

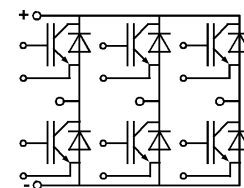
| Absolute Maximum Ratings | | Values | Units |
|--------------------------|---|--------------------|----------------------|
| Symbol | Conditions ¹⁾ | | |
| V_{CES} | | 1200 | V |
| V_{CGR} | $R_{GE} = 20 \text{ k}\Omega$ | 1200 | V |
| I_C | $T_{case} = 25/65 \text{ }^\circ\text{C}$ | 50 / 40 | A |
| I_{CM} | $T_{case} = 25/65 \text{ }^\circ\text{C}; t_p = 1 \text{ ms}$ | 100 / 80 | A |
| V_{GES} | | ± 20 | V |
| P_{tot} | per IGBT, $T_{case} = 25 \text{ }^\circ\text{C}$ | 220 | W |
| $T_j, (T_{stg})$ | | -40 ... +150 (125) | $^\circ\text{C}$ |
| V_{isol} | AC, 1 min. | 2500 | V |
| humidity | DIN 40 040 | Class F | |
| climate | DIN IEC 68 T.1 | 40/125/56 | |
| Inverse Diode | | | |
| $I_F = -I_C$ | $T_{case} = 25/80 \text{ }^\circ\text{C}$ | 45 / 30 | A |
| $I_{FM} = -I_{CM}$ | $T_{case} = 25/80 \text{ }^\circ\text{C}; t_p = 1 \text{ ms}$ | 100 / 80 | A |
| I_{FSM} | $t_p = 10 \text{ ms; sin.}; T_j = 150 \text{ }^\circ\text{C}$ | 350 | A |
| I^2t | $t_p = 10 \text{ ms; } T_j = 150 \text{ }^\circ\text{C}$ | 600 | A^2s |

SEMITRANS® M Low Loss IGBT Modules

SKM 40 GD 124 D



Sixpack



GD

Features

- MOS input (voltage controlled)
- N channel, homogeneous Silicon structure (NPT- Non punch-through IGBT)
- Low loss high density chips
- Low tail current
- High short circuit capability, self limiting to $6 * I_{Cnom}$
- Latch-up free
- Fast & soft inverse CAL diodes ⁸⁾
- Isolated copper baseplate using DCB Direct Copper Bonding Technology without hard mould
- Large clearance (9 mm) and creepage distances (13 mm)

Typical Applications

- Switched mode power supplies
- Three phase inverters for AC motor speed control

| Characteristics | | min. | typ. | max. | Units |
|------------------------------------|--|----------------|----------|------------|--------------------|
| Symbol | Conditions ¹⁾ | | | | |
| $V_{(BR)CES}$ | $V_{GE} = 0, I_C = 0,8 \text{ mA}$ | $\geq V_{CES}$ | - | - | V |
| $V_{GE(th)}$ | $V_{GE} = V_{CE}, I_C = 1 \text{ mA}$ | 4,5 | 5,5 | 6,5 | V |
| I_{CES} | $V_{GE} = 0 \left. \begin{array}{l} T_j = 25 \text{ }^\circ\text{C} \\ T_j = 125 \text{ }^\circ\text{C} \end{array} \right\}$ | - | 0,1 | 1 | mA |
| | | - | 3 | - | mA |
| I_{GES} | $V_{GE} = 20 \text{ V}, V_{CE} = 0$ | - | - | 200 | nA |
| V_{CESat} | $I_C = 25 \text{ A} \left\{ \begin{array}{l} V_{GE} = 15 \text{ V}; \\ T_j = 25 (125) \text{ }^\circ\text{C} \end{array} \right\}$ | - | 2,1(2,4) | 2,45(2,85) | V |
| V_{CESat} | $I_C = 40 \text{ A} \left\{ \begin{array}{l} V_{GE} = 15 \text{ V}; \\ T_j = 25 (125) \text{ }^\circ\text{C} \end{array} \right\}$ | - | 2,6(3,1) | - | V |
| g_{fs} | $V_{CE} = 20 \text{ V}, I_C = 25 \text{ A}$ | 12 | - | - | S |
| C_{CHC} | per IGBT | - | - | 300 | pF |
| C_{ies} | $V_{GE} = 0$ | - | 1900 | 2100 | pF |
| C_{oes} | $V_{CE} = 25 \text{ V}$ | - | 250 | 300 | pF |
| C_{res} | $f = 1 \text{ MHz}$ | - | 110 | 150 | pF |
| L_{CE} | | - | - | 60 | nH |
| $t_{d(on)}$ | $V_{CC} = 600 \text{ V}$ | - | 60 | - | ns |
| t_r | $V_{GE} = +15 \text{ V} / -15 \text{ V}^{3)}$ | - | 49 | - | ns |
| $t_{d(off)}$ | $I_C = 25 \text{ A, ind. load}$ | - | 380 | - | ns |
| t_f | $R_{Gon} = R_{Goff} = 40 \text{ }^\circ\Omega$ | - | 37 | - | ns |
| $E_{on}^{5)}$ | $T_j = 125 \text{ }^\circ\text{C}$ | - | 3,7 | - | mWs |
| $E_{off}^{5)}$ | | - | 2,9 | - | mWs |
| Inverse Diode ⁸⁾ | | | | | |
| $V_F = V_{EC}$ | $I_F = 25 \text{ A} \left\{ \begin{array}{l} V_{GE} = 0 \text{ V}; \\ T_j = 25 (125) \text{ }^\circ\text{C} \end{array} \right\}$ | - | 2,0(1,8) | 2,5 | V |
| $V_F = V_{EC}$ | $I_F = 40 \text{ A} \left\{ \begin{array}{l} V_{GE} = 0 \text{ V}; \\ T_j = 25 (125) \text{ }^\circ\text{C} \end{array} \right\}$ | - | 2,3(2,1) | - | V |
| V_{TO} | $T_j = 125 \text{ }^\circ\text{C}$ | - | 1,1 | 1,2 | V |
| r_t | $T_j = 125 \text{ }^\circ\text{C}$ | - | - | 44 | $\text{m}\Omega$ |
| I_{RRM} | $I_F = 25 \text{ A}; T_j = 125 \text{ }^\circ\text{C}^{2)}$ | - | 22 | - | A |
| Q_{rr} | $I_F = 25 \text{ A}; T_j = 125 \text{ }^\circ\text{C}^{2)}$ | - | 3,7 | - | μC |
| Thermal Characteristics | | | | | |
| R_{thjc} | per IGBT | - | - | 0,56 | $^\circ\text{C/W}$ |
| R_{thjc} | per diode | - | - | 1,0 | $^\circ\text{C/W}$ |
| R_{thch} | per module | - | - | 0,05 | $^\circ\text{C/W}$ |

¹⁾ $T_{case} = 25 \text{ }^\circ\text{C}$, unless otherwise specified

²⁾ $I_F = -I_C, V_R = 600 \text{ V}, -di_F/dt = 500 \text{ A}/\mu\text{s}, V_{GE} = 0 \text{ V}$

³⁾ Use $V_{GEOff} = -5 \dots -15 \text{ V}$

⁸⁾ CAL = Controlled Axial Lifetime Technology

Case and mech. data → B 6 – 80

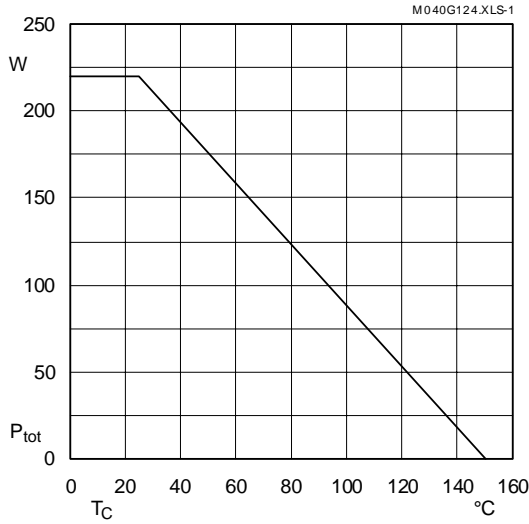


Fig. 1 Rated power dissipation $P_{tot} = f(T_C)$

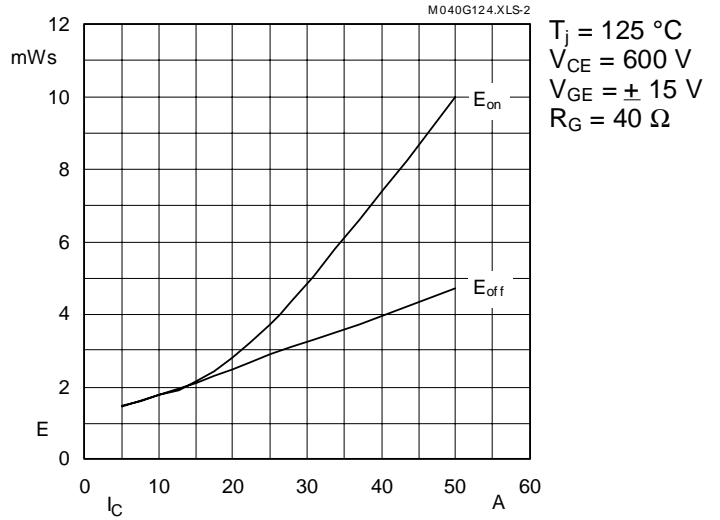


Fig. 2 Turn-on /-off energy $= f(I_C)$

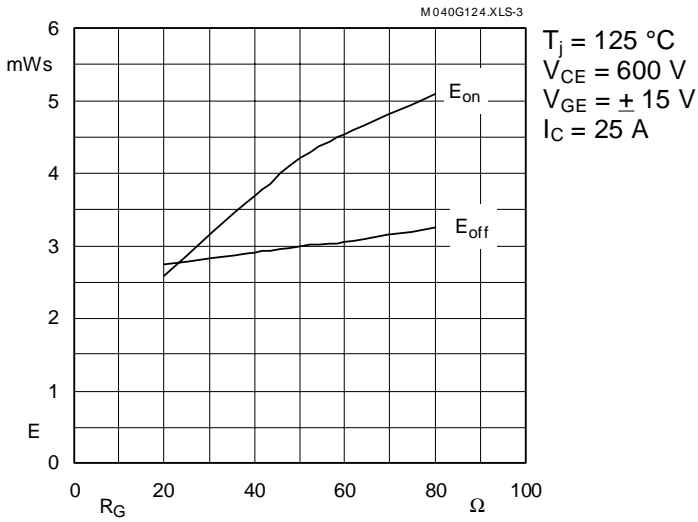


Fig. 3 Turn-on /-off energy $= f(R_G)$

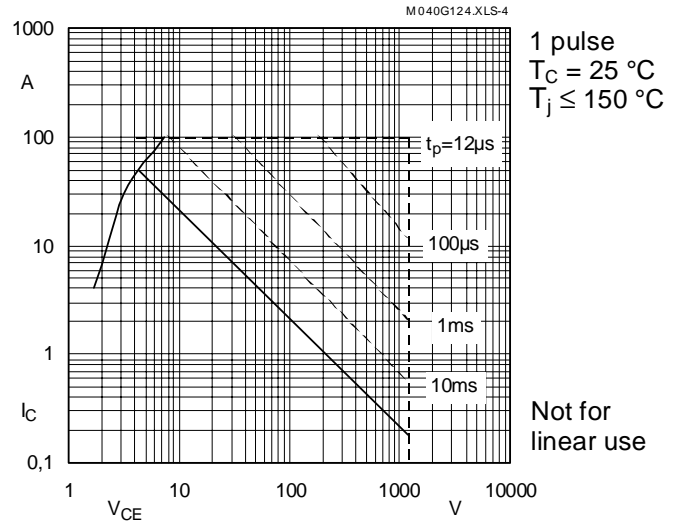


Fig. 4 Maximum safe operating area (SOA) $I_C = f(V_{CE})$

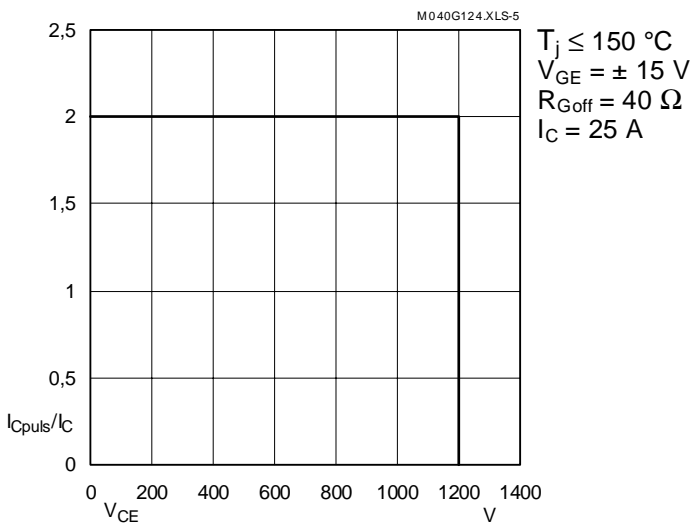


Fig. 5 Turn-off safe operating area (RBSOA)

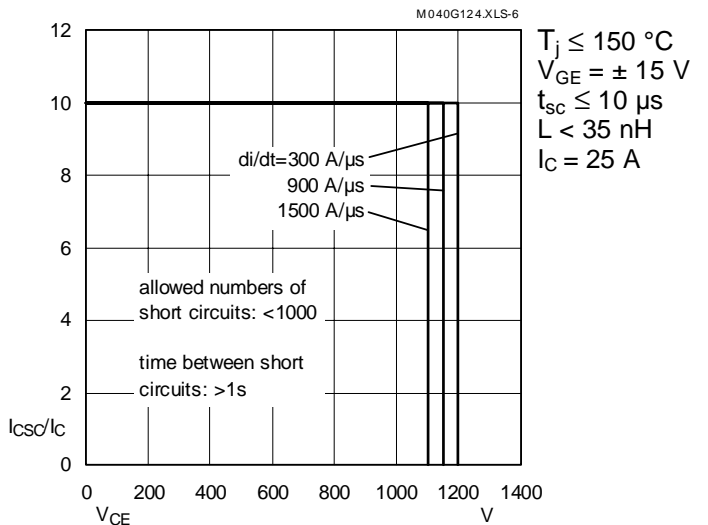


Fig. 6 Safe operating area at short circuit $I_C = f(V_{CE})$

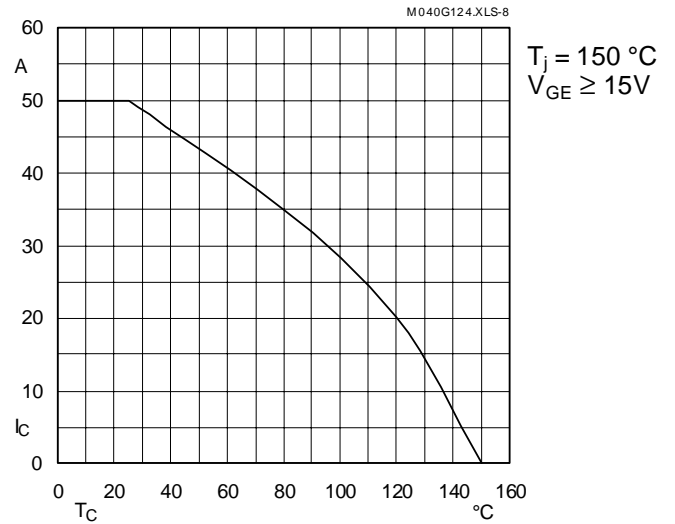


Fig. 8 Rated current vs. temperature $I_C = f(T_C)$

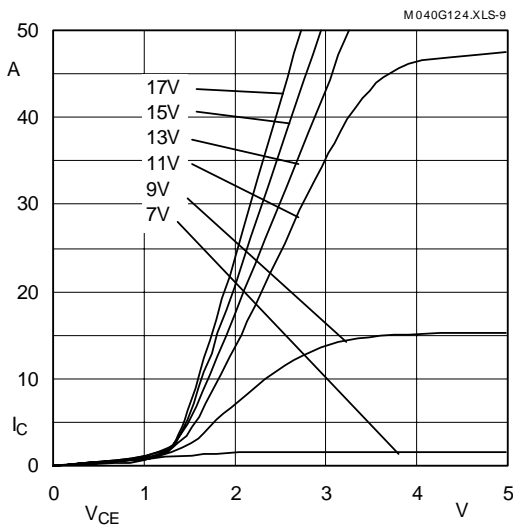


Fig. 9 Typ. output characteristic, $t_p = 80 \mu s$; $25 \text{ }^\circ\text{C}$

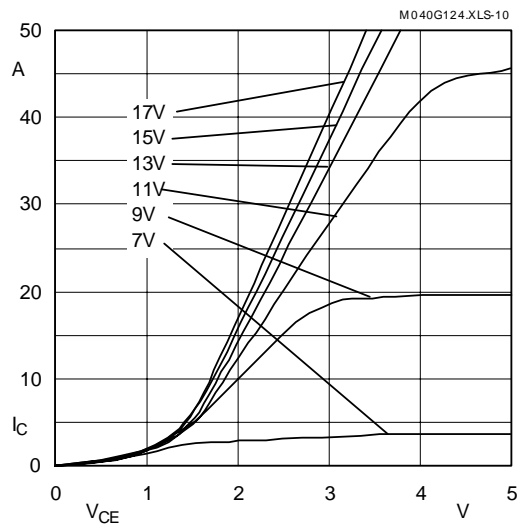


Fig. 10 Typ. output characteristic, $t_p = 80 \mu s$; $125 \text{ }^\circ\text{C}$

$$P_{\text{cond}(t)} = V_{\text{CEsat}(t)} \cdot I_C(t)$$

$$V_{\text{CEsat}(t)} = V_{\text{CE(TO)(Tj)}} + r_{\text{CE(Tj)}} \cdot I_C(t)$$

$$V_{\text{CE(TO)(Tj)}} \leq 1,3 + 0,0005 (T_j - 25) \text{ [V]}$$

$$\text{typ.: } r_{\text{CE(Tj)}} = 0,032 + 0,00010 (T_j - 25) \text{ [\Omega]}$$

$$\text{max.: } r_{\text{CE(Tj)}} = 0,046 + 0,00014 (T_j - 25) \text{ [\Omega]}$$

$$\text{valid for } V_{\text{GE}} = +15 \frac{+2}{-1} \text{ [V]; } I_C \geq 0,3 I_{\text{Cn}}$$

Fig. 11 Saturation characteristic (IGBT)
Calculation elements and equations

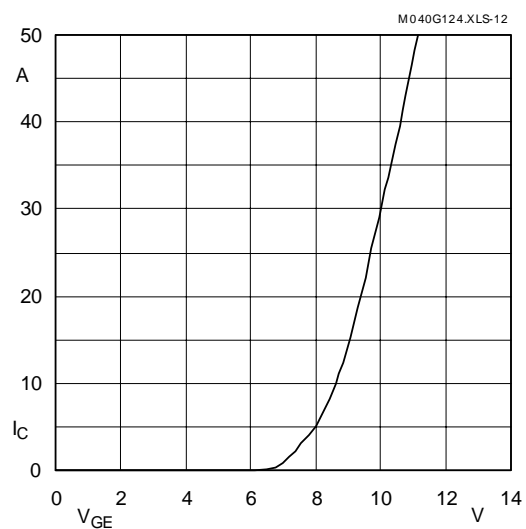


Fig. 12 Typ. transfer characteristic, $t_p = 80 \mu s$; $V_{\text{CE}} = 20 \text{ V}$

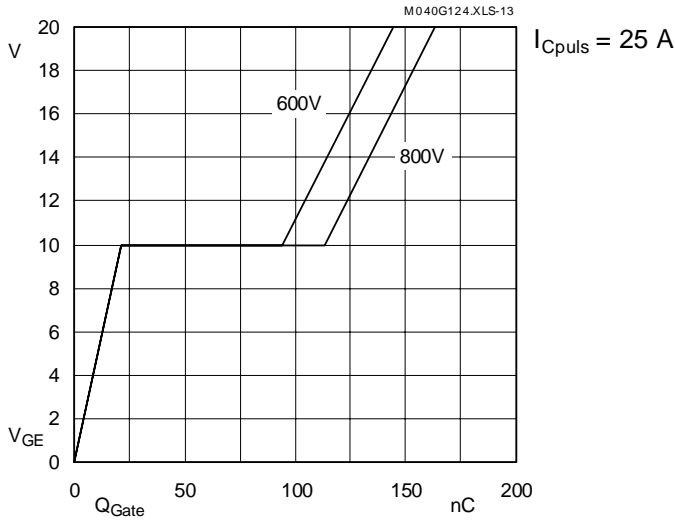


Fig. 13 Typ. gate charge characteristic

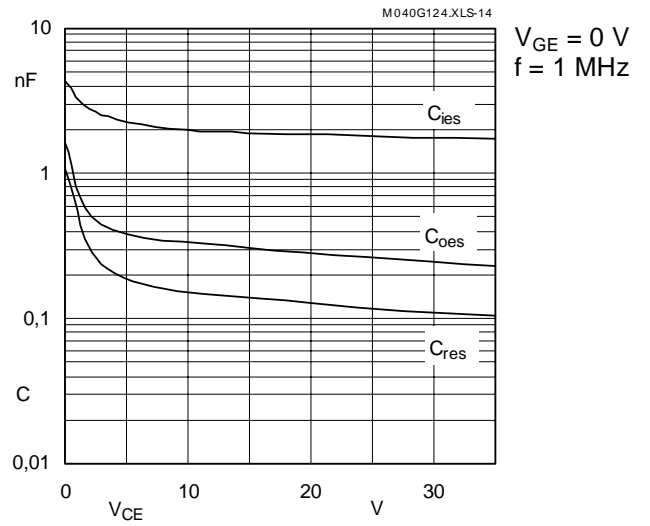


Fig. 14 Typ. capacitances vs. V_{CE}

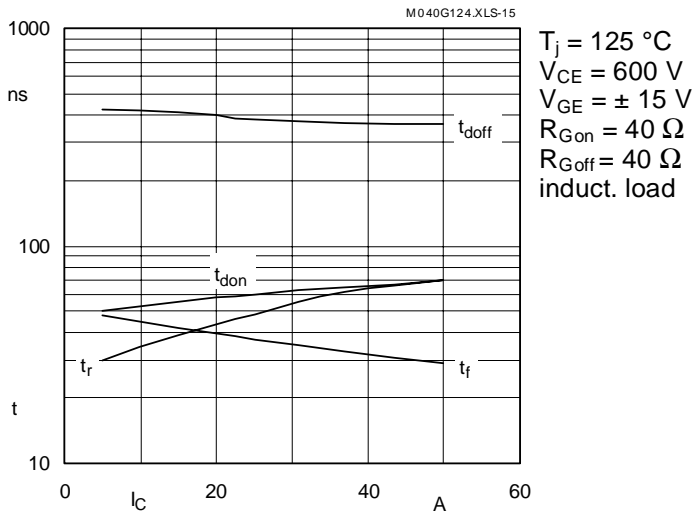


Fig. 15 Typ. switching times vs. I_C

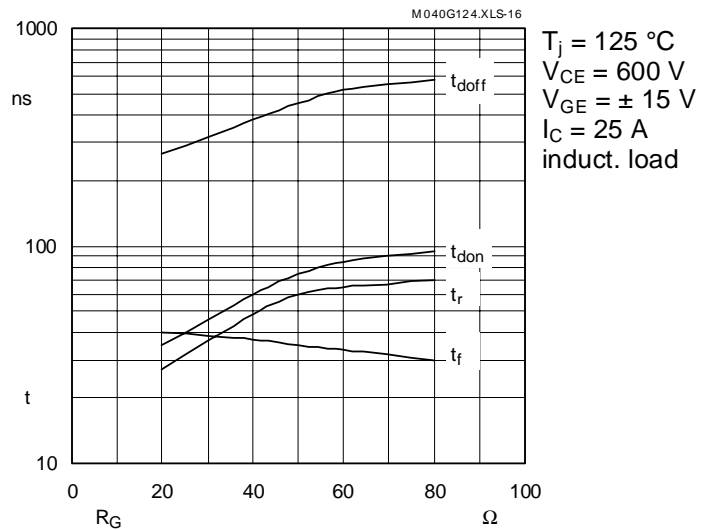


Fig. 16 Typ. switching times vs. gate resistor R_G

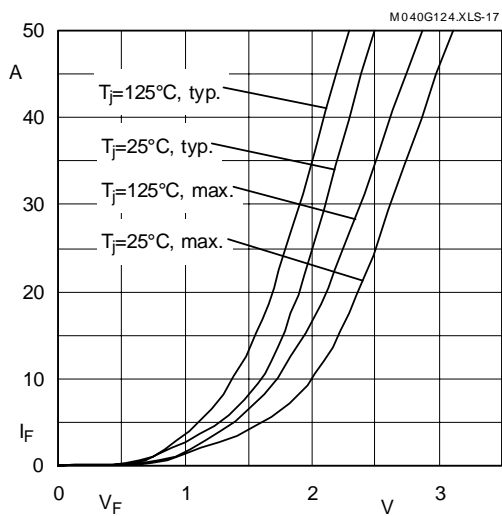


Fig. 17 Typ. CAL diode forward characteristic

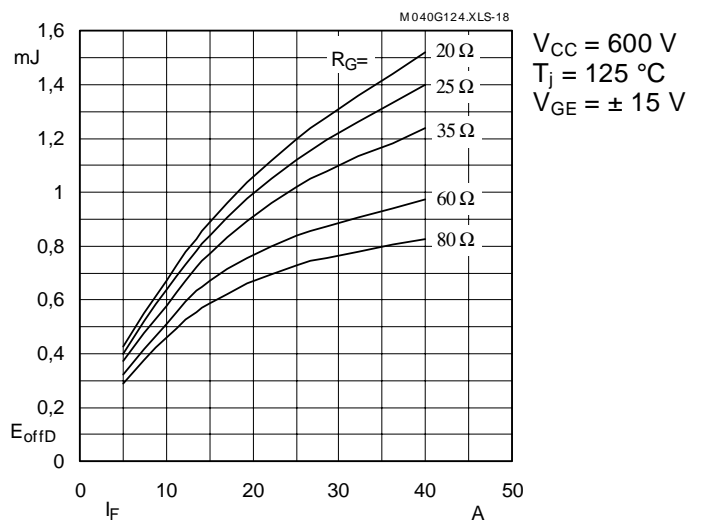


Fig. 18 Diode turn-off energy dissipation per pulse

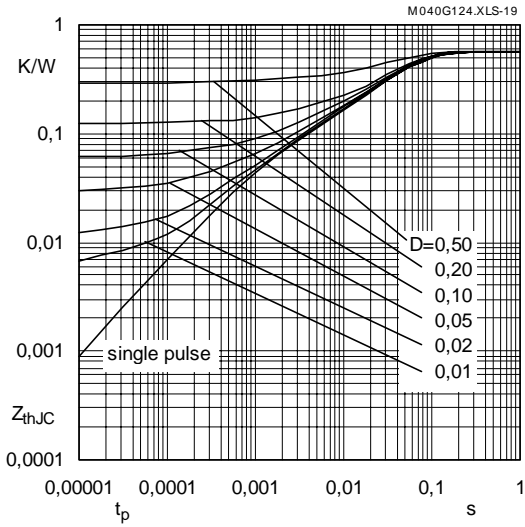


Fig. 19 Transient thermal impedance of IGBT
 $Z_{thJC} = f(t_p)$; $D = t_p / t_c = t_p \cdot f$

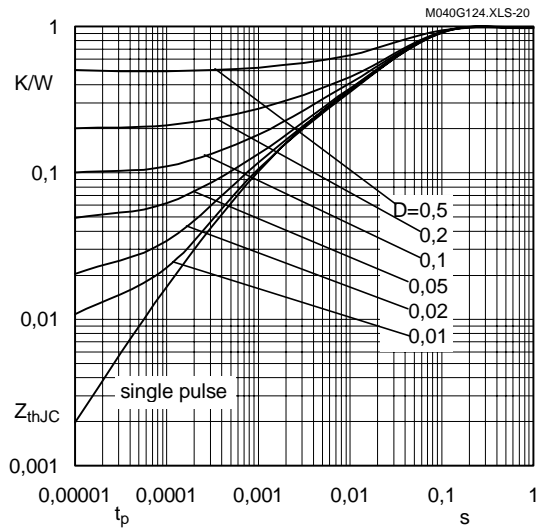


Fig. 20 Transient thermal impedance of inverse CAL diodes
 $Z_{thJC} = f(t_p)$; $D = t_p / t_c = t_p \cdot f$

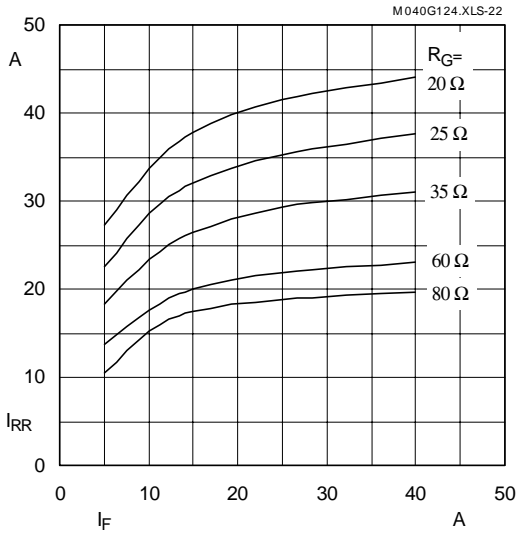


Fig. 22 Typ. CAL diode peak reverse recovery current $I_{RR} = f(I_F; R_G)$

$V_{CC} = 600 \text{ V}$
 $T_j = 125 \text{ }^\circ\text{C}$
 $V_{GE} = \pm 15 \text{ V}$

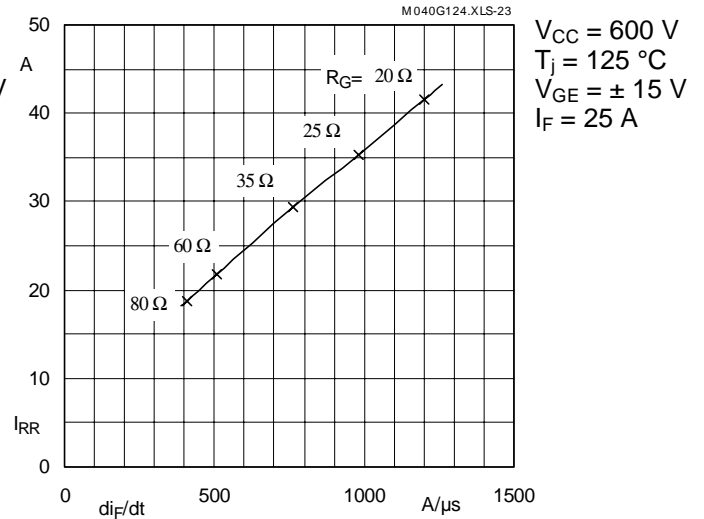


Fig. 23 Typ. CAL diode peak reverse recovery current $I_{RR} = f(di/dt)$

$V_{CC} = 600 \text{ V}$
 $T_j = 125 \text{ }^\circ\text{C}$
 $V_{GE} = \pm 15 \text{ V}$
 $I_F = 25 \text{ A}$

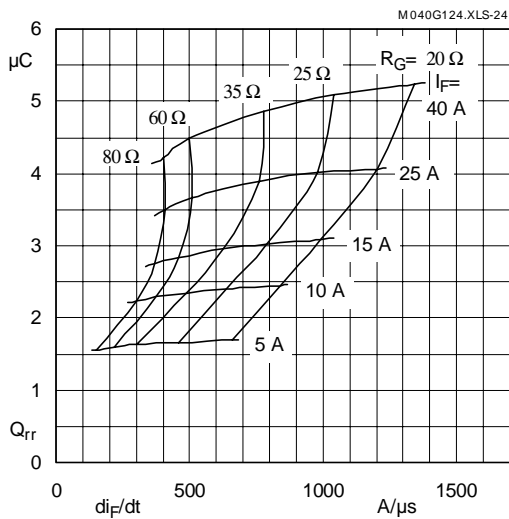
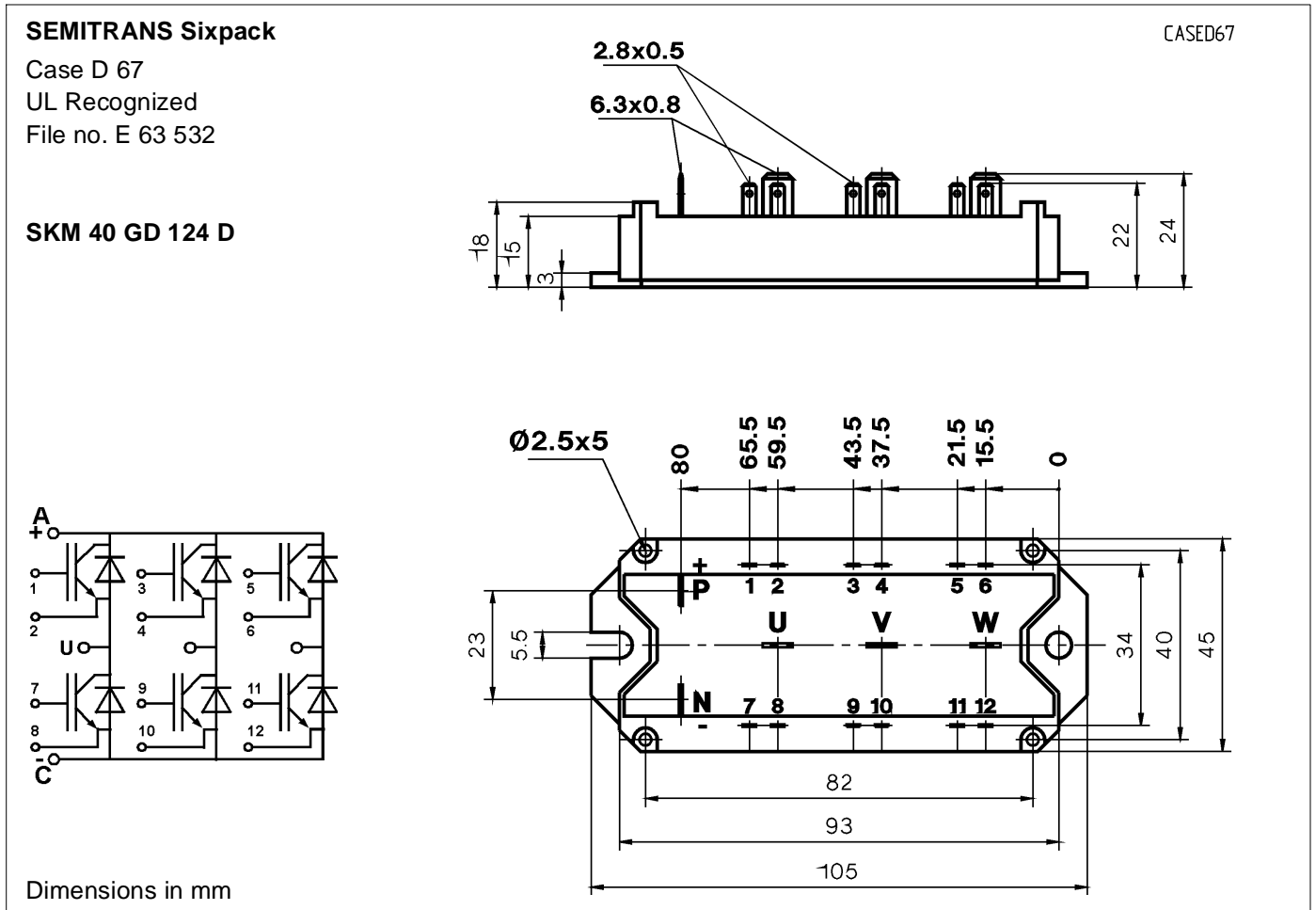


Fig. 24 Typ. CAL diode recovered charge

$V_{CC} = 600 \text{ V}$
 $T_j = 125 \text{ }^\circ\text{C}$
 $V_{GE} = \pm 15 \text{ V}$



Case outline and circuit diagram

| Mechanical Data | | | Values | | | Units |
|-----------------|-----------------------|------|--------|------|--------|------------------|
| Symbol | Conditions | | min. | typ. | max. | |
| M ₁ | to heatsink, SI Units | (M5) | 4 | – | 5 | Nm |
| | to heatsink, US Units | | 35 | – | 44 | lb.in. |
| a | | | – | – | 5x9,81 | m/s ² |
| w | | | – | – | 175 | g |

This is an electrostatic discharge sensitive device (ESDS). Please observe the international standard IEC 747-1, Chapter IX.

Two devices are supplied in one SEMIBOX A.

Larger packing units (10 and 20 pieces) are used if suitable SEMIBOX → C – 1.