

# LINEAR INTEGRATED CIRCUITS

## PRELIMINARY DATA

### PUSH-PULL FOUR CHANNEL DRIVERS

The L293 and the L293E are monolithic integrated high voltage, high current four channel drivers in dual in-line plastic package with 16 leads and 20 leads respectively. They are designed to accept standard DTL or TTL input logic levels and drive inductive loads (such as relays, solenoids, DC and stepping motors) and switching power transistors.

Both are provided of complementary push-pull output stage, two inhibit inputs (which disable two channels each), and an additional supply inputs so that the logic circuitry may run at a lower voltage to reduce power dissipation.

In the L293E the emitters of the lower transistors of each push-pull stage are not internally grounded and the corresponding pins can be used for the connection of an external sensing resistor, making very easy switch-mode current control.

The main features of the L293 and of the L293E are:

- 1A output current capability per channel
- 2A peak output current (non-repetitive) per channel
- Inhibit facility
- Overtemperature protection
- Logical "O" input voltage up to 1.5V (high noise immunity).

The devices are assembled in new packages which have the four central pins connected together and used for heatsinking and grounding.

#### ABSOLUTE MAXIMUM RATINGS

| V,              | Supply voltage   | 36         | V  |
|-----------------|--|------------|----|
| V <sub>ss</sub> | Logic supply voltage                                       | 36         | v  |
| Vi              | Input voltage  | 7          | v  |
| Vinh            | Inhibit voltage  | 7          | V  |
| lout            | Peak output current (non-repetitive)                       | 2          | Α  |
| Ptot            | Total power dissipation at $T_{ground-pins} = 80^{\circ}C$ | 5          | W  |
| $T_{stg},T_{j}$ | Storage and junction temperature                           | -40 to 150 | °C |

### ORDERING NUMBERS: L293B (16 leads)

L293E (20 leads)

### MECHANICAL DATA







## CONNECTION AND BLOCK DIAGRAM (L293) (top view)





## CONNECTION AND BLOCK DIAGRAM (L293E) (top view)









L293 L298E



## THERMAL DATA

| R <sub>th i-case</sub> | Thermal resistance junction-case    | max | 14 | °C/W |
|------------------------|-------------------------------------|-----|----|------|
| R <sub>th j-amb</sub>  | Thermal resistance junction-ambient | max | 80 | °C/W |

## **ELECTRICAL CHARACTERISTICS** (For each channel, $V_S = 24V$ , $V_{SS} = 5V$ , $T_{amb} = 25^{\circ}$ C, unless otherwise specified)

|                      | Parameter                                   | Test conditions                              | Min. | Тур. | Max.            | Unit |
|----------------------|---|--|------|------|-----------------|------|
| Vs                   | Supply voltage                              |  |      |      | 36              | v    |
| V <sub>ss</sub>      | Logic supply voltage                        |  | 4.5  |      | 36              | V    |
| ۱ <sub>s</sub>       | Total quiescent supply                      | $V_i = L$ $I_o = 0$ $V_{inh} = H$            |      | 2    | 6               |      |
|                      | current                                     | $V_i = H$ $I_o = 0$ $V_{inh} = H$            |      | 16   | 24              | mA   |
|                      |   | V <sub>inh</sub> = L                         |      |      | 4               |      |
| ۱ <sub>ss</sub>      | Total quiescent logic                       | $V_i = L$ $I_o = 0$ $V_{inh} = H$            |      | 44   | 60              |      |
|                      | supply current                              | $V_i = H$ $I_o = 0$ $V_{inh} = H$            |      | 16   | 22              | mA   |
|                      |   | V <sub>inh</sub> = L                         |      | 16   | 24              |      |
| Vi∟                  | Input low voltage                           |  | -0.3 |      | 1.5             | V    |
| ViH                  | Input high voltage                          | V <sub>ss</sub> ≤ 7V                         | 2.3  |      | V <sub>ss</sub> |      |
|                      |   | $V_{ss} > 7V$                                | 2.3  |      | 7               | ľ    |
| I <sub>iL</sub> .    | Low voltage input current                   | V <sub>i</sub> = L                           |      |      | -10             | μA   |
| Чн                   | High voltage input current                  | V <sub>j</sub> = H                           |      | 30   | 100             | μA   |
| V <sub>inhL</sub>    | Inhibit low voltage                         |  | -0.3 |      | 1.5             | V    |
| V <sub>inhH</sub>    | Inhibit high voltage                        | V <sub>ss</sub> ≤ 7V                         | 2.3  |      | V <sub>ss</sub> |      |
|                      |   | . V <sub>ss</sub> > 7V                       | 2.3  |      | 7               | 1 °  |
| linh∟                | Low voltage inhibit current                 |  |      | -30  | -100            | μA   |
| linhH                | High voltage inhibit<br>current             |  |      |      | ± 10            | μA   |
| V <sub>CEsat</sub> H | Source output saturation voltage            | I <sub>0</sub> = 1A                          |      | 1,4  | 1.8             | V    |
| V <sub>CEsatL</sub>  | Sink output saturation voltage              | I <sub>o</sub> = -1A                         |      | 1.2  | 1.8             | V    |
| VSENS                | Sensing Voltage<br>(pins 4, 7, 14, 17) (**) |  |      |      | 2               | V    |
| t <sub>r</sub>       | Rise time                                   | 0.1 to 0.9 V <sub>o</sub> (*)                |      | 250  |                 | ns   |
| t <sub>f</sub>       | Fall time                                   | 0.9 to 0.1 V <sub>o</sub> (*)                |      | 250  |                 | ns   |
| ton                  | Turn-on delay                               | 0.5 V <sub>i</sub> to 0.5 V <sub>o</sub> (*) |      | 450  |                 | ns   |
| toff                 | Turn-off delay                              | 0.5 V <sub>i</sub> to 0.5 V <sub>o</sub> (*) |      | 200  |                 | ns   |

(\*) See fig. 1.

(\*\*) Referred to L293E.



## TRUTH TABLE

| V <sub>i</sub> (each channel) | v <sub>o</sub> | V <sub>inh.</sub> (°°) |
|-------------------------------|----------------|------------------------|
| н                             | н              | н                      |
| L                             | L              | н                      |
| н                             | X (°)          | L                      |
| L                             | X (°)          | L                      |

(°) High output impedance.

(°°) Relative to the considerate channel.

#### Fig. 1 - Switching times



## Fig. 2 - Saturation voltage vs. output current



 $\begin{array}{c|c} \textbf{rature} & & & & & & \\ \hline v_{CE \, satH} & & & & & & & \\ (v) & & & & & & & & \\ & & & & & & & & \\ & & & & & & & \\ & & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & \\ & & & & & & & & & \\ & & & & & & & & & \\ & & & & & & & & & \\ & & & & & & & & & \\ & & & & & & & & & \\ & & & & & & & & & \\ & & & & & & & & & \\ & & & & & & & & & \\ & & & & & & & & & \\ & & & & & & & & & \\ & & & & & & & & & \\ & & & & & & & & & & \\ & & & & & & & & & & \\ & & & & & & & & & & \\ & & & & & & & & & & \\ & & & & & & & & & & \\ & & & & & & & & & & \\ & & & & & & & & & \\ & & & & & & & & &$ 

Io=0.5A

1.0= 0.1 A

100 Tamb(\*C)

Fig. 3 - Source saturation

voltage vs. ambient tempe-

#### Fig. 4 – Sink saturation voltage vs. ambient temperature





50

0

1

0

- 50



## Fig. 7 - Output voltage vs. inhibit voltage



Fig. 5 – Quiescent logic supply current vs. logic supply voltage





## APPLICATION INFORMATION

Fig. 8 - DC motor controls (with connection to ground and to the supply voltage)



| V <sub>inh</sub> | A | М1                         | в | M2                         |
|------------------|---|----------------------------|---|----------------------------|
| н                | н | Fast motor<br>stop         | н | Run                        |
| н                | L | Run                        | L | Fast motor<br>stop         |
| L                | × | Free running<br>motor stop | × | Free running<br>motor stop |
|                  |   |                            |   |                            |

L = Low H = High X = Don't care

#### Fig. 9 – Bidirectional DC motor control



|                                 | INPUTS       | FUNCTION                   |  |
|---------------------------------|--------------|----------------------------|--|
|                                 | C = H; D = L | Turn right                 |  |
| V <sub>inh</sub> = H            | C = L; D = H | Turn left                  |  |
|                                 | C = D        | Fast motor stop            |  |
| V <sub>inh</sub> ≠ L            | C = X; D = X | Free running<br>motor stop |  |
| L = Low H = High X = Don't care |              |                            |  |

#### Fig. 10 - Bipolar stepping motor control



D1 - D8 = 1N4001



## APPLICATION INFORMATION (continued)

Fig. 11 - Stepping motor driver with phase current control and short circuit protection



D1 : D0 : 0.5A has alones (114-001 of equivalent).

# NOTE – For a more detailed description of the L293/L293E and its applications, refer to SGS-TECHNICAL NOTE TN.150.

### MOUNTING INSTRUCTIONS

The  $R_{thj-amb}$  of the L293 and the L293E can be reduced by soldering the GND pins to a suitable copper area of the printed circuit board or to an external heatsink.

The diagram of fig. 13 shows the maximum dissipable power  $P_{tot}$  and the  $R_{thj-amb}$  as a function of the side " $\ell$ " of two equal square copper areas having a thickness of 35  $\mu$  (see fig. 12). In addition, it is possible to use an external heatsink (see fig. 14).

During soldering the pins temperature must not exceed 260°C and the soldering time must not be longer than 12 seconds.

The external heatsink or printed circuit copper area must be connected to electrical ground.













