Monolithic Digital IC

**LB1877M** 



## Brushless Motor Driver with Speed Control for Portable Cassette Recorders

### Overview

The LB1877M is a motor driver well suited for driving motors of minicassette recorders, headphone stereos, and microcasette recorders that use a 3V power supply.

## **Package Dimensions**

unit: mm

#### 3036B-MFP20



## **Functions and Features**

- Brushless sensorless motor drive (3-phase half-wave drive)
- Forward/reverse drive possible
- Built-in speed control function (voltage servo)
- Built-in reference voltage (0.9V)
- · Soft switching

## **Specifications**

#### Absolute Maximum Ratings at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Maximum supply voltage	V <sub>CC</sub> max		6.0	V
Maximum output current	IO max		0.5	А
Allowable power dissipation	Pd max		0.5	W
Operating temperature	Topr		-10 to +80	°C
Storage temperature	Tstg		-40 to +150	°C

#### Allowable Operating Ranges at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Power supply voltage	V <sub>CC</sub>		1.8 to 5.0	V

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# Electrical Characteristics at Ta = $25^{\circ}$ C, V<sub>CC</sub> = 2.4V

Parameter	Symbol	Conditions	Ratings			Unit	Measuremen
	Symbol		min	typ	max	Unit	circuit
Power supply current	ICC1	S/S pin High level		4.0		mA	1
	ICC2	S/S pin Low level (standby)			20	μΑ	2
[S/S pin]							
S/S pin High level	SSH	Start	1.5		V <sub>CC</sub>	V	3
S/S pin Low level	SSL	Stop	0		0.3	V	4
[DR pin]		•					
DR pin High level	DRH	Reverse	1.5		V <sub>CC</sub>	V	9
DR pin Low level	DRL	Normal direction	0		0.3	V	10
[Internal reference voltage]	1	1	· · ·				
Internal reference voltage	VREF	Output current 0 µA	0.8	0.9	1.0	V	11
Output current	IREF	Output current 250 µA			25	mV/250 μA	12
Reference voltage to power supply	$\Delta VREF/\Delta V_{CC}$	V <sub>CC</sub> = 1.8 to 5.0V			5	mV/V	13
voltage characteristics							
Reference voltage to temperature	∆IREF/∆Ta	$V_{CC} = 2.4V$	- 0.1		0.3	mV/°C	Target
characteristics							
[OSC pin]		1	11				
Charge current	Isc		3.0	4.5	6.0	μA	14
[COM pin]		1	1				
Sink current	ICOM		17	24	33	μA	15
[LB pin]		1	1 1				1
Charge current	ILB		4.5	6.5	9.0	μA	16
[VSP pin]		1	11				
Input voltage range	VIN	$V_{CC} = 2.4V$	0.15		1.8	V	17
Speed signal detection precision	VSP	$V_{CC} = 2.4V$ VIN = 1V	420	500	580	mV	18
Speed signal relative precision	RSP		- 6		6	%	Target
Speed signal to power supply	$\Delta VSP/\Delta V_{CC}$	V <sub>CC</sub> = 1.8 to 5.0V			2.5	mV/V	19
voltage characteristics							
Speed signal to temperature	∆VSP/∆Ta		- 0.1		0.2	mV/°C	Target
characteristics							
[IN+ pin]		l	1				
Input voltage range	VIN+	$V_{CC} = 2.4 V$	0.1		V <sub>CC</sub> - 0.7	V	20
[OUT pin]			1		00		1
Output current	IOUT	VIN+ = 1V	25	30	47.3	μA	21
[RI pin]						•	
Current detection precision	VRI	$RI = 10 k\Omega U$ , V, Wout = 2.3V	10	20	35	mV	22
[U, V, WOUT pins]	1	1 , , -		_	_		1
Output saturation voltage	Vsat	IO = 200 mA			0.25	V	23
[Thermal]		1					-
Thermal protection trigger temperature	TTSD			180		°C	Target
Temperature hysteresis width	ATTSD			15		°C	Target

Note: Items shown to be Target are not measured.



## **Pin Function**

Pin number	Pin name	Function
20	UOUT	U-phase output
1	VOUT	V-phase output
2	WOUT	W-phase output
6	UB	U-phase base of 3-phase differential
5	VB	V-phase base of 3-phase differential
4	WB	W-phase base of 3-phase differential
18	VCC	Power supply
7	OSC	Startup oscillator pin
8	COM	Output waveform detection comparator voltage
3	P – GND	Output transistor and predriver ground
9	GND	Ground pin
11	S/S	Start/stop pin
19	DR	Forward/reverse pin
12	VREF	Reference voltage 0.9V
14	VSP	Output waveform peak detection pin
13	IN+	Error amp non-inverted pin
15	OUT	Error amp output pin
10	RI	Current feedback resistor connection pin
16	FC	Frequency response adjustment pin
17	LB	Motor start lockup prevention. Connect to GND via capacitor

## **Pin Assignment**





#### **Pin Description**

Unit (resistance:  $\Omega$ , capacitance: F)

Pin Desc	-			Unit (resistance: $\Omega$ , capacitance: F
Pin number		Pin voltage	Equivalent circuit	Pin function
18	VCC	1.8V to 5.0V		Power supply for all circuits
9	GND			Ground for all circuits except
				FC and power block.
12	VREF	0.7V to 0.9V		Internal reference voltage.
				Connected as speed control
				voltage to IN+ pin via external
				resistor.
			<b>↓ ↓ ↓ 50k</b>	
			A SOK	
			$\frac{1}{m}$ $\frac{1}{m}$ $\frac{1}{m}$ $\frac{1}{m}$	
7	OSC	1V to Vcc		Startup oscillator pin.
				Adjusts self-excitation
				frequency via external
			₹200	capacitor.
8	COM	1.3V to Vcc	To comparator input	Determines threshold voltage
Ŭ	001	1.00 10 000		of waveform detection circuit.
			10k (8)	Connected to Vcc via an
				external resistor.
			∧ ∧ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓	Varies the startup threshold
			≥ 20k ≥ 20k ≥ 20k	voltage.
14	VSP	0.1V to		Peak detection circuit output
14	VOI	Vcc – 0.7V		pin.
				P
13	IN+			Error amplifier non-inverted
				pin.
				Controls rotation speed via
			T I I I I	input pin voltage.
15	OUT		Drive	Error amplifier output pin.
				Connect external resistor
				between Vsp pins for
				feedback.
			Current feedback circuit	
10	RI			Current feedback output pin.
			∠+K_     ∠ . ]         ¤	Connect external resistor
			ि । । । । । । । 10k ≰ धुः	between this pin and ground
				for current feedback
				adjustment.
			(13) (15) (10)	,

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Continued from				Unit (resistance: Ω, capacitance: F
Pin number P 16	Pin name FC	Pin voltage	Equivalent circuit	Pin function
10	FC	Voltage input not allowed	Drive current $6k \neq 3S \neq 2k$ To RI pin $76$	Frequency characteristics adjustment pin. Connect to ground via capacitor.
11	S/S	0 to Vcc		Start/stop pin.
			50k \$ 50k	
19	DR	0 to Vcc	50k≹ ₹50k 19 777 777	Forward/reverse rotation pin.
20	UOUT	0 to 8V		U, V, W phase output pins.
1	VOUT			Connect to motor coils
2	WOUT			
17	LB	0 to 1V		Motor start lockup prevention
3 F	P – GND			Power block ground.

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Pin number	Pin name	Pin voltage	Equivalent circuit	Pin function
4	WB	Voltage	- <b>+ + + +</b>	Base pins for U, V, W
5	VB	input not		differential.
6	UB	allowed		Connect to ground via
				capacitor for soft switching

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