device address byte must be 0xA0'h
- Set the AD[3:0] inputs for SMBus address byte. When the AD[3:0] = 0000'b, the device address byte is B0'h.
- Based on the SMBus 2.0 specification, a device can have a 7-bit slave address of 1010 000'b. The LSB is set to 0'b (for a WRITE). The bit mapping for SMBus is listed below:
 - [7:5] = Reserved Bits from the SMBus specification
 - [4:1] = Usable SMBus Address Bits
 - [0] = Write Bit
- The DS100BR111A devices have AD[3:0] inputs in SMBus mode (pins 1, 2, 9, 10). These pins set SMBus slave address. When the AD[3:0] = 0001'b, the device address byte is B2'h.
 - [7:5] = Default to 3b'101
 - [4:1] = Address of 4'b0001
 - [0] = Write Bit, 1'b0
- The device address can be set with the use of the AD[3:0] input up to 16 different addresses. Use the example below to set each of the SMBus addresses.
 - AD[3:0] = 0001'b, the device address byte is B2'h
 - AD[3:0] = 0010'b, the device address byte is B4'h
 - AD[3:0] = 0011'b, the device address byte is B6'h
 - AD[3:0] = 0100'b, the device address byte is B8'h
- The master implementation in the DS100BR111A, support multiple devices reading from 1 EEPROM. When tying multiple devices to the SDA and SCL pins, use these guidelines:
 - Use adjacent SMBus addresses for the 4 devices
 - Use a pull-up resistor on SDA; value = 2.0KΩ
 - Use a pull-up resistor on SCL; value = 2.0KΩ
 - Daisy-chain READEN# (pin 17) and DONE# (pin18) from one device to the next device in the sequence
 1. Tie READEN# of the 1st device in the chain (U1) to GND
 2. Tie DONE# of U1 to READEN# of U2
 3. Tie DONE# of U2 to READEN# of U3
 4. Tie DONE# of U3 to READEN# of U4
 5. Optional: Tie DONE# of U4 to a LED to show each of the devices have been loaded successfully

Master EEPROM Mode in the DS100BR111A

Below is an example of a 2 kbits (256 x 8-bit) EEPROM in hex format for the DS100BR111A device. The first 3 bytes of the EEPROM always contain a header common and necessary to control initialization of all devices connected to the I2C bus. CRC enable flag to enable/disable CRC checking. There is a MAP bit to flag the presence of an address map that specifies the configuration data start in the EEPROM. If the MAP bit is not present the configuration data start address is derived from the DS100BR111A address and the configuration data size. A bit to indicate an EEPROM size > 256 bytes is necessary to properly address the EEPROM. There are 37 bytes of data size for each DS100BR111A device.

**Figure 7. Typical EEPROM Data Set**

The CRC-8 calculation is performed on the first 3 bytes of header information plus the 37 bytes of data for the DS100BR111A or 40 bytes in total. The result of this calculation is placed immediately after the DS100BR111A data in the EEPROM which ends with "5454". The CRC-8 in the DS100BR111A uses a polynomial = $x^8 + x^2 + x + 1$

In SMBus master mode the DS100BR111A reads its initial configuration from an external EEPROM upon power-up. Some of the pins of the DS100BR111A perform the same functions in SMBus master and SMBus slave mode. Once the DS100BR111A has finished reading its initial configuration from the external EEPROM in SMBus master mode it reverts to SMBus slave mode and can be further configured by an external controller over the SMBus. The connection to an external SMBus master is optional and can be omitted for applications where additional security is desirable. There are two pins that provide unique functions in SMBus master mode.

- DONE#
- READEN#

When the DS100BR111A is powered up in SMBus master mode, it reads its configuration from the external EEPROM when the READEN# pin goes low. When the DS100BR111A is finished reading its configuration from the external EEPROM, it drives the DONE# pin low. In applications where there is more than one DS100BR111A on the same SMBus, bus contention can result if more than one DS100BR111A tries to take control of the SMBus at the same time. The READEN# and DONE# pins prevent this bus contention. The system should be designed so that the READEN# pin from one DS100BR111A in the system is driven low on power-up. This DS100BR111A will take command of the SMBus on power-up and will read its initial configuration from the external EEPROM. When it is finished reading its configuration, it will drive the DONE# pin low. This pin should be connected to the READEN# pin of another DS100BR111A. When this DS100BR111A senses its READEN# pin driven low, it will take command of the SMBus and read its initial configuration from the external EEPROM, after which it will set its DONE# pin low. By connecting the DONE# pin of each DS100BR111A to the READEN# pin of the next DS100BR111A, each DS100BR111A can read its initial configuration from the EEPROM without causing bus contention.



Table 6. Multi-Device EEPROM Register Map Overview

[illegible]

Table 6. Multi-Device EEPROM Register Map Overview (continued)

	Addr	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Device 0 Addr 39	47	RES	RES	RES	RES	RES	RES	RES	RES
Device 1 Addr 3	48	RES	RES	RES	RES	RES	LOS_Channe l	RES	RES
Device 1 Addr 4	49	Ovrd_LOS	LOS Value	PDWN Inp	PDWN OSC	RES	eSATA CHA	eSATA CHB	Ovrd TX_DIS
Device 1 Addr 38	83	RES	RES	RES	RES	RES	RES	RES	RES
Device 1 Addr 39	84	RES	RES	RES	RES	RES	RES	RES	RES
Device 2 Addr 3	85	RES	RES	RES	RES	RES	LOS_Channe l	RES	RES
Device 2 Addr 4	86	Ovrd_LOS	LOS Value	PDWN Inp	PDWN OSC	RES	eSATA CHA	eSATA CHB	Ovrd TX_DIS
Device 2 Addr 38	120	RES	RES	RES	RES	RES	RES	RES	RES
Device 2 Addr 39	121	RES	RES	RES	RES	RES	RES	RES	RES
Device 3 Addr 3	122	RES	RES	RES	RES	RES	LOS_Channe l	RES	RES
Device 3 Addr 4	123	Ovrd_LOS	LOS Value	PDWN Inp	PDWN OSC	RES	eSATA CHA	eSATA CHB	Ovrd TX_DIS
Device 3 Addr 38	157	RES	RES	RES	RES	RES	RES	RES	RES
Device 3 Addr 39	158	RES	RES	RES	RES	RES	RES	RES	RES

- CRC EN = 1; Address Map = 1
- EEPROM > 256 Bytes = 0
- COUNT[3:0] = 0011'b

NOTE

Multiple DS100BR111A devices may point at the same address space if they have identical programming values.

Table 7. Single EEPROM Header + Register Map with Default Value

EEPROM Address Byte		Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Description	0	CRC EN	Address Map Present	EEPROM > 256 Bytes	RES	COUNT[3]	COUNT[2]	COUNT[1]	COUNT[0]
Value		0	0	0	0	0	0	0	0
Description	1	RES	RES	RES	RES	RES	RES	RES	RES
Value		0	0	0	0	0	0	0	0
Description	2	Max EEPROM Burst size[7]	Max EEPROM Burst size[6]	Max EEPROM Burst size[5]	Max EEPROM Burst size[4]	Max EEPROM Burst size[3]	Max EEPROM Burst size[2]	Max EEPROM Burst size[1]	Max EEPROM Burst size[0]
Value		0	0	0	0	0	0	0	0
Description	3	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register		0x01 [7]	0x01 [6]	0x01 [5]	0x01 [4]	0x01 [3]	0x01 [2]	0x01 [1]	0x01 [0]
Value		0	0	0	0	0	0	0	0

Table 7. Single EEPROM Header + Register Map with Default Value (continued)

EEPROM Address Byte		Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Description	4	Ovrd_LOS	LOS_Value	PDWN Inp	PWDN Osc	Reserved	eSATA Enable A	eSATA Enable B	Ovrd TX_DIS
Register		0x02 [5]	0x02 [4]	0x02 [3]	0x02 [2]	0x02 [0]	0x04 [7]	0x04 [6]	0x04 [5]
Value		0	0	0	0	0	0	0	0
Description	5	TX_DIS CHA	TX_DIS CHB	Reserved	Reserved	Reserved	Reserved	Override IDLE_th	Reserved
Register		0x04 [4]	0x04 [3]	0x04 [2]	0x04 [1]	0x04 [0]	0x06 [4]	0x08 [6]	0x08 [5]
Value		0	0	0	0	0	1	0	0
Description	6	Ovrd_IDLE	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register		0x08 [4]	0x08 [3]	0x08 [2]	0x08 [1]	0x08 [0]	0x0B [6]	0x0B [5]	0x0B [4]
Value		0	0	0	0	0	1	1	1
Description	7	Reserved	Reserved	Reserved	Reserved	Idle auto A	Idle sel A	Reserved	Reserved
Register		0x0B [3]	0x0B [2]	0x0B [1]	0x0B [0]	0x0E [5]	0x0E [4]	0x0E [3]	0x0E [2]
Value		0	0	0	0	0	0	0	0
Description	8	CHA EQ[7]	CHA EQ[6]	CHA EQ[5]	CHA EQ[4]	CHA EQ[3]	CHA EQ[2]	CHA EQ[1]	CHA EQ[0]
Register		0x0F [7]	0x0F [6]	0x0F [5]	0x0F [4]	0x0F [3]	0x0F [2]	0x0F [1]	0x0F [0]
Value		0	0	1	0	1	1	1	1
Description	9	A Sel scp	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register		0x10 [7]	0x10 [6]	0x10 [5]	0x10 [4]	0x10 [3]	0x10 [2]	0x10 [1]	0x10 [0]
Value		1	1	1	0	1	1	0	1
Description	10	DEMA[2]	DEMA[1]	DEMA[0]	CHA Slow	IDLE thA[1]	IDLE thA[0]	IDLE thD[1]	IDLE thD[0]
Register		0x11 [2]	0x11 [1]	0x11 [0]	0x12 [7]	0x12 [3]	0x12 [2]	0x12 [1]	0x12 [0]
Value		0	1	0	0	0	0	0	0
Description	11	Idle auto B	Idle sel B	Reserved	Reserved	CHB EQ[7]	CHB EQ[6]	CHB EQ[5]	CHB EQ[4]
Register		0x15 [5]	0x15 [4]	0x15 [3]	0x15 [2]	0x16 [7]	0x16 [6]	0x16 [5]	0x16 [4]
Value		0	0	0	0	0	0	1	0
Description	12	CHB EQ[3]	CHB EQ[2]	CHB EQ[1]	CHB EQ[0]	B Sel scp	Reserved	Reserved	Reserved
Register		0x16 [3]	0x16 [2]	0x16 [1]	0x16 [0]	0x17 [7]	0x17 [6]	0x17 [5]	0x17 [4]
Value		1	1	1	1	1	1	1	0
Description	13	Reserved	Reserved	Reserved	Reserved	CHB DEM[2]	CHB DEM[1]	CHB DEM[0]	CHB Slow
Register		0x17 [3]	0x17 [2]	0x17 [1]	0x17 [0]	0x18 [2]	0x18 [1]	0x18 [0]	0x19 [7]
Value		1	1	0	1	0	1	0	0
Description	14	IDLE thA[1]	IDLE thA[0]	IDLE thD[1]	IDLE thD[0]	Reserved	Reserved	Reserved	Reserved
Register		0x19 [3]	0x19 [2]	0x19 [1]	0x19 [0]				
Value		0	0	0	0	0	0	0	0
Description	15	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									
Value		0	0	1	0	1	1	1	1
Description	16	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									
Value		1	0	1	0	1	1	0	1
Description	17	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									
Value		0	1	0	0	0	0	0	0

Table 7. Single EEPROM Header + Register Map with Default Value (continued)

EEPROM Address Byte		Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Description	18	Reserved	BR111A CHA VOD[2]	BR111A CHA VOD[1]	BR111A CHA VOD[0]	Reserved	Reserved	Reserved	Reserved
Register			0x23 [4]	0x23 [3]	0x23 [2]				
Value		0	0	0	0	0	0	1	0
Description	19	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									0x25 [4]
Value		1	1	1	1	1	0	1	0
Description	20	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register		0x25 [3]	0x25 [2]						
Value		1	1	0	1	0	1	0	0
Description	21	Reserved	Reserved	Reserved	Reserved	ovrd fst idle	en hi idle th A	en hi idle th B	en fst idle A
Register						0x28 [6]	0x28 [5]	0x28 [4]	0x28 [3]
Value		0	0	0	0	0	0	0	1
Description	22	en fst idle B	sd mgain A	sd mgain B	Reserved	Reserved	Reserved	Reserved	Reserved
Register		0x28 [2]	0x28 [1]	0x28 [0]					
Value		1	0	0	0	0	0	0	0
Description	23	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									
Value		0	1	0	1	1	1	1	1
Description	24	Reserved	Reserved	Reserved	Reserved	CHB VOD[2]	CHB VOD[1]	CHB VOD[0]	Reserved
Register						0x2D [4]	0x2D [3]	0x2D [2]	
Value		0	1	0	1	1	0	1	0
Description	25	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									
Value		1	0	0	0	0	0	0	0
Description	26	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									
Value		0	0	0	0	0	1	0	1
Description	27	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									
Value		1	1	1	1	0	1	0	1
Description	28	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									
Value		1	0	1	0	1	0	0	0
Description	29	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									
Value		0	0	0	0	0	0	0	0
Description	30	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									
Value		0	1	0	1	1	1	1	1
Description	31	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									
Value		0	1	0	1	1	0	1	0
Description	32	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									
Value		1	0	0	0	0	0	0	0

Table 7. Single EEPROM Header + Register Map with Default Value (continued)

EEPROM Address Byte		Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Description	33	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									
Value		0	0	0	0	0	1	0	1
Description	34	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									
Value		1	1	1	1	0	1	0	1
Description	35	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									
Value		1	0	1	0	1	0	0	0
Description	36	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									
Value		0	0	0	0	0	0	0	0
Description	37	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									
Value		0	0	0	0	0	0	0	0
Description	38	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									
Value		0	1	0	1	0	1	0	0
Description	39	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
Register									
Value		0	1	0	1	0	1	0	0

Below is an example of a 2 kbits (256 x 8-bit) EEPROM Register Dump in hex format for a multi-device DS100BR111A application.

EEPROM Address	Address (Hex)	EEPROM Data	Comments
0	00	0x43	CRC_EN = 0, Address Map = 1, Device Count = 3 (Devices 0, 1, 2, and 3)
1	01	0x00	
2	02	0x08	EEPROM Burst Size
3	03	0x00	CRC not used
4	04	0x0B	Device 0 Address Location
5	05	0x00	CRC not used
6	06	0x30	Device 1 Address Location
7	07	0x00	CRC not used
8	08	0x30	Device 2 Address Location
9	09	0x00	CRC not used
10	0A	0x0B	Device 3 Address Location
11	0B	0x00	Begin Device 0 and Device 3 - Address Offset 3
12	0C	0x00	
13	0D	0x04	
14	0E	0x07	
15	0F	0x00	
16	10	0x2F	Default EQ CHA
17	11	0xED	
18	12	0x40	
19	13	0x02	Default EQ CHB
20	14	0xFE	Default EQ CHB

EEPROM Address	Address (Hex)	EEPROM Data	Comments
21	15	0xD4	
22	16	0x00	
23	17	0x2F	
24	18	0xAD	
25	19	0x40	
26	1A	0x02	BR111A CHA VOD =575 mV
27	1B	0xFA	
28	1C	0xD4	
29	1D	0x01	
30	1E	0x80	
31	1F	0x5F	
32	20	0x56	BR111A CHB VOD = 850 mV
33	21	0x80	
34	22	0x05	
35	23	0xF5	
36	24	0xA8	
37	25	0x00	
38	26	0x5F	
39	27	0x5A	
40	28	0x80	
41	29	0x05	
42	2A	0xF5	
43	2B	0xA8	
44	2C	0x00	
45	2D	0x00	
46	2E	0x54	
47	2F	0x54	End Device 0 and Device 3 - Address Offset 39
48	30	0x00	Begin Device 1 and Device 2 - Address Offset 3
49	31	0x00	
50	32	0x04	
51	33	0x07	
52	34	0x00	
53	35	0x2F	Default EQ CHA
54	36	0xED	
55	37	0x40	
56	38	0x02	Default EQ CHB
57	39	0xFE	Default EQ CHB
58	3A	0xD4	
59	3B	0x00	
60	3C	0x2F	
61	3D	0xAD	
62	3E	0x40	
63	3F	0x02	BR111A CHA VOD = 575 mV
64	40	0xFA	
65	41	0xD4	
66	42	0x01	
67	43	0x80	
68	44	0x5F	

EEPROM Address	Address (Hex)	EEPROM Data	Comments
69	45	0x56	BR111A CHB VOD = 850 mV
70	46	0x80	
71	47	0x05	
72	48	0xF5	
73	49	0xA8	
74	4A	0x00	
75	4B	0x5F	
76	4C	0x5A	
77	4D	0x80	
78	4E	0x05	
79	4F	0xF5	
80	50	0xA8	
81	51	0x00	
82	52	0x00	
83	53	0x54	
84	54	0x54	End Device 1 and Device 2 - Address Offset 39

Table 8. SMBus Register Map

Address	Register Name	Bits	Field	Type	Default	EEPROM Reg Bit	Description
0x00	Device ID	7	Reserved	R/W	0x00		set bit to 0
		6:3	I2C Address [3:0]	R			[6:3] SMBus strap observation
		2	EEPROM reading done	R			1: EEPROM Loading 0: EEPROM Done Loading
		1	Reserved	RWS C			Set bit to 0
		0	Reserved	RWS C			Set bit to 0
0x01	Control 1	7:6	Idle Control	R/W	0x00	Yes	Control [7]: Continuous talk ENABLE (Channel A) [6]: Continuous talk ENABLE (Channel B)
		5:3	Reserved	R/W			Set bits to 0
		2	LOS Select	R/W			LOS Monitor Selection 1: Use LOS from CH B 0: Use LOS from CH A
		1:0	Reserved	R/W			Set bits to 00'b
0x02	Control 2	7	Reserved	R/W	0x00		Set bit to 0
		6	Reserved				Set bit to 0
		5	LOS override			Yes	LOS pin override enable (1); Use Normal Signal Detection (0)
		4	LOS override value			Yes	1: Normal Operation 0: Output LOS
		3	PWDN Inputs			Yes	1: PWDN
		2	PWDN Oscillator			Yes	0: Normal Operation
		1	Reserved				
		0	Reserved			Yes	Set bit to 0

Table 8. SMBus Register Map (continued)

Address	Register Name	Bits	Field	Type	Default	EEPROM Reg Bit	Description
0x04	Control 3	7:6	eSATA Mode Enable	R/W	0x00	Yes	[7] Channel A (1) [6] Channel B (1)
		5	TX_DIS Override Enable				1: Override Use Reg 0x04[4:3] 0: Normal Operation - uses pin
		4	TX_DIS Value Channel A				1: TX Disabled 0: TX Enabled
		3	TX_DIS Value Channel B				
		2	Reserved				Set bit to 0'b
		1:0	Reserved				Set bits to 00'b
0x05	CRC 1	7:0	CRC[7:0]	R/W	0x00		Slave Mode CRC Bits
0x06	CRC 2	7	Disable EEPROM CFG	R/W	0x10		Disable Master Mode EEPROM Configuration
		6:5	Reserved				Set bits to 00'b
		4	Reserved			Yes	Set bit to 1'b
		3	CRC Slave Mode Enable				[1]: CRC Disable (No CRC Check) [0]: CRC Check ENABLE Note: With CRC check DISABLED register updates take immediate effect on high speed data path. With CRC check ENABLED register updates will NOT take effect until correct CRC value is loaded
		2:1	Reserved				Set bits to 00'b
		0	CRC Enable				Slave CRC Trigger
0x07	Digital Reset and Control	7	Reserved	R/W	0x01		Set bit to 0'b
		6	Reset Regs				Self clearing reset for registers Writing a [1] will return register settings to default values.
		5	Reset SMBus Master				Self clearing reset for SMBus master state machine
		4:0	Reserved				Set bits to 0001'b
0x08	Pin Override	7	Reserved	R/W	0x00		Set bit to 0
		6	Override Idle Threshold			Yes	[1]: Override by Channel - see Reg 0x13 and 0x19 [0]: SD_TH pin control
		5	Reserved			Yes	Set bit to 0'b
		4	Override IDLE			Yes	[1]: Force IDLE by Channel - see Reg 0x0E and 0x15 [0]: Normal Operation
		3	Reserved			Yes	Set bit to 0'b
		2	Reserved			Yes	Set bit to 0'b
		1	Override DEM			Yes	
		0	Reserved			Yes	Set bit to 0'b
0x0C	CH A Analog Override 1	7	Reserved	R/W	0x00		Set bit to 0'b
		6	Reserved				Set bit to 0'b
		5	Reserved				Set bit to 0'b
		4	Reserved				Set bit to 0'b
		3:0	Reserved				Set bits to 000'b
0x0D	CH A Reserved	7:0	Reserved	R/W	0x00		Set bits to 00'h

Table 8. SMBus Register Map (continued)

Address	Register Name	Bits	Field	Type	Default	EEPROM Reg Bit	Description
0x0E	CH A Idle Control	7:6	Reserved	R/W	0x00		set bits to 00'b
		5	Idle Auto			Yes	Auto IDLE value when override bit is set (reg 0x08 [4] = 1)
		4	Idle Select			Yes	Force IDLE value when override bit is set (reg 0x08 [4] = 1)
		3	Reserved			Yes	Set bit to 0'b
		2:0	Reserved				Set bits to 000'b
0x0F	CH A EQ Setting	7:0	BOOST [7:0]	R/W	0x2F	Yes	EQ Boost Default to 24 dB See Table 2 for Information
0x10	CH A Control 1	7	Sel_scp	R/W	0xED	Yes	1 = Short Circuit Protection ON 0 = Short Circuit Protection OFF
		6	Reserved			Yes	Set bit to 1'b
		5:3	Reserved			Yes	Set bits to = 101'b
		2:0	Reserved			Yes	Set bits to = 101'b
0x11	CH A Control 2	7:5	Reserved	R	0x82		Set bits to = 100'b
		4	Reserved	R/W			Set bit to 0
		3	Reserved				Set bit to 0
		2:0	DEM [2:0]			Yes	De-Emphasis (Default = -3.5 dB) 000'b = -0.0 dB 001'b = -1.5 dB 010'b = -3.5 dB 011'b = -6.0 dB 100'b = -8.0 dB 101'b = -9.0 dB 110'b = -10.5 dB 111'b = -12.0 dB
0x12	CH A Idle Threshold	7	Slow OOB	R/W	0x00	Yes	Slow OOB Enable (1); Disable (0)
		6:4	Reserved				Set bits to 000'b.
		3:2	idle_thA[1:0]			Yes	Assert Thresholds Use only if register 0x08 [6] = 1 00 = 180 mV (Default) 01 = 160 mV 10 = 210 mV 11= 190 mV
		1:0	idle_thD[1:0]			Yes	De-assert Thresholds Use only if register 0x08 [6] = 1 00 = 110 mV (Default) 01 = 100 mV 10 = 150 mV 11= 130 mV
0x13	CH B Analog Override 1	7	Reserved	R/W	0x00		Set bit to 0
		6	Reserved				Set bit to 0
		5	Reserved				Set bit to 0
		4	Reserved				Set bit to 0
		3:0	Reserved				Set bits to 0000'b
0x14	CH B Reserved	7:0	Reserved	R/W	0x00		Set bits to 00'h
0x15	CH B Idle Control	7:6	Reserved	R/W	0x00		Set bits to 00'b
		5	Idle Auto			Yes	Auto IDLE value when override bit is set (reg 0x08 [4] = 1)
		4	Idle Select			Yes	Force IDLE value when override bit is set (reg 0x08 [4] = 1)
		3:2	Reserved			Yes	Set bits to 00'b.
		1:0	Reserved				Set bits to 00'b.

Table 8. SMBus Register Map (continued)

Address	Register Name	Bits	Field	Type	Default	EEPROM Reg Bit	Description
0x16	CH B EQ Setting	7:0	BOOST [7:0]	R/W	0x2F	Yes	EQ Boost Default to 24 dB See Table 2 for Information
0x17	CH B Control 1	7	Sel_scp	R/W	0xED	Yes	1 = Short Circuit Protection ON 0 = Short Circuit Protection OFF
		6	Reserved			Yes	Set bit to 1'b
		5:3	Reserved			Yes	Set bits to = 101'b
		2:0	Reserved				Set bits to = 101'b
0x18	CH B Control 2	7:5	Reserved	R	0x82		Set bits to = 100'b
		4	Reserved	R/W			Set bit to 0'b
		3	Reserved				Set bit to 0'b
		2:0	DEM [2:0]			Yes	De-Emphasis (Default = -3.5 dB) 000'b = -0.0 dB 001'b = -1.5 dB 010'b = -3.5 dB 011'b = -6.0 dB 100'b = -8.0 dB 101'b = -9.0 dB 110'b = -10.5 dB 111'b = -12.0 dB
0x19	CH B Idle Threshold	7	Slow OOB	R/W	0x00	Yes	Slow OOB Enable (1); Disable (0)
		6:4	Reserved				Set bits to 000'b.
		3:2	IDLE_thA[1:0]			Yes	Assert Thresholds Use only if register 0x08 [6] = 1 00 = 180 mV (Default) 01 = 160 mV 10 = 210 mV 11 = 190 mV
		1:0	IDLE_thD[1:0]			Yes	De-assert Thresholds Use only if register 0x08 [6] = 1 00 = 110 mV (Default) 01 = 100 mV 10 = 150 mV 11 = 130 mV
0x23	BR111A CH A VOD	7:6	Reserved	R/W	0x00		Set bits to 0.
		4:2	VOD_CH0[2:0]			Yes	DS100BR111A VOD Controls for CH A (Default = 000'b) 000'b = 575 mV 001'b = 650 mV 010'b = 750 mV 011'b = 850 mV 100'b = 950 mV 101'b = 1050 mV 110'b = 1150 mV
		1:0	Reserved				Set bits to 00'b.
0x25	BR210A CH A VOD	7:5	Reserved	R/W	0xAD		Set bits to 101'b.
		4:2	VOD_CH0[2:0]			Yes	Set bits to 011'b.
		1:0	Reserved				Set bits to 01'b.
0x28	Idle Control	7	Reserved	R/W	0x00		
		6	Override Fast Idle			Yes	
		5:4	en_high_idle_th[1:0]			Yes	Enable high SD thresholds [5]: CH A [4]: CH B
		3:2	en_fast_idle[1:0]			Yes	Enable Fast Idle [3]: CH A [2]: CH B
		1:0	Reserved				Set bits to 00'b.

Table 8. SMBus Register Map (continued)

Address	Register Name	Bits	Field	Type	Default	EEPROM Reg Bit	Description
0x2D	CH B VOD Control	7:5	Reserved	R/W	0xAD		Set bits to 101'b.
		4:2	VOD_CH0[2:0]			Yes	VOD Controls for CH B (Default = 011'b) 000'b = 575 mV 001'b = 650 mV 010'b = 750 mV 011'b = 850 mV 100'b = 950 mV 101'b = 1050 mV 110'b = 1150 mV
		1:0	Reserved				Set bits to '01b
0x51	Device Information	7:5	Version[2:0]	R	0x87		Read bits = 100'b
		4:0	Device ID[4:0]				BR111A = '0 0111b

Typical DC Performance Characteristics

The following data was collected at 25°C

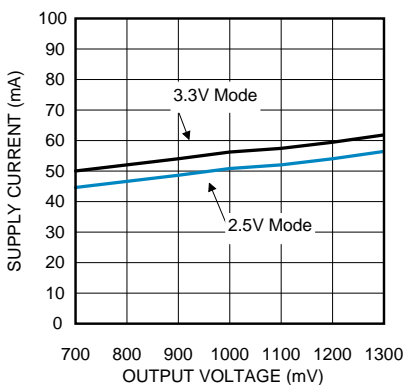


Figure 9. Supply Current vs. Output Voltage Setting

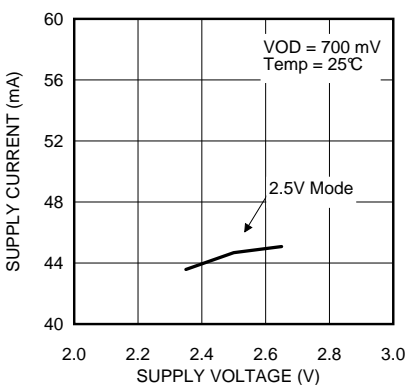


Figure 10. Supply Current vs. Supply Voltage

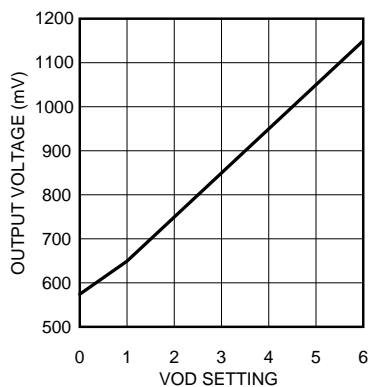


Figure 11. Output Voltage vs. Output Voltage Setting

Typical AC Performance Characteristics

NO MEDIA:

Device	Random Jitter (RJ)	Deterministic Jitter (DJ)	DJ Component Breakdown	Total Jitter (Tj @ 1E-12)
DS100BR111A @ 10.3125 Gbps	210 fs	10.0 ps	DDJ = 7.8 ps	12.9 ps
			DCD = 1.8 ps	
			DDPWS = 5.6 ps	
			PJ = 0.25 ps	

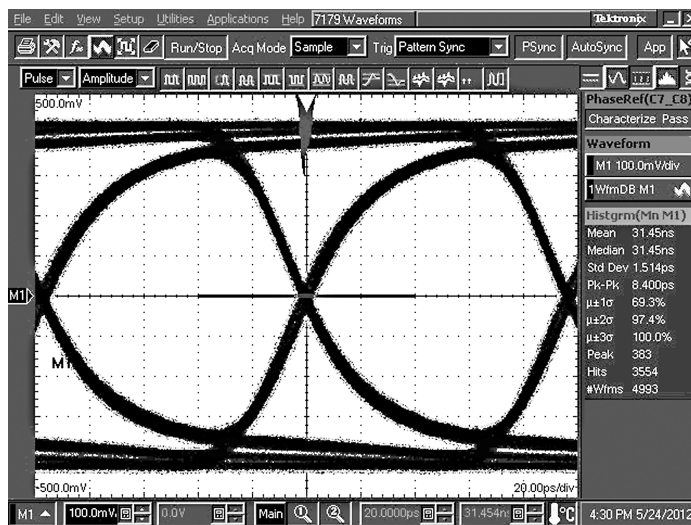


Figure 12. No Media; D3186 Driving Device Directly

The following lab setups were used to collect typical performance data on FR4 and Cable media.

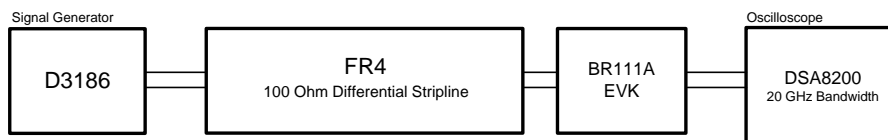


Figure 13. Equalization Test Setup for FR4

EQUALIZATION RESULTS:

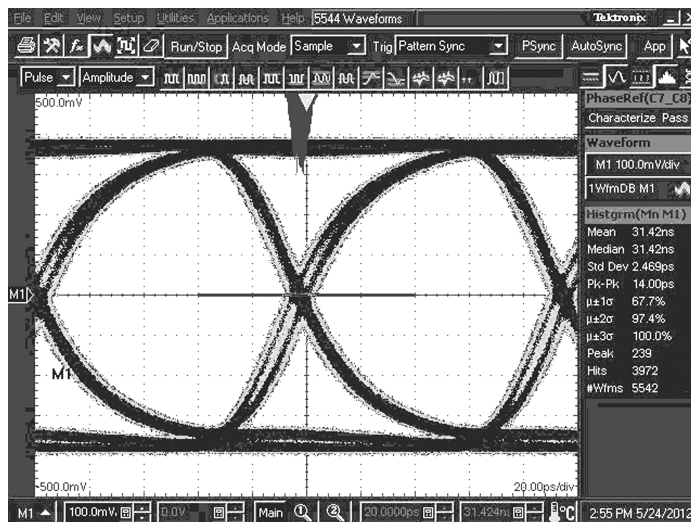


Figure 14. Equalization Performance with 30" of 4 mil FR4 Using EQ Setting 0x17

The following lab setups were used to collect typical performance data on FR4 and Cable media.

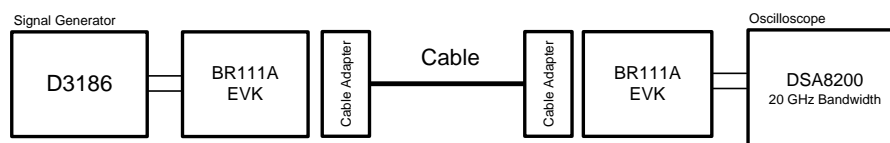


Figure 15. Equalization Test Setup for Cables

CABLE TRANSMIT and RECEIVE RESULTS:

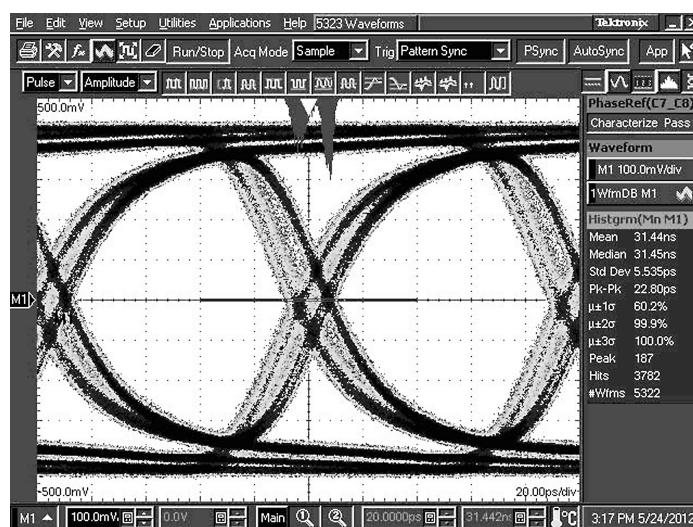


Figure 16. 8M 30AWG Cable Performance with 700mV Launch VOD and Rx EQ Setting 0x2B

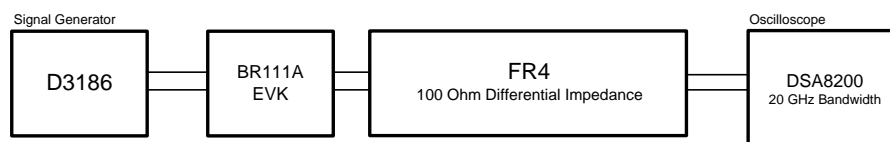


Figure 17. De-Emphasis Test Setup

DE-EMPHASIS RESULTS:

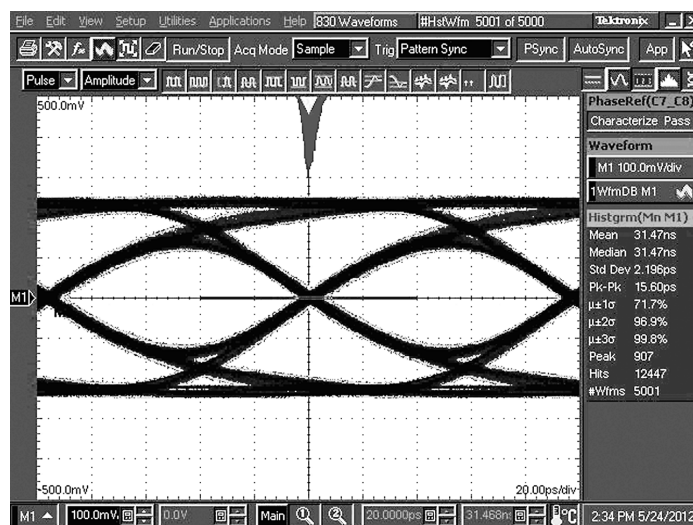


Figure 18. De-Emphasis Performance with 10" of 4 mil FR4 Using DE Setting 0x02

The following lab setups were used to collect typical performance data on FR4 and Cable media.



Figure 19. 10" of 4 mil FR4 Without De-Emphasis

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish	MSL Peak Temp (3)	Op Temp (°C)	Top-Side Markings (4)	Samples
DS100BR111ASQ/NOPB	ACTIVE	WQFN	RTW	24	1000	Green (RoHS & no Sb/Br)	CU SN	Level-3-260C-168 HR		BR111A	Samples
DS100BR111ASQE/NOPB	ACTIVE	WQFN	RTW	24	250	Green (RoHS & no Sb/Br)	CU SN	Level-3-260C-168 HR		BR111A	Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) Only one of markings shown within the brackets will appear on the physical device.

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TAPE AND REEL INFORMATION


*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
DS100BR111ASQ/NOPB	WQFN	RTW	24	1000	178.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1
DS100BR111ASQE/NOPB	WQFN	RTW	24	250	178.0	12.4	4.3	4.3	1.3	8.0	12.0	Q1

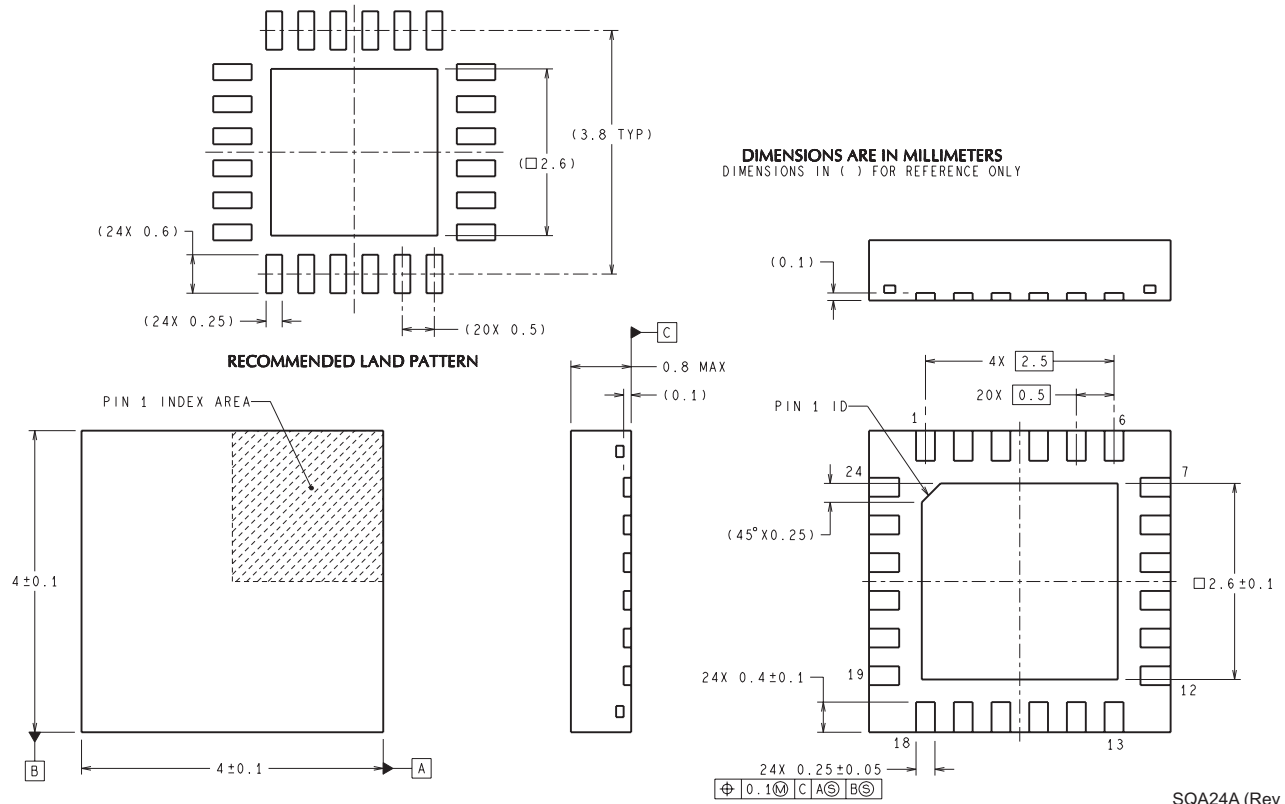
TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
DS100BR111ASQ/NOPB	WQFN	RTW	24	1000	213.0	191.0	55.0
DS100BR111ASQE/NOPB	WQFN	RTW	24	250	213.0	191.0	55.0

RTW0024A



SQA24A (Rev B)

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