OKI semiconductor MSM82C53-5RS/GS/JS MSM82C53-2RS/GS/JS

CMOS PROGRAMMABLE INTERVAL TIMER

GENERAL DESCRIPTION

The MSM82C53-5RS/GS/JS and MSM82C53-2RS/GS/JS are programmable universal timers designed for use in microcomputer systems. Based on silicon gate CMOS technology, it requires a standby current of only 100 μ A (max.) when the chip is in the nonselected state. During timer operation, power consumption is still very low with only 5 mA (max.) at 5 MHz of current required.

The devices consist of three independent counters, and can count up to a maximum of 5 MHz (MSM82C53-5) and 8 MHz (MSM82C53-2). The timer features six different counter modes, and binary count/BCD count functions. Count values can be set in byte or word units, and all functions are freely programmable.

FEATURES

- Maximum operating frequency of 5 MHz (MSM82C53-5)
- Maximum operating frequency of 8 MHz (MSM82C53-2)
- High speed and low power consumption achieved
- through silicon gate CMOS technology. • Completely static operation
- Three independent 16-bit down-counters
- 3V to 6V single power supply

- Six counter modes available for each counter
- Binary and decimal counting possible
- 24-pin DIP (MSM82C53-5RS/MSM82C53-2RS)
- 32-pin flat package (MSM82C53-5GS/MSM82C53-2GS)
- 28-pin PLCC Package (MSM82C53-5JS/MSM82C53-2JS)



FUNCTIONAL BLOCK DIAGRAM

PIN CONFIGURATION



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ABSOLUTE MAXIMUM RATINGS

			Limits				
Parameter	Symbol	Conditions	MSM82C53-5RS MSM82C53-2RS	MSM82C53-5GS MSM82C53-2GS	MSM82C53-5J5 MSM82C53-2JS	Unit	
Ssupply Voltage	Vcc			-0.5 to +7		v	
Input Voltage	∨ _{IN}	Respect to GND	Respect to GND -0.5 to V _{cc} + 0.5				
Output Voltage	VOUT]	-	0.5 to V _{cc} + 0	.5	v	
Storage Temperature	Tstg			- 55 to + 150		°C	
Power Dissipation	PD	Ta = 25°C	0.9	0.7	0.9	w	

OPERATING RANGES

Parameter	Symbol	Limits	Conditions	Unit
Supply Voltage	Vcc	3 to 6	VIL = 0.2V, VIH = VCC - 0.2V, operating frequency 2.6 MHz	v
Operating Temperature	Тор	-40 to +85		°C

RECOMMENDED OPERATING CONDITIONS

Parameter	Symbol	Min.	Тур.	Max.	Unit
Supply Voltage	Vcc	4.5	5	5.5	v
Operating Temperature	ТОР	-40	+25	+85	°C
"L" Input Voltage	VIL	-0.3		+0.8	v
"H" Input Voltage	VIH	2.2		V _{CC} + 0.3	v

DC CHARACTERISTICS

Parameter	Symbol	Cond	itions	Min.	Тур.	Max.	Unit
"L" Output Voltage	VOL	IOL = 4mA				0.45	v
"H" Output Voltage	∨он	IOH = -1mA		3.7			v
Input Leak Current	ILI.	0 S VIN S VCC	V _{CC} =4.5V to 5.5V	-10		10	μA
Output Leak Current	1LO	0 ≤ VOUT ≤ VCC	Ta=-40°C to +85°C	-10		10	μA
Standby Supply Current	Iccs	$\frac{\overline{CS} \ge V_{CC} - 0.2V}{V_{IH} \ge V_{CC} - 0.2V}$ $V_{IL} \le 0.2V$				100	μA
Operating Supply Current	100	tCLK = 200 ns CL = 0pF				5	mA
	'cc	t _{CLK} = 125 ns CL = 0pF	MSM82C53-2		1	8	mA

AC CHARACTERISTICS

 $(V_{CC} = 4.5V \sim 5.5V, T_a = -40 \sim +85^{\circ}C)$

		MSM8	2C53-5	MSM8	2C53-2			
Parameter	Symbol	Min.	Ma×.	Min.	Max.	Unit	Co	nditions
Address Set-up Time before reading	TAR	30		30		ns		C _L = 150pF
Address Hold Time after reading	TRA	0		0		ns	Read	
Read Pulse Width	TRR	150		150		ns	cycle	
Read Recovery Time	TRVR	200		200		ns	1	
Address Set-up Time before writing	TAW	0		0		ns		
Address Hold Time after writing	TWA	30		20		ns		
Write Pulse Width	TWW	150		150		ns	Write	
Data Input Set-up Time before writing	TDW	100		100		ns	cycle	
Data Input Hold Time after writing	TWD	30		20		ns		
Write Recovery time	TRVW	200		200		ns		
Clock Cycle Time	TCLK	200	D.C.	125	D.C.	ns		
Clock "H" Pulse Width	трун	60		60		ns]	
Clock "L" Pulse Width	TPWL	60		60		ns	Clock	
"H" Gate Pulse Width	TGW	50		50		ns	and gate	
"L" Gate Pulse Width	TGL	50		50		ns	timing	
Gate Input Set-up Time before clock	TGS	50		50		ns	-	
Gate Input Hold Time after clock	TGH	50		50		ns		
Output Delay Time after reading	TRD		120		120	ns		
Output Floating Delay Time after reading	TDF	5	90	5	90	ns		
Output Delay Time after gate	TODG		120		120	ns	Delay time	
Output Delay Time after clock	TOD		150		150	ns	1	
Output Delay Time after address	TAD		180		180	ns	1	

Note: Timing measured at $V_L = 0.8V$ and $V_H = 2.2V$ for both inputs and outputs.

TIME CHART

Write Timing



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Read Timing

Clock & Gate Timing



Pin Symbol	Name	Input/output	Function
D7 ~ D0	Bidirectional data bus	Input/output	Three-state 8-bit bidirectional data bus used when writing control words and count values, and reading count values upon reception of WR and RD signals from CPU.
ĊŚ	Chip select input	Input	Data transfer with the CPU is enabled when this pin is at low level. When at high level, the data bus $(D_0 \text{ thru } D_7)$ is switched to high impedance state where neither writing nor reading can be executed. Internal registers, however, remain unchanged.
RD	Read input	Input	Data can be transferred from MSM82C53 to CPU when this pin is at low level.
WR	Write input	Input	Data can be transferred from CPU to MSM82C53 when this pin is at low level.
A0, A1	Address input	Input	One of the three internal counters or the control word regis- ter is selected by A0/A1 combination. These two pins are normally connected to the two lower order bits of the address bus.
CLK0~2	Clock input	Input	Supply of three clock signals to the three counters incorporated in MSM82C53.
GATE0~2	Gate input	Input	Control of starting, interruption, and restarting of counting in the three respective counters in accordance to the set con- trol word contents.
OUT0~2	Counter output	Output	Output of counter output waveform in accordance with the set mode and count value.

DESCRIPTION OF PIN FUNCTIONS

SYSTEM INTERFACING



DESCRIPTION OF BASIC OPERATIONS

Data transfers between the internal registers and the external data bus is outlined in the following table.

cs	RD	WR	A1	ÅO	Function
0	1	0	0	0	Data bus to counter #0 Writing
0	1	0	0	1	Data bus to counter # 1 Writing
0	1	0	1	0	Data bus to counter # 2 Writing
0	1	0	1	1	Data bus to control word register Writing
0	0	1	0	0	Data bus from counter # 0 Reading
0	0	1	0	1	Data bus from counter # 1 Reading
0	0	1	1	0	Data bus from counter # 2 Reading
0	0	1	1	1)
1 [/]	×	×	×	×	 Data bus in high impedance status
0	1	1	x	×]]

x denotes "not specified".

DESCRIPTION OF OPERATION

82C53 functions are selected by a control word from the CPU. In the required program sequence, the control word setting is followed by the count value setting and execution of the desired timer operation.

Control Word and Count Value Program

Each counter operation mode is set by control word programming. The control word format is outlined below.

D7	DĢ	D5	D4	D3	D2	D1	D0
SC1	SC0	RL1	RLO	M2	M1	МО	BCD
	Select Counter		Read/Load		Mode		
	(CS = 0, A0, A1 = 1,1, RD = 1, WR = 0)						

Select Counter (SCO, SC1): Selection of set counter

SC1	SC0	Set Contents
0	0	Counter # 0 selection
0	1	Counter #1 selection
1	0	Counter # 2 selection
1	1	Illegal combination

 Read/Load (RL1, RL0): Count value Reading/ Loading format setting

RL1	RLO	Set Contents
0	0	Counter Latch operation
0	1	Reading/Loading of Least Significant byte (LSB)
1	0	Reading/Loading of Most Significant byte (MSB)
1	1	Reading/Loading of LSB followed by MSB

Mode (M2, M1, M0): Operation waveform mode setting

M2	M1	MO	Set Contents
0	0	0	Mode 0 (Interrupt on Terminal Count)
0	0	1	Mode 1 (Programmable One-Shot)
×	1	0	Mode 2 (Rate Generator)
×	1	1	Mode 3 (Square Wave Generator)
1	0	0	Mode 4 (Software Triggered Strobe)
1	0	1	Mode 5 (Hardware Triggered Strobe)

x denotes "not specified".

BCD: Operation count mode setting

BCD	Set Contents
0	Binary Count (16-bits Binary)
1	BCD Count (4-decades Binary Coded Decimal)

After setting Read/Load, Mode, and BCD in each counter as outlined above, next set the desired count value. (In some Modes, counting is started immediately after the count value has been written). This count value setting must conform with the Read/Load format set in advance. Note that the internal counters are reset to OOOOH during control word setting. The counter value (OOOOH) can.t be read.

If the two bytes (LSB and MSB) are written at this stage (RLO and RL1 = 1,1), take note of the following precaution.

Although the count values may be set in the three counters in any sequence after the control word has been set in each counter, count values must be set consecutively in the LSB - MSB order in any one counter.

Example of control word and count value setting

Counter # 0: Read/Load LSB only, Mode 3, Binary count, count value 3H
Counter # 1: Read/Load MSB only, Mode 5, Binary count, count value AA00H
L Counter # 2: Read/Load LSB and MSB, Mode 0, BCD count, count value 1234
MVI A, 1EH OUT n3 Counter #0 control word setting
MVI A, 6AH OUT n3 Counter #1 control word setting
MVI A, B1H OUT n3 Counter #2 control word setting
MVI A, 03H Counter #0 count value setting
MVI A, AAH OUT n1 Counter #1 count value setting

OUT n1 Generating MVI A, 34H OUT n2 Counter #2 count value setting MVI A, 12H (LSB then MSB)

MVI A, 12H (LSB then MSB) OUT n2

- Note: n0: Counter #0 address
 - n1: Counter #1 address
 - n2: Counter #2 address
 - n3: Control word register address
- The minimum and maximum count values which can be counted in each mode are listed below.

Mode	Min.	Max.	Remarks
0	1	0	0 executes 10000H count (ditto in other modes)
1	1	0	
2	2	0	1 cannot be counted
3	2	1	1 executes 10001H count
4	1	0	
5	1	0	. (c

Mode Definition

Mode 0 (terminal count)

The counter output is set to "L" level by the mode setting. If the count value is then written in the counter with the gate input at "H" level (that is, upon completion of writing the MSB when there are two bytes), the clock input counting is started. When the terminal count is reached, the output is switched to "H" level and is maintained in this status until the control word and count value are set again.

Counting is interrupted if the gate input is switched to "L" level, and restarted when switched back to "H" level.

When Count Values are written during counting, the operation is as follows:

- 1 byte Read/Load.... When the new count value is written, counting is stopped immediately, and then restarted at the new count value by the next clock.
- 2-byte Read/Load.... When byte 1 (LSB) of the new count value is written, counting is stopped immediately. Counting is restarted at the new count value when byte 2 (MSB) is written.

Mode 1 (programmable one-shot)

The counter output is switched to "H" level by the mode setting. Note that in this mode, counting is not started if only the count value is written. Since counting has to be started in this mode by using the leading edge of the gate input as a trigger, the counter output is switched to "L" level by the next clock after the gate input trigger. This "L" level status is maintained during the set count value, and is switched back to "H" level when the terminal count is reached.

Once counting has been started, there is no interruption until the terminal count is reached, even if the gate input is switched to "L" level in the meantime. And although counting continues even if a new count value is written during the counting, counting is started at the new count value if another trigger is applied by the gate input.

Mode 2 (rate generator)

The counter output is switched to "H" level by the mode setting. When the gate input is at "H" level, counting is started by the next clock after the count value has been written. And if the gate input is at "L" level, counting is started by using the rising edge of the gate input as a trigger after the count value has been set.

An "L" level output pulse appears at the counter output during a single clock duration once every n clock inputs where n is the set count value. If a new count value is written during while counting is in progress, counting is started at the new count value following output of the pulse currently being counted. And if the gate input is switched to "L" level during counting, the counter output is forced to switch to "H" level, the counting being restarted by the rising edge of the gate input.

Mode 3 (square waveform rate generator)

The counter output is switched to "H" level by the mode setting. Counting is started in the same way as described for mode 2 above.

The repeated square wave output appearing at the counter output contains half the number of counts as the set count value. If the set count value (n) is an odd number, the repeated square wave output consists of only (n + 1)/2 clock inputs at "H" level and (n - 1)/2 clock inputs at "L" level.

If a new count value is written during counting, the new count value is reflected immediately after the

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change ("H" to "L" or "L" to "H") in the next counter output to be executed. The counting operation at the gate input is done the same as in mode 2.

Mode 4 (software trigger strobe)

The counter output is switched to "H" level by the mode setting. Counting is started in the same way as described for mode 0. A single "L" pulse equivalent to one clock width is generated at the counter output when the terminal count is reached.

This mode differs from 2 in that the "L" level output appears one clock earlier in mode 2, and that pulses are not repeated in mode 4. Counting is stopped when the gate input is switched to "L" level, and restarted from the set count value when switched back to "H" level.

Mode 5 (hardware trigger strobe)

The counter output is switched to "H" level by the mode setting. Counting is started, and the gate input used, in the same way as in mode 1.

The counter output is identical to the mode 4 output.

The various roles of the gate input signals in the above modes are summarized in the following table.

Gate	"L" Level Falling Edge	Rising Edge	"H" Level
0	Counting not possible		Counting possible
1		 (1) Start of counting (2) Retriggering 	
2	 Counting not possible Counter output forced to "H" level 	Start of counting	Counting possible
3	(1) Counting not possible(2) Counter output forced to "H" level	Start of counting	Counting possible
4	Counting not possible		Counting possible
5		(1) Start of counting(2) Retriggering	







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Reading of Counter Values

All 82C53 counting is down-counting, the counting being in steps of 2 in mode 3. Counter values can be read during counting by (1) direct reading, and (2) counter latching ("read on the fly").

Direct reading

Counter values can be read by direct reading operations.

Since the counter value read according to the timing of the \overline{RD} and CLK signals is not guaranteed, it is necessary to stop the counting by a gate input signal, or to interrupt the clock input temporarily by an external circuit to ensure that the counter value is correctly read.

Counter latching

In this method, the counter value is latched by writing a counter latch command, thereby enabling a stable value to be read without effecting the counting in any way at all. An example of a counter latching program is given below.

Counter latching executed for counter #1 (Read/ Load 2-byte setting)

MVI A	01 <u>00</u> ××××	
	Denotes counter latching	

- OUT n3 ------ Write in control word address (n3) ----- The counter value at this point is latched

MOV B, A	Reading of MSB from counter
IN n1	#1.
MOV C, A	#1.

Example of Practical Application

• 82C53 used as a 32-bit counter.



Use counter #1 and counter #2

Counter	#1:		0,	upper	order	16-bit	counter
Counter	#2:	value mode	2,	lower	order	16-bit	counter
		value					1

This setting enables counting up to a maximum of 2^{32} .