# MILITARY/HIGH-REL PRODUCTS PROCESSED TO MIL-STD 883, METHOD 5004, CLASS B 2048 x 8 Bit Static RAM MKB4802(P/J/E)-81/83

#### FEATURES

- Static operation
- D Organization: 2K x 8 bit RAM JEDEC pinout
- □ Pin compatible with Mostek's BYTEWYDE<sup>™</sup> memory family
- □ Double density version of the MKB4118 1K x 8 static RAM
- □ 24/28 pin ROM/PROM compatible pin configuration
- □ CE and OE functions facilitate bus control
- □ -55°C to 125°C operating temperature

## DESCRIPTION

The MKB4802 uses Mostek's Scaled POLY 5<sup>™</sup> process and advanced circuit design techniques to package 16,384 bits of static RAM on a single chip. Static operation is achieved



#### TRUTH TABLE

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ĈĒ	ŌĒ	WE	Mode	DQ				
⊻ін	×	×	Deselect	High Z				
VIL	×	VIL	Write	D <sub>IN</sub>				
VIL	VIL	VIH	Read	DOUT				
VIL	VIH	VIH	Read	High Z				

#### X = Don't Care

□ High performance

**PIN CONNECTIONS** 

Part No.	Access Time	R∕W Cycle Time
MKB4802-81	120 nsec	120 nsec
MKB4802-83	200 nsec	200 nsec

with high performance and low power dissipation by utilizing Address Activated<sup>™</sup> circuit design techniques.

The MKB4802 series presents to the user a high density cost effective N-MOS memory with the performance charac-

Figure 2			
A7 1 A6 2 A5 3 A4 4 A3 5 A2 6 A1 7 A0 8 D00 9 D0110 D0211 Vss12	224 V 233 A 222 A 21 W 200 19 A 18 C 17 D 16 D 15 D 14 D 13 D	LEADLESS CHIP CARRIER (EPAK) TOP VIEW (450 mil x 550 mil JEDEC type E)	9 30 30 30 30 30 30 30 30 30 30

## **PIN NAMES**

A <sub>0</sub> -A <sub>10</sub> CE V <sub>SS</sub> DQ <sub>0</sub> -DQ	Address Inputs Chip Enable Ground 7Data In/Data Out	V <sub>CC</sub> WE OE	Power (+5 V) Write Enable Output Enable
	/		

## **ABSOLUTE MAXIMUM RATINGS\***

Voltage on any pin relative to V <sub>SS</sub>	
Operating Temperature T <sub>A</sub> (Ambient)	55°C to +125°C
Storage Temperature (Ambient)	65°C to +150°C
Power Dissipation	1 Watt
Output Current	
*Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stra-	

operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

# **RECOMMENDED D.C. OPERATING CONDITIONS8**

 $(-55^{\circ}C \le T_A \le +125^{\circ}C)$ 

SYM	PARAMETER	MIN	ΤΥΡ	MAX	UNITS	NOTES
v <sub>cc</sub>	Supply Voltage	4.75	5.0	5.25	V	1
V <sub>SS</sub>	Supply Voltage	0	0	0	V	1
V <sub>IH</sub>	Logic "1" Voltage All Inputs	2.4		V <sub>CC</sub> + .5 V	V	1
V <sub>IL</sub>	Logic "0" Voltage All Inputs	-0.3		.65	V	1,10

#### DC ELECTRICAL CHARACTERISTICS<sup>1,8</sup>

 $(-55^{\circ}C \le T_A \le +125^{\circ}C) (V_{CC} = 5.0 \text{ volts} \pm 5\%)$ 

SYM	PARAMETER	MIN	MAX	UNITS	NOTES
I <sub>CC1</sub>	Average V <sub>CC</sub> Power Supply Current		120	mA	9
I <sub>CC1</sub>	Average $V_{CC}$ Power Supply Current (T <sub>A</sub> = 125°C)		90	mA	9, 11
I <sub>IL</sub>	Input Leakage Current (Any Input)	-10	10	μΑ	2
I <sub>OL</sub>	Output Leakage Current	-10	10	μA	2
V <sub>он</sub>	Output Logic "1" Voltage I <sub>OUT</sub> = -1 mA	2.4		v	
V <sub>OL</sub>	Output Logic "0" Voltage I <sub>OUT</sub> = 4 mA		0.4	V	

## AC ELECTRICAL CHARACTERISTICS<sup>1,8</sup>

 $(-55^{\circ}C \le T_{A} \le +125^{\circ}C) (V_{CC} = +5.0 \text{ volts} \pm 5\%)$ 

SYM	PARAMETER	ТҮР	MAX	NOTES
C <sub>I</sub>	Capacitance on all pins (except D/Q)	4 pF		6
C <sub>D/Q</sub>	Capacitance on D/Q pins	10 pF		6,7

#### **ELECTRICAL CHARACTERISTICS**<sup>3,4</sup>

(-55°C  $\leq$  T<sub>A</sub>  $\leq$  +125°C) (V<sub>CC</sub> = 5.0 volts  $\pm$  5%)

SYM	PARAMETER	MKB4	MKB4802-81		MKB4802-83		
		MIN	MAX	MIN	MAX	UNITS	NOTES
t <sub>RC</sub>	Read Cycle Time	120		200		ns	
t <sub>AA</sub>	Address Access Time		120		200	ns	5
t <sub>CEA</sub>	Chip Enable Access Time		60		100	ns	5
t <sub>CEZ</sub>	Chip Enable Data Off Time	5	35	5	35	ns	
t <sub>OEA</sub>	Output Enable Access Time		60		100	ns	5
t <sub>OEZ</sub>	Output Enable Data Off Time	5	35	5	35	ns	
t <sub>AZ</sub>	Address Data Off Time	10		10		ns	
t <sub>WC</sub>	Write Cycle Time	120		200		ns	
t <sub>AS</sub>	Address Setup Time	0	1	0		ns	see text
t <sub>AH</sub>	Address Hold Time	40		65		ns	see text
t <sub>DSW</sub>	Data To Write Setup Time	10		20		ns	
t <sub>DHW</sub>	Data From Write Hold Time	10		10		ns	
t <sub>WD</sub>	Write Pulse Duration	45		60		ns	see text
twez	Write Enable Data Off Time	5	35	5	35	ns	
	Write Pulse Lead Time	65		130		ns	

#### NOTES:

- 1. All voltages referenced to VSS. 2. Measured with .4  $\leq$  VI  $\leq$  5.0 V, outputs deselected and VCC = 5 V.
- 3. AC measurements assume Transition Time = 5 ns; levels VSS to 3.0 V.
- 4. Input and output timing reference levels are at 1.5 V.
- 5. Measured with a load as shown in Figure 3.
- 6. Effective capacitance calculated from the equation  $C = \Delta Q$  with  $\Delta V = 3$  volts and power supplies at nominal levels. and power supplies at nominal levels.
- 7. Output buffer is deselected.
- 8. A minimum of 2 ms time delay is required after application of V<sub>CC</sub> (+5 V) before proper device operation can be achieved.
- 9. I<sub>CC1</sub> measured with outputs open.
- 10. Negative undershoots to a minimum of -1.5 V are allowed with a maximum of 50 ns pulse width. DC value of low level input must not exceed -0.3 V.
- 11. Power supply current decreases with increasing temperature.





TIMING DIAGRAM



teristics necessary for today's high performance microprocessor applications. The MKB4802 is ideal for memory applications where the organization requires relatively shallow depth with a wide word format.

The MKB4802 features a fast  $\overline{\text{CE}}$  (50% of Address Access) function to permit memory expansion without impacting system access time. A fast  $\overline{\text{OE}}$  (50% of access time) is included to permit data interleaving for enhanced system performance.

The MKB4802 is pin compatible with Mostek's BYTEWYDE™ Memory Family of RAMs, ROMs and EPROMs.

#### OPERATION

#### **READ MODE**

The MKB4802 is in the READ MODE whenever the Write Enable Control Input (WE) is in the high state. In the READ mode of operation, the MKB4802 provides a fast address ripple-through access of data from 8 of 16,384 locations in the static storage array. Thus, the unique address specified by the 11 Address Inputs (A<sub>n</sub>) define which 1 of 2048 bytes of data is to be accessed.

A transition on any of the 11 address inputs will disable the 8 Data Output Drivers after  $t_{AZ}$ . Valid Data will be available to the 8 Data Output Drivers within  $t_{AA}$  after the last address input signal is stable, providing that the  $\overline{CE}$  and  $\overline{OE}$  access time are satisfied. If  $\overline{CE}$  or  $\overline{OE}$  access times are not met, data access will be measured from the limiting parameter ( $t_{CEA}$  or  $t_{OEA}$ ) rather than the address. The state of the 8 data I/O signals is controlled by the Chip Enable ( $\overline{CE}$ ) and Output Enable ( $\overline{OE}$ ) control signals.

#### WRITE MODE

The MKB4802 is in the Write Mode whenever the Write Enable ( $\overline{\text{WE}}$ ) and Chip Enable ( $\overline{\text{CE}}$ ) control inputs are in the low state.

The WRITE cycle is initiated by the  $\overline{WE}$  pulse going low provided that  $\overline{CE}$  is also low. The leading edge of the  $\overline{WE}$ pulse is used to latch the status of the address bus.

NOTE: In a write cycle the latter occurring edge of either  $\overline{WE}$  or  $\overline{CE}$  will determine the start of the write cycle. Therefore,  $t_{AS'}, t_{WD}$  and  $t_{AH}$  are referenced to the latter occurring edge of  $\overline{CE}$  or  $\overline{WE}$ . Addresses are latched at this time. All write cycles whether initiated by  $\overline{CE}$  or  $\overline{WE}$  must be terminated by the rising edge of  $\overline{WE}$ . If the output bus has been enabled ( $\overline{CE}$  and  $\overline{OE}$  low) the  $\overline{WE}$  will cause the output to go to the high Z state in  $t_{WE7}$ .

Data In must be valid  $t_{DSW}$  prior to the low to high transition of  $\overline{WE}$ . The Data In lines must remain stable for  $t_{DHW}$  after  $\overline{WE}$  goes inactive. The write control of the MKB4802 disables the data out buffers during the write cycle; however,  $\overline{OE}$  should be used to disable the data out buffers to prevent bus contention between the input data and data that would be output upon completion of the write cycle.