TOSHIBA BIPOLAR LINEAR INTEGRATED CIRCUIT SILICON MONOLITHIC

# TA7288P

#### DUAL BRIDGE DRIVER

The TA7288P is a bridge driver that is ideal for normal / reverse switching.

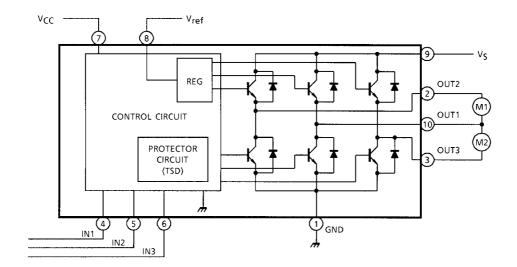
This circuit offers four modes: normal rotation, reverse rotation, stop, and brake.

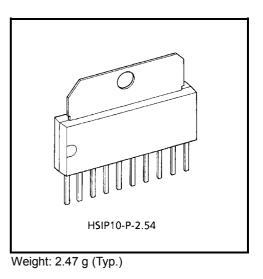
The output current is 1.0 A (AVE.) and 2.0 A (PEAK). TA7288P has an ideal circuit configuration for VCR front tape loading and offers two types of power supply pins. One is for output, the other for control. The  $V_{ref}$  pin on the output side used to control the motor voltage facilitates motor voltage adjustment. The IC requires little input current, enabling direct connection with CMOS.

#### FEATURES

- 4 Modes Available (CW / CCW / STOP / BRAKE)
- Output Current Up to 1.0 A (AVE.) and 2.0 A (PEAK)
- Wide Range of Operating Voltage: V<sub>CC</sub> (opr.) = 4.5~18 V
  - $V_{S (opr.)} = 0 \sim 18 V$ Vref (opr.) = 0 ~ 18 V
- Build in Thermal Shutdown, Over Current Protector and Punch-Through Current Restriction Circuit.
- Hysteresis for All Inputs.

#### **BLOCK DIAGRAM**

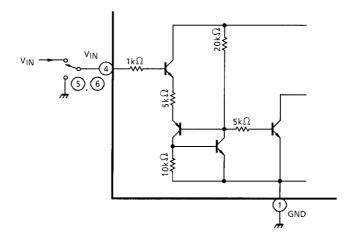




#### **PIN FUNCTION**

PIN No.	SYMBOL	FUNCTIONAL DESCRIPTION			
1	GND	GND terminal			
2	OUT2	Output terminal			
3	OUT3	Output terminal			
4	IN1	Input terminal			
5	IN2	Input terminal			
6	IN3	Input terminal			
7	V <sub>CC</sub>	Supply voltage terminal for Logic			
8	V <sub>ref</sub>	Supply voltage terminal for control			
9	VS	Supply voltage terminal for Motor drive			
10	OUT1	Output terminal			

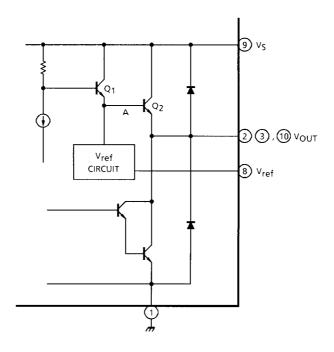
#### **INPUT CIRCUIT**



Input terminals of pin (4), (5) and pin (6) are all high active type and have a hysteresis of 0.7 V (Typ.) 5  $\mu$ A type of source mode input current is required.

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#### **OUTPUT CIRCUIT**



Output voltage is controlled by Vref voltage. Relationship between VOUT and Vref is VOUT = VBE ( $\approx 0.7)$  + Vref

V<sub>ref</sub> terminal required to connect to VS terminal for stable operation in case of no requirement of VOUT control.

#### **FUNCTION**

INPUT			OUTPUT			MODE		
IN1	IN2	IN3	OUT1	OUT2	OUT3	M1	M2	
0	0	1/0	L	L	L	BRAKE	BRAKE	
1	0	0	н	L	8	CW / CCW	STOP	
1	0	1	L	н	8	CCW / CW	STOP	
0	1	0	Н	8	L	STOP	CW / CCW	
0	1	1	L	8	Н	STOP	CCW / CW	
1	1	1/0	L	L	L	BRAKE	BRAKE	

∞: High impedance

Note: Inputs are all high active type.

#### MAXIMUM RATINGS (Ta = 25°C)

CHARACTERISTIC		SYMBOL	RATING	UNIT
Supply Voltage	V <sub>CC</sub>	25	V	
Motor Drive Voltage		VS	25	V
Reference Voltage		V <sub>ref</sub>	25	V
Output Current	PEAK	I <sub>O (PEAK)</sub>	2.0 (Note 1)	А
	AVE.	IO (AVE.)	1.0	А
Power Dissipation		PD	12.5 (Note 2)	W
Operating Temperature		T <sub>opr</sub>	-30~75	°C
Storage Temperature		T <sub>stg</sub>	-5~150	°C

Note 1: Duty 1 / 10, 100 ms

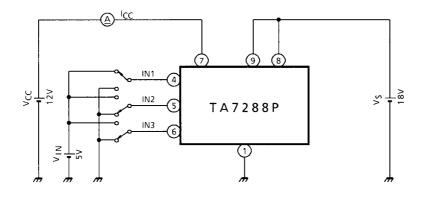
Note 2: Tc = 25°C

#### ELECTRICAL CHARACTERISTICS (Unless otherwise noted, Ta = 25°C, V<sub>CC</sub> = 12 V, V<sub>S</sub> = 18 V)

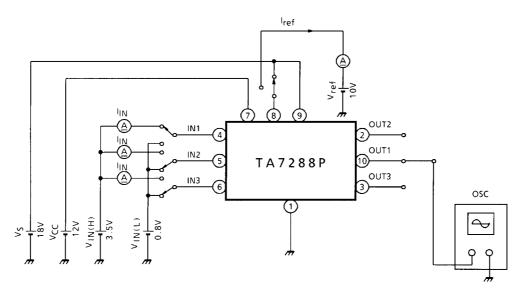
CHARACTERISTIC		SYMBOL	TEST CIR- CUIT	TEST CONDITION	MIN	TYP.	MAX	UNIT	
Supply Current		I <sub>CC1</sub>	1	Output OFF CW / CCW mode — 17		17	30	mA	
		I <sub>CC2</sub>	1	Output OFF Brake mode	_	13	25	ША	
Input Voltage	1 (High)	V <sub>IN (H)</sub>	2	T <sub>j</sub> = 25°C pin (4), (5), (6) 3.5		_	5.5	V	
	2 (Low)	V <sub>IN (L)</sub>	2	T <sub>j</sub> = 25°C pin (4), (5), (6)	GND	_	0.8	v	
Input Current		I <sub>IN</sub>	2	V <sub>IN</sub> = 3.5 V, Sink mode	—	5	20	μA	
Input Hysteresis Voltage		$\Delta V_T$	2	—	—	0.7	_	V	
Saturation Voltage	Upper	V <sub>SATU-1</sub>	3	$V_{ref} = V_S, V_S - V_{out},$ $I_O = 0.2 A$	_	0.9	1.2	V	
	Lower	V <sub>SATL-1</sub>	3	$V_{ref} = V_S, V_{out}$ -GND, I <sub>O</sub> = 0.2 A	_	1.0	1.3	V	
	Upper	V <sub>SATU-2</sub>	3	$V_{ref} = V_S, V_S - V_{out},$ $I_O = 1.0 A$	_	1.3	1.6	V	
	Lower	V <sub>SATL-2</sub>	3	$V_{ref} = V_S, V_{out}$ -GND I <sub>O</sub> = 1.0 A	_	1.8	2.5	V	
Output Voltage		V <sub>SATU-1</sub> '	3	V <sub>ref</sub> = 10 V, V <sub>out</sub> -GND I <sub>O</sub> = 0.5 A	10.7	11.0	11.8	V	
		V <sub>SATU-2'</sub>	3	V <sub>ref</sub> = 10 V, V <sub>out</sub> -GND I <sub>O</sub> = 1.0 A	10.4	10.7	11.5	V	
Leakage Current	Upper	I <sub>L U</sub>	_	V <sub>S</sub> = 25 V	_	—	50	μA	
	Lower	IL L	_	V <sub>S</sub> = 25 V	—	—	50		
Diode Forward Voltage	Upper	V <sub>F U</sub>	4	I <sub>F</sub> = 1 A	—	2.2	—	v	
	Lower	V <sub>F L</sub>	4	I <sub>F</sub> = 1 A	—	1.4	_		
Reference Current		I <sub>ref</sub>	2	V <sub>ref</sub> = 10 V, Source mode	—	5	30	μA	

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TEST CIRCUIT 1. I<sub>CC1, 2</sub>

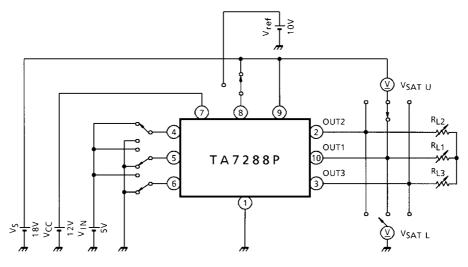


## TEST CIRCUIT 2. V IN (H), V IN (L), IIN, $\Delta V$ T, Iref



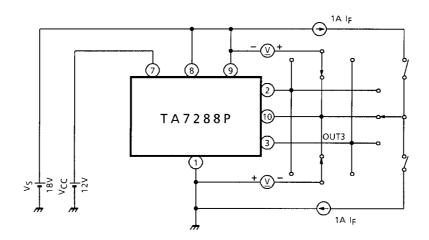
#### **TEST CIRCUIT 3.**

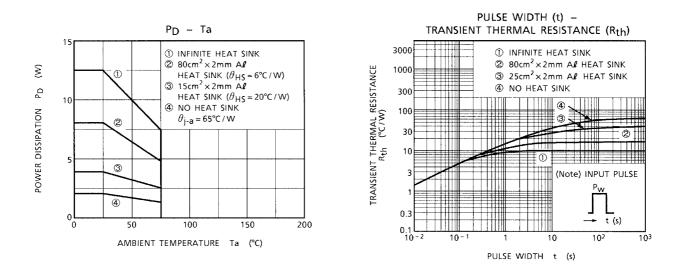
VSAT U-1, L-1, U-2, L-2, U-1', U-2'



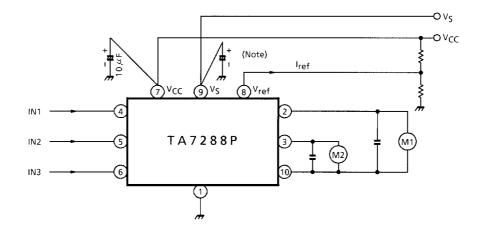
 $I_{\mbox{O}}$  calibration is required to adjust specified values of test conditions by  $R_{L1}{\sim}R_{L3}.$ 

## TEST CIRCUIT 4. $V_{F U, L}$





#### **APPLICATION CIRCUIT**



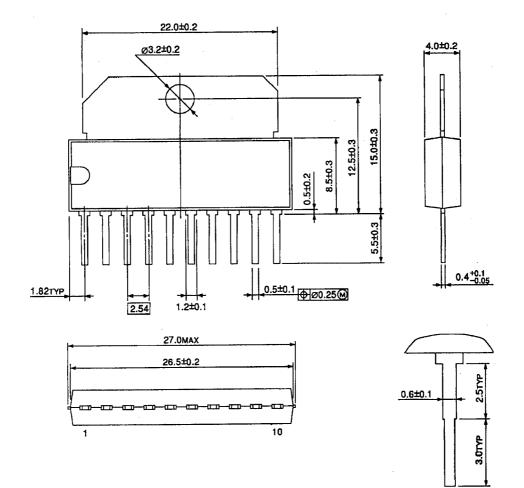
- Note 1: Connect if required
- Note 2: Utmost care is necessary in the design of the output line, V<sub>S</sub> and GND line since IC may be destroyed due to short–circuit between outputs, air contamination fault, or fault by improper grounding.

### **TOSHIBA**

#### PACKAGE DIMENSIONS

HSIP10-P-2.54

Unit: mm



Weight: 2.47 g (Typ.)

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