LB1996



Three-Phase Brushless Motor Driver for CD-ROM Spindle Drive

Overview

The LB1996 is a 3-phase brushless motor driver especially suited for CD-ROM spindle motor drives.

Functions

- Current linear drive
- Control V type amplifier
- Separate power supply for output upper side bias circuit allows low output saturation by boosting this power supply only (useful for 5V power supply types).
- Upper side current detection technique reduces loss voltage of current detection resistor. Voltage effect of this resistor reduces internal power dissipation of IC.
- Built-in short braking circuit
- Built-in reverse blocking circuit
- Hall FG output
- Built-in S/S function
- Built-in current limiter circuit
- Built-in Hall power supply
- Built-in thermal shutdown circuit
- 1 Hall FG/3 Hall FG switchable

Package Dimensions

unit: mm **3227-HSOP24**





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Specifications

Maximum Ratings at Ta = $25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Power supply voltage	V _{CC} 1 max		7.0	V
	V _{CC} 2 max		14.4	V
	V _{CC} 3 max		14.4	V
Applied output voltage	V _O max		14.4	V
Applied intput voltage	V _{IN} max		V _{CC} 1	V
Output current	I _O max		1.3	А
Allowable power dissipation	Pd max	IC only	0.8	W
		with substrate (114.3 x 76.1 x 1.6 mm ³ , glass exposy)	1.9	W
Operating temperature	Topr		-20 to +75	°C
Storage temperature	Tstg		–55 to +150	°C

Operating Conditions at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Power supply voltage	V _{CC} 1		4 to 6	V
	V _{CC} 2	$\geq V_{CC}1$	4 to 13.6	V
	۷ _{CC} 3		4 to 13.6	V

Sample Application at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
12V type	V _{CC} 1	Regulated voltage	4 to 6	V
	$V_{CC}^2 = V_{CC}^3$	Unregulated voltage	4 to 13.6	V
5V type	$V_{CC}1 = V_{CC}3$	Regulated voltage	4 to 6	V
	V _{CC} 2	Boost-up voltage or regulated voltage (Note)	4 to 13.6	V

Note: When boost-up voltage is used at V_{CC}^2 , output can be set to low-saturation.

Electrical Characteristics at Ta = 25° C, V_{CC}1 = 5V, V_{CC}2 = V_{CC}3 = 12V

Parameter	Symbol	Conditions	Ratings			Unit
	0,11201		min	typ	max	
[Power supply current]	-					
Power supply current	I _{CC} 1	V _C = V _{CREF}		8		mA
	I _{CC} 2	V _C = V _{CREF}		0		mA
	I _{CC} 3	V _C = V _{CREF}		150	250	μA
Output idle current	I _{CC} 10Q	$V_{S/S} = 0V$			200	μA
	I _{CC} 2OQ	$V_{S/S} = 0V$			30	μA
	I _{CC} 3OQ	$V_{S/S} = 0V$			30	μA
[Output]						
Saturation voltage, upper side 1	V _{OU} 1	$I_{O} = -0.5A, V_{CC}1 = 5V, V_{CC}2 = V_{CC}3 = 12V$		1.0		V
lower side 1	V _{OD} 1	$I_{O} = 0.5A, V_{CC}1 = 5V, V_{CC}2 = V_{CC}3 = 12V$		0.3		V
Saturation voltage, upper side 2	V _{OU} 2	$I_{O} = -0.5A, V_{CC}1 = V_{CC}3 = 5V, V_{CC}2 = 12V$		0.3		V
lower side 2	V _{OD} 2	$I_{O} = 0.5A, V_{CC}1 = V_{CC}3 = 5V, V_{CC}2 = 12V$		0.3		V
Current limiter setting voltage	V _{CL}	$R_{RF} = 0.43\Omega$		0.37		V
[Hall amplifier]						
Common mode input voltage range	V _{HCOM}		1.2		V _{CC} -1.0	V
Input bias current	I _{HIB}			1		μA
Minimum Hall input level	V _{HIN}		60			mV _{P-P}
[S/S pin]						
High level voltage	V _{S/SH}		2.0		V _{CC} 1	V
Low level voltage	V _{S/SL}				0.7	V
Input current	I _{S/SI}	$V_{S/S} = 5V$			200	μA
Leak current	I _{S/SL}	$V_{S/S} = 0V$	-30			μA
[Control]						
V _C pin input current	I _{VC}	$V_{C} = V_{CREF} = 2.5V$		1		μA
V _{CREF} pin input current	IVCREF	$V_{C} = V_{CREF} = 2.5V$		1		μA
Voltage gain	GV _{CO}	$\Delta V_{RF} / \Delta V_{C}$		0.25		times
Startup voltage	V _{CTH}	V _{CREF} = 2.5V	2.35		2.65	V
Startup voltage width	ΔV_{CTH}	V _{CREF} = 2.5V	50		150	mV
[Hall power supply]						
Hall power supply voltage	V _H	I _H = 5 mA		0.8		V
Allowable current	Ι _Η		20			mA
[Thermal shutdown]						
Operating temperature	T _{TSD}	Design target value	150	180	210	°C
Hysteresis	ΔT_{TSD}	Design target value		15		°C
[Short braking]						
Brake pin at High level	V _{BRH}		4		5	V
Brake pin at Low level	V _{BRL}		0		1	V
[1 Hall FG/3 Hall FG switching]						
FG _{SEL} pin at High level	V _{FSH}		4		5	V
FG _{SEL} pin at Low level	V _{FSL}		0		1	V

Note:

• During S/S OFF (standby), the Hall comparator is at High.

• Items shown to be design target values are not measured.

Truth Table

	Source -> Sink		Hall input	Control	
	Source -> Sirik	U	V	W	V _C
1	Phase W -> Phase V	н	н		н
1	Phase V -> Phase W			-	L
2	Phase W -> Phase U	н	L	1	Н
-	Phase U -> Phase W			-	L
3	Phase V -> Phase W	1	L	н	н
5	Phase W -> Phase V	-			L
4	Phase U -> Phase V	1	н	1	Н
-	Phase V -> Phase U	L			L
5	Phase V -> Phase U	Н	1	Н	Н
Ĵ	Phase U -> Phase V		Ľ	11	L
6	Phase U -> Phase W	L	н	н	Н
0	Phase W -> Phase U				Ĺ

Input:

H: Input 1 is higher in potential than input 2 by at least 0.2V.

L: Input 1 is lower in potential than input 2 by at least 0.2V.

Pin Assignment



Block Diagram



Sample Application Circuit



Power supply - GND Output - GND Between Hall inputs

Capacitor requirements may change depending on motor. For some motors, capacitor between Hall inputs may not be needed.

Pin Descriptions

Pin number	Pin name	Pin voltage	Equivalent circuit	Pin function
3	V _{CC} 2	4V to 13.6V		Source side predrive voltage supply pin
4	V _{CC} 3	4V to 13.6V		Constant current control amplifier voltage supply pin
6	V _{CC} 1	4V to 6V		Power supply pin for all circuits except output transistors, source predriver, and constant current control amplifier
14	RS		100μA VCC1 100μA (14)(15)	Reverse detector pin Forward rotation: High Reverse rotation: Low
15	FG		A11172	1 Hall element or 3 Hall elements waveform Schmitt comparator combined output
8 7	U _{IN} 1 U _{IN} 2		ν _{CC1}	U phase Hall element input and reverse detector U phase Schmitt comparator input pin Logic High indicates $U_{IN}1 > U_{IN}2$.
10 9	V _{IN} 1 V _{IN} 2	1.2V to V _{CC} 1–1V		V phase Hall element input and reverse detector V phase Schmitt comparator input pin Logic High indicates V _{IN} 1 > V _{IN} 2.
12 11	W _{IN} 1 W _{IN} 2		25µA (↓) (↓) 25µA ////////////////////////////////////	W phase Hall element input and reverse detector W phase Schmitt comparator input pin Logic High indicates W _{IN} 1 > W _{IN} 2.
13	V _H		Vcc1 75μA 30kΩ 2kΩ 2kΩ 75μA 13 A11174	Hall element lower side bias voltage supply pin
17	S/S	0V to V _{CC} 1	V _{CC} 1 17 √ 50kΩ ≥ 17 √ Λ11175	When this pin is at 0.7V or lower, or when it is open, all circuits are inactive. When driving motor, set this pin to 2V or higher.
18	SIG GND			GND pin for all circuits except output
20	FC		V _{CC} 1	Control loop frequency compensa- tor pin. Connecting a capacitor between this pin and GND prevents closed loop oscillation in current limiting circuitry.

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Pin number	Pin name	Pin voltage	Equivalent circuit	Pin function
21	V _{CREF}	2V to 3V	25μA 25μA 25μA 200Ω 25μA 200Ω 21	Control reference voltage supply pin. Determines control start voltage.
22	Vc	0V to V _{CC} 1	30kΩ 15kΩ 100μA 100μA 100μA 100μA 100μA 100μA	Speed control voltage supply pin V type control technique $V_C > V_{CREF}$: Forward $V_C < V_{CREF}$: Slowdown (Reverse-blocking circuit prevents reverse rotation.)
	14/		A11177	
23	W _{OUT} PWR GND			W phase output
24				Output transistor GND
1	V _{OUT} U _{OUT}			V phase output U phase output
2	COUT			Upper side output NPN transistor
5	RF		3.9Ω 	collector pin (common for all 3 phases). For current detection, connect resistor between V_{CC} 3 pin and RF pin. Constant current control and current limiter works by detecting this voltage.
19	FG _{SEL}		75kΩ 19 50kΩ 411179	3 Hall FG/1 Hall FG switching pin FG _{SEL} High -> 3 Hall FG Low/Open -> 1 Hall FG
16	BRAKE		100μA 75kΩ 100μA 50kΩ 100μA 10	Short brake pin BRAKE: High -> Short brake operation Low/Open -> Motor drive operation

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