CMOS 4-Bit Microcontroller

TMP47C241N TMP47C241M

The TMP47C241 are high speed and high performance 4-bit single chip micro computers, integrating 8-bit AD converter, watchdog timer and serial Interface based on the TLCS-47 series.

Part No.	ROM	RAM	Rackage	OTP
TMP47C241N	20400 hit	1204 hit	P-SDIP28-400-1.78	TMP47P241VN
TMP47C241M	2048 x 8-bit	128 x 4-bit	P-SOP28-450-1.27	TMP47P241VM

Features

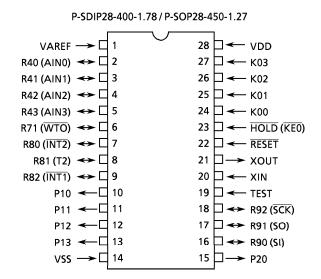
◆4-bit single chip microcomputer Instruction execution time: 1.3 μ s (at 6 MHz) P-SDIP28-400-1.78 Low voltage operation: 2.7 V (at 4.2 MHz) ♦90 basic instructions Table look-up instructions ◆Subroutine nesting: 15 levels max ♦6 interrupt sources (External: 2, Internal: 4) All sources have independent latches each, and multiple interrupt control is available TMP47C241N ◆I/O port (21 pins) TMP47P241VN Input 2 ports 5 pins P-SOP28-450-1.27 5 pins Output 2 ports 1/0 4 ports 11 pins Two 12-bit Timer / Counters Timer, event counter, and pulse width measurement mode Interval timer ♦Watchdog Timer Serial Interface with 4-bit buffer TMP47C241M External / internal clock, and leading / trailing edge shift TMP47P241VM mode

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- ◆8-bit successive approximate type AD converter (With sample and hold)
 - 4 analog inputs
 - Converting time: 48 μ s (4 MHz)
- ♦ High current outputs LED direct drive capability: typ. 20 mA x 5 bits (Ports P1, P2) typ. 7 mA x 3 bits (Port R9)
- ♦ Hold function
 - Battery / Capacitor back-up
- ◆Real Time Emulator: BM47214A + BM1152 (SDIP)

Pin Assignment (Top View)



Power Supply VDD-KE FLAG Accumulator HR LR PC Data Memory C Z S G ALU RAM address buffer (RAM) Program Memory (ROM) STACK SPW Hold input HOLD (Sense input) (KEO) TC1 TC2 DC FIF EIR Data table Hold controller Interrupt controller Reset input RESET-System controller Test pin TEST **Timing Generator** Interval Timer IR 12-bit Osc. Connecting XIN - XOUT 4-bit Serial 8-bit Clock Generator Timer / AD converter Interface Decoder Counter (2ch) pin Watchdog Timer R7 P2 P1 R8 R9 К0 R4 R82 (INT1) R81 (T2) R80 (INT2) R92 (SCK) R91 (SO) R71 (WTO) P20 P13 VAREF R43(AIN3) к03 to to to I/O port R90 (SI) R40(AIN0) P19, K00 Watchdog timer I/O port I/O port Analog output High current Input port I/O port (T/C input interrupt input (Serial out) reference voltage output port (Analog input)

Block Diagram

Pin Function

Pin Name	Input / Output	Function	5	
K03 to K00	Input	4-bit input port		
P13 to P10	Output	4-bit output port with latch.		
P20	Gutput	1-bit output port with latch.		
R43 (AIN3) to R40 (AIN0)	l/O (Input)	4-bit I/O port with latch. When using as input port, the latch must be set to "1".	AD converter analog input	
R71 (WTO)	I/O (Output)	1-bit I/O port with latch. When using as input port or watchdog timer output, the latch must be set to "1".	Watchdog timer output	
R82 (ĪNT1)		3-bit I/O port with latch.	External interrupt 1 input	
R81 (T2)	l/O (Input)	When using as input port, external interrupt input pin, or timer / counter external input	Timer / Counter 2 external input	
R80 (INT2)		pin, the latch must be set to "1".	External interrupt 2 input	
R92 (SCK)	I/O (I/O)	3-bit I/O port with latch.	Serial clock I/O	
R91 (SO)	I/O (Output)	When using as input port or serial port, the	Serial data output	
R90 (SI)	l/O (Input)	latch must be set to "1".	Serial data input	
XIN	Input	Resonator connecting pin.		
XOUT	Output	For inputting external clock, XIN is used and X	OUT is opened.	
RESET	Input	Reset signal input		
HOLD (KEO)	Input (Input)	HOLD request / release signal input	Sense input	
TEST	Input	Test pin for out-going test. Be opened or fixed	to low level.	
VDD		+ 5 V		
VSS	Power supply	0 V (GND)	AD converter analog reference voltage (GND)	
VAREF]	AD converter analog reference voltage		

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Operational Description

Conserning the TMP47C241, the hardware configuration and operation are described. The configuration of basic machine instruction for TMP47C241 is same as TLCS-47 Series.

1. System Configuration

(1) Internal CPU Function

These as the same as the TMP47C203.

(2) Peripheral Hardware Function

1 I/O Ports	④ AD converter
② Interval Timer	⑤ Watchdog Timer
③ Timer/Counters	6 Serial Interface

2. Peripheral Hardware Function

2.1 Ports

The TMP47C241 has 8 I/O ports (21 pins) each as follows:

	-		····	
1	К0	;	4-bit input	
2	P1	;	4-bit output	
3	P2	;	1-bit output	
4	R4	;	4-bitinput / output	(shared by the AD converter analog inputs)
5	R7	;	1-bit input / output	(shared by the watchdog timer output)
6	R8	;	3-bit input / output	shared by external interrupt request input and timer / counter input)
$\overline{\mathcal{O}}$	R9	;	3-bit input / output	(shared by serial port)
8	KE	;	1-bit sense input	(shared by hold request / release signal input)

5 pins (typ. 20 mA) of P1, P2 ports and 3pins (typ. 7 mA) of R9 port are high current output ports which can directly drive LEDs.

Table 2-3 lists the port address assignments and the I/O instructions that can access the ports. The 5-bit to 8-bit data conversion instruction [OUTB @HL] is invalid.

(1) Port K0 (K03 to K00)

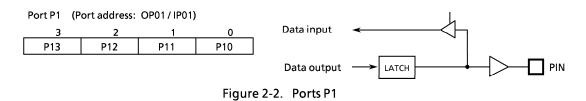
Port K0 is a 4-bit input-only port. A pull-up or pull-down resistor can be contained by the mask option.



Figure 2-1. Port K0

(2) Ports P1 (P13 to P10)

Ports P1 is 4-bit high current output ports which can directly drive LEDs, with 4-bit latches. When an input instruction is executed, the latch data is read in these ports. The latch is initialized to "1" during reset.



Electrical Characteristics

Absolute Maximum Ratings	$(V_{SS} = 0 V)$
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Parameter	Symbol	Pins	Ratings	Unit
Supply Voltage	V _{DD}		– 0.3 to 7	V
Input Voltage	V _{IN}		- 0.3 to V _{DD} + 0.3	V
	V _{OUT1}	Except sink open drain pin	- 0.3 to V _{DD} + 0.3	
Output Voltage	V _{OUT2}	Ports P1, P2, R7 to R9	– 0.3 to 10	l v
	V _{OUT3}	Analog inputs	- 0.3 to V _{DD} + 0.3	1
	I _{OUT1}	Ports P1, P2	30	
Output Current (Per 1 pin)	I _{OUT2}	Port R9	15	mA
	I _{OUT3}	Ports R4, R7, R8	3.2	
Output Current (Total)	ΣI_{OUT1}	Ports P1, P2, R9	120	mA
Power Dissipation [Topr = 70°C]	PD		300	mW
Soldering Temperature (time)	Tsld		260 (10 s)	°C
Storage Temperature	Tstg		– 55 to 125	°C
Operating Temperature	Topr		– 30 to 70	°C

Note: The absolute maximum ratings are rated values which must not be exceeded during operation, even for an instant. Any one of the ratings must not be exceeded. If any absolute maximum rating is exceeded, a device may break down or its performance may be degraded, causing it to catch fire or explode resulting in injury to the user. Thus, when designing products which include this device, ensure that no absolute maximum rating value will ever be exceeded.

Recommended Operating Conditions

 $(V_{SS} = 0 V, Topr = -30 to 70^{\circ}C)$

Parameter	Symbol	Pins	Conditions	Min	Max	Unit
			fc = 6.0 MHz	4.5		
Supply Voltage	V _{DD}		fc = 4.2 MHz	2.7	6.0	V
			In the HOLD mode	2.0]	
	V _{IH1}	Except Hysteresis Input	In the normal	V _{DD} × 0.7		
Input High Voltage	V _{IH2}	Hysteresis Input	operating area	V _{DD} × 0.75		V
	V _{IH3}		In the HOLD mode	V _{DD} ×0.9		
	V _{IL1}	Except Hysteresis Input	In the normal		$V_{DD} \times 0.3$	
Input Low Voltage	V _{IL2}	Hysteresis Input	operating area	0	V _{DD} × 0.25	v
	V _{IL3}		In the HOLD mode		V _{DD} × 0.1	
			V_{DD} = 4.5 V to 6.0 V		6.0	
Clock Frequency	fc		V _{DD} = 2.7 V to 6.0 V	0.4	4.2	MHz
			In the RC oscillation		2.5	

Note: The recommended operating conditions for a device are operating conditions under which it can be guaranteed that the device will operate as specified. If the device is used under operating conditions other than the recommended operating conditions (supply voltage, operating temperature range, specified AC/DC values etc.), malfunction may occur. Thus, when designing products which include this device, ensure that the recommended operating conditions for the device are always adhered to.

Unit

v

μA

kΩ

 μA

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mΑ

mΑ

μA

Parameter	Symbol	Pins	Conditions	Min	Тур.	Max
Hysteresis Voltage	V _{HS}	Hysteresis Input		-	0.7	—
Input Current	I _{IN1}	Port K0, TEST, RESET, HOLD	V _{DD} = 5.5V, V _{IN} = 5.5V / 0V	_	_	± 2
input current	I _{IN2}	Ports R (open drain)				
Input Posistoneo	R _{IN1}	Port K0 with pull-up/pull-down		30	70	150
Input Resistance	R _{IN2}	RESET		100	220	450
Output Leakage Current	I _{LO}	Ports R, P (open drain)	$V_{DD} = 5.5 V, V_{OUT} = 5.5 V$			2
Output Low Voltage	V _{OL2}	Except XOUT, ports P	$V_{DD} = 4.5 V, I_{OL} = 1.6 mA$	I	I	0.4
Low Output Current	I _{OL1}	Ports P1, P2	V _{DD} = 4.5 V, V _{OI} = 1.0 V	Ι	20	_
	I _{OL2}	Port R9	$v_{DD} = 4.5 v, v_{OL} = 1.0 v$		7	—
			$V_{DD} = 5.5 V$, fc = 4 MHz	١	2	4
Supply Current (in the Normal mode)	I _{DD}		$V_{DD} = 3.0 V$, fc = 4 MHz	Ι	1	2
			$V_{DD} = 3.0 V, fc = 400 kHz$	-	0.5	1
Supply Current (in the HOLD mode)	I _{DDH}		V _{DD} = 5.5 V	_	0.5	10

DC Characteristics

 $(V_{SS} = 0 V, Topr = -30 to 70^{\circ}C)$

Note 1: Typ. values show those at Topr = 25° C, V_{DD} = 5 V.

Note 2: Input Current I_{IN1} ; The current through resistor is not included, when the input resistor (pull-up/pull-down) is contained.

Note 3: Supply Current I_{DD}, I_{DDH} ; $V_{IN} = 5.3 \text{ V} / 0.2 \text{ V} (V_{DD} = 5.5 \text{ V})$, 2.8 V / 0.2 V ($V_{DD} = 3.0 \text{ V}$)

AD Conversion Characteristics

 $(Topr = -30 \text{ to } 70^{\circ}\text{C})$

Parameter	Symbol	Conditions	Min	Тур.	Max	Unit
Analog Reference Voltage	V _{AREF}		V _{DD} – 1.5	-	V _{DD}	v
Analog Reference Voltage Range	ΔV_{AREF}	V _{AREF} – V _{SS}	2.7	-	—	v
Analog Input Voltage	V _{AIN}		V _{SS}	-	V _{AREF}	v
Analog Supply current	I _{REF}		—	0.5	1.0	mA
Nonlinearity Error			—	-	± 1	
Zero Point Error		$V_{DD} = 5.0 V, V_{SS} = 0.0 V$	_	_	± 1	LSB
Full Scale Error		V _{AREF} = 5.000 V	_	-	± 1	
Total Error		V _{ASS} = 0.000 V	_	_	± 2	

Parameter	Symbol	Conditions	Min	Тур.	Max	Unit
		V _{DD} = 4.5 to 6.0 V	1.3			
Instruction Cycle Time	t _{cy}	V _{DD} = 2.7 to 6.0 V	1.9		20	μs
High level Clock pulse Width	t _{WCH}					
Low level Clock pulse Width	t _{WCL}	External clock mode	80	_	_	ns
AD Sampling Time	t _{AIN}		-	4	-	μs
Shift Data Hold Time	t _{sDH}		0.5 t _{cy} – 0.3	_	-	μs
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Recommended Oscilla	ating Conditio	ons $(V_{SS} = 0 V, V_{DD})$	= 2.7 to 6.0 V, T	opr = - 30	to 70°C	.)
 (1) 6 MHz Ceramic Resona CSA6.00MG KBR-6.00MS (2) 4 MHz 	ator (MURATA) (KYOCERA)	$(V_{SS} = 0 V, V_{DD})$ $C_{XIN} = C_{XOUT} = 30 pF$ $C_{XIN} = C_{XOUT} = 30 pF$		XIN 61 41		
 (1) 6 MHz Ceramic Resona CSA6.00MG KBR-6.00MS (2) 4 MHz Ceramic Resona CSA4.00MG KBR-4.00MS FCR4.0M5 (TE Crystal Oscillato 204B-6F 4.00 	ator (MURATA) (KYOCERA) ator (MURATA) (KYOCERA) DK) Dr	C _{XIN} = C _{XOUT} = 30 pF	C,		Х мнz [мнz]	
 (1) 6 MHz Ceramic Resona CSA6.00MG KBR-6.00MS (2) 4 MHz Ceramic Resona CSA4.00MG KBR-4.00MS FCR4.0M5 (TI Crystal Oscillato 204B-6F 4.00 (3) 400 kHz Ceramic Resona CSB400B (ML KBR-400B (KM) 	ator (MURATA) (KYOCERA) ator (MURATA) (KYOCERA) OK) or 00 (TOYOCOI ator JRATA) YOCERA)	$C_{XIN} = C_{XOUT} = 30 \text{ pF}$ $C_{XIN} = C_{XOUT} = 33 \text{ pF}$ $M) C_{XIN} = C_{XOUT} = 20 \text{ pF}$ $C_{XIN} = C_{XOUT} = 20 \text{ pF}$, F $C_{XIN} = C_{XOUT} = 100 \text{ pF}$, F	ς, ς 8 _{XOUT} = 6.8 k Ω		X VIHz or //Hz // / / / / / / / / / / / / / / / /	
 (1) 6 MHz Ceramic Resona CSA6.00MG KBR-6.00MS (2) 4 MHz Ceramic Resona CSA4.00MG KBR-4.00MS FCR4.0M5 (TI Crystal Oscillato 204B-6F 4.00 (3) 400 kHz Ceramic Resona CSB400B (ML KBR-400B (KM) 	ator (MURATA) (KYOCERA) ator (MURATA) (KYOCERA) OK) or 00 (TOYOCOI ator JRATA) YOCERA)	$C_{XIN} = C_{XOUT} = 30 \text{ pF}$ $C_{XIN} = C_{XOUT} = 20 \text{ pF}$ $C_{XIN} = C_{XOUT} = 20 \text{ pF}$	ς, RXOUT = 6.8 kΩ RXOUT = 10 kΩ C		X VIHz or VIHz	

Typical Characteristics

