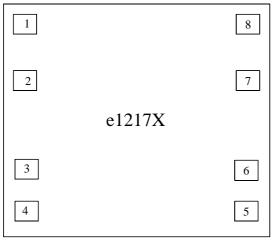


# 32-kHz Standard Watch CMOS IC

#### **Features**

- 32-kHz oscillator
- 1.3 V to 1.8 V operating-voltage range
- 180 nA typical current consumption
- Voltage regulator

## **Pad Configuration**



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Figure 1. Chip size 1.06 mm x 1.02 mm Pad size: 112 μm x 112 μm Pad window: 100 μm x 100 μm

- Integrated capacitors, mask selectable
- Mask options for pad designation, motor period and motor pulse width
- Low resistance outputs for bipolar stepping motor
- Motor fast-test function

## **General Description**

The e1217X is an integrated circuit in CMOS Silicon Gate Technology for analog watches. It consists of a 32-kHz oscillator, frequency dividers down to 1/64 Hz, output pulse formers and push-pull motor drivers. For tuning of the crystal, integrated capacitors are provided (selectable mask option). Low current consumption and high oscillator stability are enabled by an on-chip voltage regulator.

Pin	Symbol	Function				
1, 4	V <sub>SS</sub>	Negative supply voltage				
5, 6, 8	$V_{DD}$	Positive supply voltage				
1 to 4	OSCIN/	Oscillator input/output				
	OSCOUT					
(7/5) or (7/6)	MOT 1/2	Motor drive outputs				
1 to 5, 8	RESET	Reset input				
1 to 5, 8	TEST	Test input/output				

# **Absolute Maximum Ratings**

Parameters	Symbol	Value	Unit
Supply voltage	V <sub>SS</sub>	−0.3 to +5	V
Input voltage range, all inputs	V <sub>IN</sub>	$(V_{SS}-0.3 V_) \le V_{IN} \le (V_{DD} + 0.3 V)$	V
Output short circuit duration		indefinite	
Power dissipation (DIL package)	P <sub>tot</sub>	125	mW
Operating ambient temperature range	T <sub>amb</sub>	−20 to +70	°C
Storage temperature range	T <sub>stg</sub>	-40 to +125	°C
Lead temperature during soldering at 2 mm distance, 10 s	$T_{\rm sld}$	260	°C

Absolute maximum ratings define parameter limits which, if exceeded, may permanently change or damage the device.

All inputs and outputs on Atmel Wireless & Microcontrollers' circuits are protected against

electrostatic discharges. However, precautions to minimize the build-up of electrostatic charges during handling are recommended.

The circuit is protected against supply-voltage reversal for typically 5 minutes.

Rev. A2, 12-Dec-00



## **Functional Description**

### **Voltage Regulator**

An integrated voltage regulator provides the oscillator with a well controlled negative supply voltage  $V_{REG}$ . This improves the stability of the oscillator and keeps current consumption at a minimum.

#### Oscillator

An oscillator inverter with feedback resistor is provided for generation of the 32768 Hz clock frequency. A total capacitance of 24 pF is integrated. This can be selected for Coscout in 2 pF increments via a mask option.

### **Frequency Divider**

A 21-bit binary counter is provided, dividing the oscillator frequency down to 1/64 Hz. The leading six stages are connected to  $V_{DD}$  and  $V_{REG}$ , while the remaining 15 stages are connected to  $V_{DD}$  and  $V_{SS}$ .

### **Motor Drive Output**

The e1217X contains two push-pull output buffers for driving bipolar stepping motors. During a motor pulse, the n-channel device of one buffer and the p-channel device of the other buffer are activated. The p-channel devices of both buffers are active (figure 3) between two the pulses.

Cycle time and pulse width can be chosen via a metal-mask option (table1).

#### RESET

A debounced RESET input is provided. Connecting the RESET input to  $V_{DD}$  resets the low order 12 stages of the frequency divider, thus disabling further motor pulses. Motor pulses in progress when the reset function is applied are completed. After releasing the RESET pad from  $V_{DD}$ , the next motor pulse appears with a delay of one half motor cycle on the drive output opposed to the former (figure 4). Due to the debounce circuitry on the RESET input,  $V_{DD}$  must be applied for at least 31.2 ms. During RESET the input current is limited to 8 nA typically.

#### **Test**

A test frequency of 512 Hz is output to this pad which can be measured with a high resistance probe (R  $\geq$  10 M $\Omega$ , C  $\leq$  20 pF). This signal can be used for testing and tuning the oscillator. Connecting TEST to  $V_{DD}$  for at least 4 ms changes the motor cycle time from the selected value to the test cycle time (mask options), while the motor pulse width remains unchanged (figure 3).

This feature can be used to reduce the amount of time required for testing the mechanical parts of the watch.

Table 1 Motor options

Cycle time T <sub>M</sub>	= 2, 4, 6, 8, 10, 12, 20, 24, 30, 40, 60, 80, 120 s
Motor pulse width t <sub>M</sub>	= 0.98 to 14.65 ms in increments of 0.98 ms
Motor test cycle time T <sub>MT</sub>	= 250, 125, 62.5 ms

2 (5) Rev. A2, 12-Dec-00



# **Operating Characteristics**

 $V_{DD}$  = 0 V;  $V_{SS}$  = -1.55 V;  $T_{amb}$  = +25°C;  $C_{TR}$  = 15 pF, unless otherwise specified. All voltage levels are measured with reference to  $V_{DD}$ . Test crystal as specified below.

Parameters	Test Conditions / Pins	Symbol	Min.	Тур.	Max.	Unit				
Operating voltage	Functional test (figure 2)	V <sub>SS</sub>	-1.3		-1.8	V				
Operating current	$C_{\text{oscout}} = 16 \text{ pF}, R_{\text{L}} = \infty$	I <sub>SS</sub>	-180 -300			nA				
RESET input current	$RESET = V_{DD}$	I <sub>R</sub>		8		nA				
Motor outputs										
Motor output current	$R_L = 2 \text{ k}\Omega, V_{SS} = -1.55 \text{ V}$	I <sub>M</sub>	± 0.7			mA				
Motor period		T <sub>M</sub>		S						
Motor pulse width		T <sub>M</sub>	S	ms						
Motor test period		T <sub>MT</sub>		ms						
Oscillator	Oscillator									
Stability	$\Delta V_{SS} = 100 \text{ mV},$ $C_{TR} = 5 \text{ pF},$	Δf/f		0.1		ppm				
Start-up voltage	Startup within 2 s	V <sub>ST</sub>	-1.3			V				
Integrated input capacitor		C <sub>OSC IN</sub>	See option list			pF				
Integrated output capacitor	$C_{OSCOUTmax} = 24 \text{ pF}$	C <sub>OSC</sub> OUT	See option list			pF				

Note 1: Typical parameters represent the statistical mean values

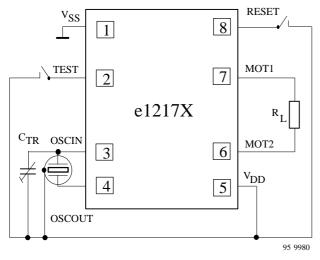


Figure 2. Functional test circuit

Range of trimmer capacitance:

 $C_{TR} = 5 pF \text{ to } 30 pF$ 

### **Test Crystal Specification**

 $\begin{array}{ll} \mbox{Frequency} & \mbox{f} = 32768 \mbox{ Hz} \\ \mbox{Series resistance} & \mbox{R}_S = 30 \mbox{ k}\Omega \\ \mbox{Static capacitance} & \mbox{C}_0 = 1.5 \mbox{ pF} \\ \mbox{Dynamic capacitance} & \mbox{C}_1 = 3 \mbox{ fF} \\ \mbox{Load capacitance} & \mbox{C}_L = 8 \mbox{ pF} \\ \end{array}$ 

#### **Additional Notes**

- 1. It is recommended to connect the quartz case to  $V_{DD}$  (by conductive epoxy).
- 2. Capacitive coupling of TEST to OSCIN must be minimized by appropriate layout of the PCB to avoid disturbance of the oscillator.

Rev. A2, 12-Dec-00 3 (5)



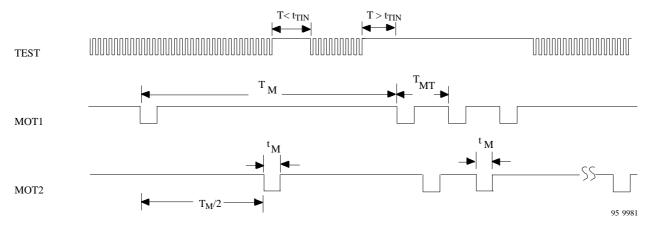


Figure 3. Motor drive outputs in normal mode and motor test

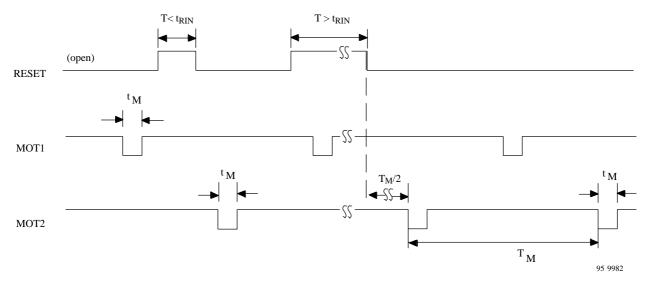


Figure 4. Motor drive outputs and RESET

4 (5) Rev. A2, 12-Dec-00



Table 2 Option list e1217X-

Option	Motor			Integrated Capacitance*)									
	Cycle (T <sub>M</sub> )	Pulse (t <sub>M</sub> ) ms	Test (T <sub>MT</sub> ) ms	C <sub>OSCIN</sub> pF	C <sub>OSCOUT</sub> pF	Pad 1	Pad 2	Pad 3	Pad 4	Pad 5	Pad 6	Pad 7	Pad 8
-В	2	3.9	125	2	14	V <sub>SS</sub>	TEST	OSCIN	OSC- OUT	V <sub>DD</sub>	мот2	MOT1	RESET
-E	2	6.8	125	2	14	V <sub>SS</sub>	TEST	OSCIN	OSC- OUT	V <sub>DD</sub>	мот2	MOT1	RESET
-I	2	7.8	125	2	14	V <sub>SS</sub>	TEST	OSCIN	OSC- OUT	V <sub>DD</sub>	MOT2	MOT1	RESET
-S	2	5.9	125	2	14	V <sub>SS</sub>	TEST	OSCIN	OSC- OUT	$V_{\mathrm{DD}}$	мот2	MOT1	RESET
-VA	2	4.9	62.5	4	14	V <sub>SS</sub>	TEST	OSC- OUT	OSCIN	$V_{\mathrm{DD}}$	мот2	MOT1	RESET
-VB	2	4.9	125	4	14	OSCIN	OSC- OUT	RESET	V <sub>SS</sub>	TEST	мот2	MOT1	V <sub>DD</sub>
-VC	40	5.9	125	2	14	OSCIN	OSC- OUT	RESET	V <sub>SS</sub>	TEST	мот2	MOT1	V <sub>DD</sub>
-VE	2	5.9	62.5	2	14	OSC- OUT	OSCIN	V <sub>DD</sub>	V <sub>SS</sub>	TEST	мот2	MOT1	RESET
-VF	2	3.9	62.5	4	14	OSCIN	OSC- OUT	RESET	V <sub>SS</sub>	мот2	VDD	MOT1	TEST
-VH	2	3.9	62.5	4	14	V <sub>SS</sub>	TEST	OSC- OUT	OSCIN	$V_{\mathrm{DD}}$	мот2	MOT1	RESET
-WB	2	4.9	125	4	14	V <sub>SS</sub>	TEST	OSCIN	OSC- OUT	$V_{\mathrm{DD}}$	мот2	MOT1	RESET
-WG	20	5.9	125	2	14	V <sub>SS</sub>	TEST	OSCIN	OSC- OUT	$V_{\mathrm{DD}}$	мот2	MOT1	RESET
-WH	40	6.8	62.5	2	14	V <sub>SS</sub>	TEST	OSCIN	OSC- OUT	V <sub>DD</sub>	мот2	MOT1	RESET

<sup>\*)</sup> On-chip stray capacitance included

### We reserve the right to make changes to improve technical design and may do so without further notice.

Parameters can vary in different applications. All operating parameters must be validated for each customer application by the customer. Should the buyer use Atmel Wireless & Microcontrollers products for any unintended or unauthorized application, the buyer shall indemnify Atmel Wireless & Microcontrollers against all claims, costs, damages, and expenses, arising out of, directly or indirectly, any claim of personal damage, injury or death associated with such unintended or unauthorized use.

Data sheets can also be retrieved from the Internet: http://www.atmel-wm.com

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Rev. A2, 12-Dec-00 5 (5)